The Local Fractional Bootstrap

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Abstract

We introduce a bootstrap procedure for high-frequency statistics of Brownian semistationary processes. More specifically, we focus on a hypothesis test on the roughness of sample paths of Brownian semistationary processes, which uses an estimator based on a ratio of realized power variations. Our new resampling method, the local fractional bootstrap, relies on simulating an auxiliary fractional Brownian motion that mimics the fine properties of high frequency differences of the Brownian semistationary process under the null hypothesis. We prove the first order validity of the bootstrap method and in simulations we observe that the bootstrap-based hypothesis test provides considerable finite-sample improvements over an existing test that is based on a central limit theorem. This is important when studying the roughness properties of time series data; we illustrate this by applying the bootstrap method to two empirical data sets: we assess the roughness of a time series of high-frequency asset prices and we test the validity of Kolmogorov’s scaling law in atmospheric turbulence data.

Keywords: Brownian semistationary process; roughness; fractal index; Hölder regularity; fractional Brownian motion; bootstrap; stochastic volatility; turbulence.

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1 Introduction

In the study of pathwise properties of continuous stochastic processes, roughness is a central attribute. Theoretically, roughness relates to the degree of Hölder regularity enjoyed by the sample paths of the stochastic process in question. The fractional Brownian motion (fBm), introduced

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by Kolmogorov (1940) and popularized later by Mandelbrot and Van Ness (1968), is perhaps the most well-known example of a process that can exhibit various degrees of roughness. The fBm with Hurst index $H \in (0,1)$ is a Gaussian process that coincides with the standard Brownian motion when $H = 1/2$. If $H < 1/2$ (respectively $H > 1/2$), then the sample paths of the fBm are rougher (respectively smoother) than those of the standard Brownian motion in terms of Hölder regularity. In this work, we are concerned with conducting inference on the fractal index, $\alpha$, of a stochastic process, when $\alpha$ is estimated using the so-called change-of-frequency (COF) estimator, introduced by Lang and Roueff (2001) for Gaussian processes and extended by Barndorff-Nielsen et al. (2013b) and Corcuera et al. (2013) to a non-Gaussian setting. In the case of the fBm it holds that $\alpha = H - 1/2$, whilst in general $\alpha < 0$ indicates roughness and $\alpha > 0$ smoothness relative to the standard Brownian motion, as with fBm. When $\alpha = 0$, the stochastic process under consideration has the same roughness as the standard Brownian motion.

Several interesting empirical time series exhibit signs of roughness, i.e. $\alpha < 0$. Some noteworthy examples include:

- time-wise measurements of velocity in turbulent flows (Corcuera et al., 2013), where roughness in inertial time scales is predicted by Kolmogorov’s scaling law (Kolmogorov, 1941) and Taylor’s frozen field hypothesis (Taylor, 1938),
- time series of electricity spot prices (Barndorff-Nielsen et al., 2013a; Bennedsen, 2017),
- measures of the realized volatility of asset prices (Gatheral et al., 2018; Bennedsen et al., 2016).

In these applications, estimation of, and inference on, the index $\alpha$ is important. There is a long history of methods of estimating $\alpha$, concentrating mostly on Gaussian processes, of which a comprehensive survey is provided in Gneiting et al. (2012). In the time series data mentioned above, non-Gaussian features are pervasive, however, which is why we concentrate on a specific, yet flexible, non-Gaussian framework. Brownian semistationary (BSS) processes (Barndorff-Nielsen and Schmiegel, 2007, 2009) form a class of stochastic processes that accommodate various departures from Gaussianity and different degrees of roughness. Barndorff-Nielsen et al. (2013b) and Corcuera et al. (2013) and have studied the properties of the COF estimator of $\alpha$ in the context of BSS processes. In particular, they have derived a central limit theorem (CLT), that makes it possible to conduct hypothesis tests on $\alpha$.

In the present paper, our main focus will be on the COF estimator of a driftless BSS process $(X_t)_{t \in \mathbb{R}}$, given by

$$X_t = \int_{-\infty}^{t} g(t - s) \sigma_s dW_s,$$
where $g : \mathbb{R}^+ \to \mathbb{R}$ is a kernel function, $(\sigma_t)_{t \in \mathbb{R}}$ a stochastic volatility process, and $(W_t)_{t \in \mathbb{R}}$ a standard Brownian motion. Important for our present purpose, we assume that the kernel function $g(x)$ behaves like a power function, $x \mapsto x^\alpha$, when $x$ is near zero; a statement we will make precise below. When this assumption holds, and some additional (mild) technical conditions are met, the sample paths of $X$ are Hölder continuous with index $\alpha + 1/2 - \varepsilon$ for any $\varepsilon > 0$ (Bennedsen et al., 2017b, Proposition 2.1). Moreover, $\alpha = 0$ is a necessary condition for the process to be a semimartingale (Basse, 2008). Intuitively, the BSS process is a moving average process driven by volatility-modulated Brownian noise and is, thus, quite general and flexible. The BSS framework is also closely related to processes such as the fBm and Gaussian Volterra processes of convolution type; see e.g. Bennedsen et al. (2017b). Therefore we expect the methods proposed in this paper to apply to these processes as well, but research into the specifics is beyond the scope of the present paper and left for future work.

The contribution of this paper is to derive a bootstrap procedure that improves the finite sample properties of the test of the null hypothesis

$$H_0 : \alpha = \alpha_0,$$

for some $\alpha_0 \in (-\frac{1}{2}, \frac{1}{2})$, when the fractal index $\alpha$ is estimated using the COF estimator. Theoretically, the COF estimator has two regimes: in the first regime $\alpha \in (-\frac{1}{2}, \frac{1}{4})$, the estimator uses the entire sample to estimate $\alpha$. In this case, we propose a novel bootstrap method, the \emph{local fractional bootstrap}, which utilizes simulations of an auxiliary fractional Brownian motion with Hurst index $H = \alpha_0 + \frac{1}{2}$, thereby mimicking the fine properties of the sample paths of the underlying BSS process under $H_0$. We establish the first-order asymptotic validity of the local fractional bootstrap for the percentile-$t$ methods, i.e., when the test-statistic is normalized by its (bootstrap) standard deviation.

As noted in Corcuera et al. (2013, Section 4), in the second regime $\alpha \in \left[\frac{1}{4}, \frac{1}{2}\right)$, the asymptotic behavior of the COF estimator is potentially affected (depending on the form of $g$) by a non-negligible bias term, causing the CLT to break down. For this reason, the authors suggest using a modified COF estimator that implements asymptotically increasing gaps between increments from which the power variations are computed. These gaps make the increments used in the estimator asymptotically uncorrelated, which opens the door to a \emph{wild bootstrap} approach (e.g. Wu, 1986; Liu, 1988; Gonçalves and Meddahi, 2009) in this regime. However, since the range $\alpha \in \left[\frac{1}{4}, \frac{1}{2}\right)$ appears to be of limited practical interest, we, for the sake of brevity, relegate the details on the wild bootstrap method, along with the simulation study of its finite sample properties, to a separate web appendix (Bennedsen et al., 2017a).

In a Monte Carlo simulation study, we assess the finite sample properties of the local fractional bootstrap procedure in comparison with the inference method based on the CLT of Corcuera et al.
We find that for all $\alpha \in (-\frac{1}{2}, \frac{1}{4})$, the local fractional bootstrap offers improvements in terms of the size of the test of $H_0$, especially when the sample size ranges from small to moderate. Indeed, since our method simulates the auxiliary bootstrap observations under $H_0$, we minimize the probability of a type I error (Davidson and MacKinnon, 1999), i.e., of rejecting $H_0$ when it actually holds. This feature proves to be important when we in the empirical section apply the method to assess the roughness of the time series of logarithmic prices of the E-mini futures contract. In this case, no-arbitrage considerations suggest that $\alpha = 0$, and we find that the bootstrap procedure is crucial for achieving the correct size of the test of $H_0 : \alpha = 0$ when applied to intraday price series.

We also apply the bootstrap method to a time series of measurements of atmospheric turbulence to test for the empirical validity of Kolmogorov’s scaling law (Kolmogorov, 1941). We find the data to be in good agreement with the scaling law, but again using the bootstrap is crucial for accurate inference when the sample size is small.

The rest of this paper is structured as follows. Section 2 sets the stage by presenting the mathematical definition of the $\mathcal{BSS}$ process as well as the assumptions we work under. This section also briefly reviews existing results as they pertain to the present work. In Section 3 we detail our bootstrap method, the local fractional bootstrap, and give the details on its implementation. Section 4 contains a Monte Carlo study of the finite sample properties of the bootstrap method and Section 5 presents the empirical applications. Section 6 concludes. Simulation setup, proofs, as well as some additional technical derivations, are given in Appendices C, B, and D. The details on the wild bootstrap method, including proofs and a simulation experiment, are available in a web appendix (Bennedsen et al., 2017a).

## 2 Setup, assumptions, and review of existing results

Now, we introduce some essential notation. Following the conventions of bootstrap literature, $\mathbb{P}^* (\mathbb{E}^* \text{ and } \text{Var}^*)$ denotes the probability measure (expected value and variance) induced by the bootstrap resampling, conditional on a realization of the original time series. In addition, for a sequence of bootstrap statistics $Z^*_n$, we write $Z^*_n = o_p^* (1)$ in probability, or $Z^*_n \overset{\mathbb{P}^*}{\rightarrow} 0$, as $n \rightarrow \infty$, in probability, if for any $\varepsilon > 0$, $\delta > 0$,

$$\lim_{n \rightarrow \infty} \mathbb{P}^* ([|Z^*_n| > \delta] > \varepsilon) = 0.$$ 

Similarly, we write $Z^*_n = O_p^* (1)$ as $n \rightarrow \infty$, in probability if for all $\varepsilon > 0$ there exists $M_\varepsilon < \infty$ such that

$$\lim_{n \rightarrow \infty} \mathbb{P}^* ([|Z^*_n| > M_\varepsilon] > \varepsilon) = 0.$$ 

Finally, we write $Z_n^* \xrightarrow{d} Z$ as $n \to \infty$, in probability, if conditional on the sample, $Z_n^*$ converges weakly to $Z$ under $\mathbb{P}^*$, for all samples contained in a set with $\mathbb{P}$-probability converging to one.

### 2.1 BSS setup and assumptions

We follow Barndorff-Nielsen et al. (2013a) and consider a filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbb{R}}, \mathbb{P})$, on which we define a Brownian semistationary (BSS) process $X = (X_t)_{t \in \mathbb{R}}$, without a drift as

$$X_t = \int_{-\infty}^{t} g(t-s) \sigma_s dW_s, \quad t \in \mathbb{R}, \quad (1)$$

where $(W_t)_{t \in \mathbb{R}}$ is a two-sided standard Brownian motion, $g: \mathbb{R}^+ \to \mathbb{R}$ is a deterministic weight function satisfying $g \in L^2(\mathbb{R}^+)$, and $(\sigma_t)_{t \in \mathbb{R}}$ is an $(\mathcal{F}_t)_{t \in \mathbb{R}}$-adapted càdlàg process. We assume that

$$\int_{-\infty}^{t} g^2(t-s) \sigma_s^2 ds < \infty \text{ a.s., for all } t \in \mathbb{R},$$

and that $X_t$ is a.s. finite for any $t \in \mathbb{R}$. We introduce a centered stationary Gaussian process $G = (G_t)_{t \in \mathbb{R}}$ that is associated to $X$, which we will call the Gaussian core of $X$, as

$$G_t = \int_{-\infty}^{t} g(t-s) dW_s, \quad t \in \mathbb{R}. \quad (2)$$

The correlation kernel $r$ of $G$ is given via

$$r(t) = \text{corr}(G_s, G_{s+t}) = \frac{\int_{0}^{\infty} g(u) g(u+t) du}{\|g\|_{L^2(\mathbb{R}^+)}^2}, \quad t \geq 0.$$

A crucial object in the asymptotic theory is the variogram $R$, given by

$$R(t) = \mathbb{E} \left[ (G_{s+t} - G_s)^2 \right] = 2 \|g\|_{L^2(\mathbb{R}^+)}^2 (1 - r(t)), \quad t \geq 0.$$

We assume that the process $X$ is observed at equidistant time points $t_i = i \Delta_n, i = 0, 1, \ldots, \lfloor t/\Delta_n \rfloor$, with $\Delta_n \downarrow 0$ as $n \to \infty$. This kind of asymptotics are termed in-fill asymptotics. The theory considered in this paper will call for computing second order differences of the BSS process using different lag spacing, $v \in \mathbb{N}$. In particular, we are concerned with power variations of the following type

$$V(X; p, v)_{t}^n \equiv \sum_{i=2v}^{\lfloor t/\Delta_n \rfloor} \left| X_{i\Delta_n} - 2X_{(i-v)\Delta_n} + X_{(i-2v)\Delta_n} \right|^p, \quad (3)$$

where $p \geq 1$ and where we refer to $v$ as the lag between observations. Although the theory goes through for general $v \in \mathbb{N}$ we will mainly consider $v = 1, 2$, which will be sufficient for our purposes. For the asymptotic theory, Corcuera et al. (2013) also introduce the normalized power variations:

$$\tilde{V}(X; p, v)_{t}^n \equiv \Delta_n \tau_n(v)^{-p} V(X; p, v)_{t}^n, \quad (4)$$
where \( \tau_n(v) = \sqrt{\mathbb{E}\left[\left|G_{i\Delta_n} - 2G_{(i-v)\Delta_n} + G_{(i-2v)\Delta_n}\right|^2\right]} \) is the standard deviation of the second order increment of the Gaussian core calculated with lag spacing \( v\Delta_n \).

Our proposal is to use the bootstrap to approximate the sampling distributions of a general class of nonlinear transformations of these statistics. This relates to the limiting behavior of the roughness parameter estimator of the BSS process, studied in Corcuera et al. (2013). In order to recall the consistency result for \( \bar{V}(X;p,v)_n \), derived by Corcuera et al. (2013), we need to introduce a set of assumptions. Below, \( \alpha \) denotes a number in \((-\frac{1}{2},0) \cup (0,\frac{1}{2})\) and functions \( L_f \) indexed by a mapping \( f \), are assumed to be slowly varying at zero, i.e. be such that \( \lim_{x \downarrow 0} \frac{L_f(tx)}{L_f(x)} = 1 \) for all \( t > 0 \). For a function \( f \), \( f^{(k)} \) denotes the \( k \)-th derivative of \( f \).

**Assumption 1.**

(i) \( g(x) = x^\alpha L_g(x) \).

(ii) \( g^{(2)}(x) = x^{\alpha-2}L_{g^{(2)}}(x) \) and for any \( \epsilon > 0 \), we have \( g^{(2)} \in L^2((\epsilon,\infty)) \). Furthermore, \( |g^{(2)}| \) is non-increasing on the interval \((a,\infty)\) for some \( a > 0 \).

(iii) For any \( t > 0 \)

\[
F_t = \int_{1}^{\infty} \left| g^{(2)}(s) \right|^2 \sigma_{t-s}^2 ds < \infty
\]

almost surely.

The next set of assumptions deals with the variogram \( R \).

**Assumption 2.** For the roughness parameter \( \alpha \) from Assumption 1, it holds that

(i) \( R(x) = x^{2\alpha+1}L_R(x) \).

(ii) \( R^{(4)}(x) = x^{2\alpha-3}L_{R^{(4)}}(x) \).

(iii) There exists a \( b \in (0,1) \) such that

\[
\limsup_{x \downarrow 0} \sup_{y \in [x,xb]} \left| \frac{L_{R^{(4)}}(y)}{L_R(x)} \right| < \infty.
\]

Finally, we introduce an assumption on the smoothness of the process \( \sigma \).

**Assumption 3-\( \gamma \).** For any \( q > 0 \), it holds that

\[
\mathbb{E}\left[|\sigma_t - \sigma_s|^q\right] \leq C_q |t-s|^{\gamma q}
\]

for some \( \gamma > 0 \) and \( C_q > 0 \).
Remark 1 The methods and results presented in this paper can be trivially extended to processes of the form
\[ X_t^* = \int_{-\infty}^{t} (g(t-s) - g_0(-s))\sigma_s dW_s, \quad t \geq 0, \]
where \( g \) is as before and \( g_0 : \mathbb{R} \to \mathbb{R} \) is a measurable function such that \( g(x) = 0 \) for all \( x < 0 \) and
\[ \int_{-\infty}^{t} (g(t-s) - g_0(-s))^2 \sigma_s^2 ds < \infty, \quad \text{for all } t \geq 0. \]
In particular, we note that \( X_t^* - X_s^* = X_t - X_s \) for any \( t > s \geq 0 \), which is why the techniques that rely on the increments of \( X \) presented below, apply, mutatis mutandis, to \( X^* \) as well.

Remark 2 Similarly, the results presented in this paper hold also when the BSS process \( X \) is distorted by a smooth drift. To be precise, denote by \( C^m([0, \infty)) \) the class of functions which are \( \lfloor m \rfloor \) times continuously differentiable and which \( \lfloor m \rfloor \)-th order derivative is Hölder continuous of order \( m - \lfloor m \rfloor \); if the stochastic process \( A = (A_t)_{t \geq 0} \) has paths in \( C^m([0, \infty)) \), then, according to Lemma 3.5 in Corcuera et al. (2013), the asymptotic theory presented below, and therefore also the bootstrap theory derived subsequently, will hold for the process
\[ Z_t = X_t + A_t, \quad t \geq 0, \]
where \( X \) is a BSS process satisfying Assumptions 1–3, provided that the condition
\[ (\min(2, m) - \alpha - 1/2) \cdot \min(p, 1) > 1/2 \]
also holds.

2.2 Power variation of the BSS process and its asymptotic theory

Under Assumptions 1 and 2, Corcuera et al. (2013, Theorem 3.1 and equation (4.5)) show that for \( v \in \mathbb{N} \)
\[ \tilde{V}(X; p, v)^n_{1, t} \xrightarrow{u.c.p} V(X; p)_t = m_p \int_0^t |\sigma_s|^p ds, \quad (5) \]
where \( m_p \equiv \mathbb{E}[|U|^p], \ U \sim N(0, 1) \), and \( u.c.p. \) denotes uniform convergence in \( \mathbb{P} \)-probability on compact sets. Corcuera et al. (2013, Theorems 3.2 and 4.5) also derive a joint asymptotic distribution of the vector \( \Delta_n^{-1/2} \left( \tilde{V}(X; p, 1)^n_{1, t} - V(X; p)_t, \tilde{V}(X; p, 2)^n_{1, t} - V(X; p)_t \right) \). In particular, under Assumptions 1–3 (Corcuera et al., 2013, Theorem 3.2),
\[ \Delta_n^{-1/2} \left( \frac{\tilde{V}(X; p, 1)^n_{1, t} - m_p \int_0^t |\sigma_s|^p ds}{\tilde{V}(X; p, 2)^n_{1, t} - m_p \int_0^t |\sigma_s|^p ds} \right) \xrightarrow{a} N(0, \Sigma_{p,t}), \quad (6) \]
Appendix B). However, this procedure has the shortcoming that the central limit theorem no longer holds.

Finally, expressions for $\lambda^j_p$ can be found in Appendix B.

Expressions for $\lambda^j_p$ can be made feasible by first estimating the factor $\tau_n(v)$, see Barndorff-Nielsen et al. (2014, Appendix B). However, this procedure has the shortcoming that the central limit theorem no longer holds.
As mentioned in the introduction, the CLT (11) may break down when \( \alpha \in \left[\frac{1}{4}, \frac{1}{2}\right) \), due to a potential bias term, which is asymptotically non-negligible in this case. This motivated Corcuera et al. (2013) to develop a modified estimator implementing gaps between increments, from which the power variation (3) is computed. By letting the gaps widen sufficiently fast, the estimator satisfies a CLT and the relevant increments become asymptotically independent. In this case, one can develop a bootstrap method based on the idea of wild bootstrap. While we have also worked out the details of this approach, we relegate them to a web appendix (Bennedsen et al., 2017a), since the case \( \alpha \in \left[\frac{1}{4}, \frac{1}{2}\right) \) seems to be of limited practical interest.

The results of Corcuera et al. (2013) do not explicitly allow for \( \alpha = 0 \). However, we can show that under slightly amended assumptions, the LLN and CLT developed for the COF estimator remain valid also in this case. Indeed, only Assumptions 1(ii) and 2(ii) need to be changed. In the rest of this paper, when \( \alpha = 0 \), we thus work under Assumptions 1–3 above with the following modifications to 1(ii) and 2(ii):

**Assumption 1.**

(iii') \( g^{(2)}(x) = Lg^{(2)}(x) \) and for any \( \epsilon > 0 \), we have \( g^{(2)} \in L^2((\epsilon, \infty)) \). Furthermore, \( |g^{(2)}| \) is non-increasing on the interval \((a, \infty)\) for some \( a > 0 \).

**Assumption 2.**

(ii') \( R^{(4)}(x) = f(x)L_{R^{(4)}}(x) \), where the function \( f \) is such that \( |f(x)| \leq Cx^{-\beta} \) for some constants \( C > 0 \) and \( \beta > 1/2 \).

We now obtain the following result, which is proved in Appendix D.

**Proposition 2.1** Suppose Assumptions 1, 2, and 3-\( \gamma \) hold. Then the LLN (8) and CLT (11) hold with \( \alpha = 0 \).

**Example 2.1** The Ornstein-Uhlenbeck kernel \( g(x) = e^{-\lambda x}, \lambda > 0 \), satisfies Assumptions 1 and 2 with \( \alpha = 0 \). Indeed, Assumption 1 is trivially seen to hold and since

\[
R(x) = \lambda^{-1} \left(1 - e^{-\lambda x}\right) = xL_R(x),
\]

where

\[
L_R(x) = x^{-1} \lambda^{-1} \left(1 - e^{-\lambda x}\right)
\]

is a slowly varying function, Assumption 2(i) also holds. We also have

\[
R^{(m)}(x) = (-1)^{m-1} \lambda^{m-1} e^{-\lambda x}, \quad m \geq 1,
\]
so Assumption 2(ii') holds with \( f(x) = e^{-\lambda x} \) and \( L_R(4) = -\lambda^{-3} \). Lastly,

\[
\lim_{x \downarrow 0} L_R(x) = 1,
\]
so Assumption 2(iii) clearly also holds.

3 The local fractional bootstrap

In this section, we introduce a bootstrap method for a general class of nonlinear transformations of the vector \((\bar{V}(X; p, 1)^n_t, \bar{V}(X; p, 2)^n_t)\). We then use the method to approximate the sampling distribution of the roughness parameter estimator \( \hat{\alpha}^n_t(p) \). In particular, we consider a hypothesis test where the null hypothesis is

\[ H_0 : \alpha = \alpha_0 \]

for some \( \alpha_0 \in (-\frac{1}{2}, \frac{1}{2}) \), whereas the alternative hypothesis is

\[ H_1 : \alpha \neq \alpha_0. \]

Our idea is to resample the high frequency second order differences of the BSS process \( X \) as defined in (3). To be valid, the method should mimic the dependence properties of the increments of \( X \). As pointed out in Corcuera et al. (2013), under Assumption 2, the short-term behavior of the Gaussian core \( G \) is similar to that of a fractional Brownian motion \( B_H \) with Hurst parameter \( H = \alpha + 1/2 \). More precisely, for any \( t_0 \in \mathbb{R} \),

\[
\left( \frac{G_{t+t_0} - G_{t_0}}{\sqrt{\text{Var}(G_{\varepsilon} - G_0)}} \right)_{t \geq 0} \xrightarrow{\mathcal{D}} (B^H_t)_{t \geq 0} \in C(\mathbb{R}^+) \]

as \( \varepsilon \to 0 \). We propose the following local fractional bootstrap algorithm:

Step 1. Specify a null hypothesis \( H_0 : \alpha = \alpha_0 \) by fixing \( \alpha_0 \in (-\frac{1}{2}, \frac{1}{2}) \).

Step 2. Generate \( \lfloor t/\Delta_n \rfloor \) random variables, \( B^H_{\Delta_n}, \ldots, B^H_{[t/\Delta_n]} \), which are independent of the original process \( X \), where \( B^H \) is a fractional Brownian motion with Hurst parameter \( H = \alpha_0 + 1/2 \).

Step 3. Finally, return the observations

\[
X^*_{t\Delta_n} = \bar{V}(p', v)^n_t : B^H_{i\Delta_n}, \quad i = 2v, \ldots, [t/\Delta_n], \tag{12}
\]

where we let (cf. Equation (5))

\[
\bar{V}(p', v)^n_t = \left( m^{-1} (X; p', v)^n_t \right)^{1/p'}. \tag{13}
\]

for some \( p' > 0 \) and \( v = 1, 2 \).
The local fractional bootstrap method data-generating process (DGP) is motivated by the following constant-volatility toy model,
\[ \tilde{X}_t = \sigma G_t = \sigma \int_{-\infty}^{t} g(t-s) \, dW_s, \quad t \geq 0, \quad (14) \]
obtained from \( X \) by setting \( \sigma_t = \sigma > 0 \) for all \( t \in \mathbb{R} \). The first component in (12) (i.e., \( \tilde{\sigma}(p', \nu)^n_t \)) contains information about the volatility process \( (\sigma_t)_{t \in \mathbb{R}} \), whereas the presence of the second component, \( B^H_{t\Delta_n} \), is to replicate the local asymptotic distributional properties of \( X_t \), in particular, the correlation structure of the increments of a fractional Brownian motion with Hurst parameter \( H = \alpha + 1/2 \).

This bootstrap algorithm deserves a few comments. First, we generate the bootstrap observations under the null hypothesis \( H_0 : \alpha = \alpha_0 \); this feature is not only natural, but it is important to minimize the probability of a type I error, see e.g. Davidson and MacKinnon (1999). Second, although (12) is motivated by the very simple model (14), and the volatility \( \sigma \) is not estimated locally, as we will show below, this does not prevent the bootstrap method to be valid more generally. In particular, its validity extends to the case where the volatility is not constant as in (1). To see why this is the case, consider the studentized statistic \( \hat{S}_n \) (cf. Equation (7)) and note that the asymptotic distribution of \( \hat{S}_n \) is not a function of \( (\sigma_t)_{t \in \mathbb{R}} \). Thus using a local or a global way to estimate the volatility (12) would not prevent the bootstrap to be valid for percentile- \( t \) methods i.e, when the bootstrap statistic is normalized by its bootstrap standard deviation. In such a context, the asymptotic validity of the local fractional bootstrap approach depends mainly on its ability to mimic the leading term driving the limiting result in (7), i.e., \( \Lambda_p^{-1/2} T_n \), where \( T_n \) is defined by (29). This is exactly what the presence of the second component in (12) does.

The structure of our local fractional bootstrap method can be related to the works of Hounyo (2018) (see also the related work of Gonçalves and Meddahi, 2009; Dovonon et al., 2018) and Hounyo and Varneskov (2017). As Hounyo (2018) and Hounyo and Varneskov (2017) explain, the fine scale behavior of Brownian semimartingales can be approximated locally, either by Gaussian or stable processes, respectively.

In particular, in Hounyo (2018), local Gaussian bootstrap high-frequency increments are obtained by drawing a random draw from a normal distribution with mean zero and variance given by the realized volatility computed over blocks of consecutive \( M \) observations. It may be possible to adapt and extend the local Gaussian bootstrap method of Hounyo (2018) to the present setting, where one could possibly replace \( \tilde{\sigma}(p', \nu)^n_t \) (in equation (12)) by a local estimator of volatility. However, such an extension is not straightforward and proving the asymptotic validity for such a method is an open, but interesting, question. We leave this for future research.

Hounyo and Varneskov (2017) provides a bootstrap method for power variations and a change-of-frequency activity index estimator. The local stable bootstrap approach introduced in Hounyo
and Varneskov (2017) is a particular wild-type bootstrap method, where the external random variable used in their bootstrap algorithm is a function of stable random variables which mimic the local asymptotic behavior of Itô semimartingales as well as the dependence that arises from using (possibly) higher-order increments. Whereas in the current paper we use the fine scale property of Brownian semimartingales to propose the local fractional bootstrap method and a bootstrap-based inference procedure for the roughness index \( \alpha \) of \( X_t \), in Hounyo and Varneskov (2017) the fine scale property of Brownian semimartingales is used to propose the local stable bootstrap algorithm and a bootstrap-based inference procedure for the activity index of the underlying process. It is worthwhile to emphasize that the setting, the goal and the bootstrap algorithms in the current paper and in Hounyo and Varneskov (2017) are different.

Next, we define the bootstrap power variations analogues of (3) and (4), as follows

\[
\begin{align*}
V^* (X, B^H; p, p', v)_t^n & \equiv \frac{[\hat{\sigma}(p', v)_t^n | p]}{\overline{p}(p, v)_t^n} V(B^H; p, v)_t^n, \\
\tilde{V}^* (X, B^H; p, p', v)_t^n & \equiv \Delta_n \tau_n (v)^{-p} V^* (X, B^H; p, p', v)_t^n \\
& = \frac{[\hat{\sigma}(p', v)_t^n | p]}{\overline{p}(p, v)_t^n} V(B^H; p, v)_t^n, 
\end{align*}
\]

(15)

where \( \overline{p}(p, v)_t^n = \Delta_n \tau_n (v)^{-p} \mu(p, v)_t^n \) with \( \mu(p, v)_t^n = \mathbb{E} (V(B^H; p, v)_t^n) \). Note that we do not require the two power parameters \( p \) and \( p' \) to be equal; that is, the power parameter used to estimate volatility \( \sigma \) need not be the same power parameter used when constructing the power variations of the auxiliary fractional Brownian motion \( B^H \).

**Lemma 3.1** Consider (1), (15), and (16) where \( B^H \) is a fractional Brownian motion with Hurst parameter \( H = \alpha_0 + 1/2 \). It follows that

(i) \( \mathbb{E} (\tilde{V}^* (X, B^H; p, p', v)_t^n) = [\hat{\sigma}(p', v)_t^n | p] \).

(ii) \( \text{Var}^* \left( \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 1)_t^n \right) = \Delta_n^{-1} \text{Var} \left( \tilde{V} (B^H; p, 1)_t^n \right) \frac{[\hat{\sigma}(p', 1)_t^n | p]}{\overline{p}(p, 1)_t^n} \).

(iii) \( \text{Var}^* \left( \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 2)_t^n \right) = \Delta_n^{-1} \text{Var} \left( \tilde{V} (B^H; p, 2)_t^n \right) \frac{[\hat{\sigma}(p', 2)_t^n | p]}{\overline{p}(p, 2)_t^n} \).

(iv) \( \text{Cov}^* \left( \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 1)_t^n, \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 2)_t^n \right) = \Delta_n^{-1} \text{Cov} \left( \tilde{V} (B^H; p, 1)_t^n, \tilde{V} (B^H; p, 2)_t^n \right) \frac{[\hat{\sigma}(p', 1)_t^n | p][\hat{\sigma}(p', 2)_t^n | p]}{\overline{p}(p, 1)_t^n \overline{p}(p, 2)_t^n} \).

(v) If \( [\hat{\sigma}(p', v)_t^n | p] \overset{u.c.p.}{\rightarrow} f_0^{\infty} |\sigma_s|^{2p} \, ds \) and \( [\hat{\sigma}(p', 1)_t^n | p] \overset{u.c.p.}{\rightarrow} f_0^{\infty} |\sigma_s|^{2p} \, ds \), then

\[
p^{-1} \lim_{n \to \infty} \sum^* (X, B^H; p, p')_t^n - \overline{\sum}_{p, t}^n = 0,
\]

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where

\[ \Sigma^* (X, B^H; p, p')^n_t \equiv \text{Var}^* \left( \Delta^{-1/2} \left( \tilde{V}^* (X, B^H; p, p', 1)^n_h \right) \right) , \quad \text{and} \]

\[ \Sigma^*_{p,t} \equiv \Lambda^*_p \int_0^t |\sigma_s|^{2p} ds , \]

such that

\[ \Lambda^*_p = \left( \frac{(\overline{p}(p, 1)^n_t)^{-2} \lambda_{11}^{11} + (\overline{p}(p, 2)^n_t)^{-1} - (\overline{p}(p, 2)^n_t)^{-1} \lambda_{12}^{12} }{(\overline{p}(p, 2)^n_t)^{-2} \lambda_{22}^{22} } \right) . \]

Part (v) of Lemma 3.1 shows that the bootstrap variance \( \Sigma^* (X, B^H; p, p')^n_t \) will only be a consistent estimator of \( \Sigma_{p,t} \) under the general model (1) if the following three conditions hold true:

\[ |\tilde{\sigma}(p', v)^n_t|^2 \overset{u.c.p.}{\rightarrow} \int_0^t |\sigma_s|^{2p} ds , \quad |\tilde{\sigma}(p', 1)^n_t| |\tilde{\sigma}(p', 2)^n_t|^p \overset{u.c.p.}{\rightarrow} \int_0^t |\sigma_s|^{2p} ds , \quad (17) \]

and

\[ \Lambda^*_p \rightarrow \Lambda_p \quad (\text{i.e.} \quad \overline{p}(p, v)^n_t \rightarrow 1) . \quad (18) \]

It is easy to see that by letting \( p' = 2p, \tilde{\sigma}(2p, v)^n_t = \left( \frac{m_{2p}}{2p} \tilde{V} (X; 2p, v)^n_{2p} \right)^{1/2} \) will satisfy (17). However, it may not be possible to satisfy (18). For instance, for \( p = 2 \), one can show that (see Appendix B)

\[ \mu(2, 1)^n_t = (|t/\Delta_n| - 1) \Delta_n^{2H} (4 - 2^{2H}) , \]

so that, clearly,

\[ \overline{p}(p, v)^n_t \rightarrow 1. \]

However, despite \( \Sigma^* (X, B^H; p, p')^n_t \) not being consistent for \( \Sigma_{p,t} \), we can still achieve an asymptotically valid bootstrap for the studentized distribution. To this end, we need to find a consistent estimator of \( \Sigma^* (X, B^H; p, p')^n_t \) based on bootstrap observations. We propose the following consistent estimator of \( \Sigma^* (X, B^H; p, p')^n_t \) defined by

\[ \tilde{\Sigma}^* (X, B^H; p, p')^n_t \equiv \left( \begin{array}{cc} \lambda_{11}^{11} & \lambda_{12}^{12} \\ \lambda_{22}^{12} & \lambda_{22}^{22} \end{array} \right) \left( \frac{\tilde{\sigma}(p, v)^n_t}{\overline{p}(p, v)^n_t} \right)^{2p} \]

\[ \left( \begin{array}{cc} \lambda_{11}^{11} & \lambda_{12}^{12} \\ \lambda_{22}^{12} & \lambda_{22}^{22} \end{array} \right) \left( \frac{\tilde{\sigma}(p, v)^n_t}{\overline{p}(p, v)^n_t} \right)^{2p} \]

where

\[ |\tilde{\sigma}(p, p', v)^n_t|^p = \tilde{V}^* (X, B^H; p, p', v)^n_t . \quad (19) \]

The key aspect is that we studentize the bootstrap statistic \( \Delta_n^{-1/2} \left( \tilde{V}^* (X, B^H; p, p', 1)^n_h \right) \) with \( \tilde{\Sigma}^* (X, B^H; p, p')^n_t \), and because this is a consistent estimator of \( \Sigma^* (X, B^H; p, p')^n_t \), this implies that

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the asymptotic variance of the bootstrap $t$-statistic defined by

$$\hat{S}_n^* = \left( \tilde{\Sigma}(X, B^H; p, p')_t^n \right)^{-1/2} \Delta_n^{-1/2} \left( \tilde{V}(X, B^H; p, p', 1)_t^n - E^* \left( \tilde{V}(X, B^H; p, p', 1)_t^n \right) \right)$$

is a two dimensional identity matrix $I_2$ (see, e.g., Gonçalves and Meddahi, 2009; Hounyo, 2017; Hounyo and Varneskov, 2017, for a similar approach). In the following theorem, we provide a theoretical justification for using the bootstrap distribution of $\hat{S}_n^*$ to estimate the distribution of $\hat{S}_n$ (cf. Equation (7)).

**Theorem 3.1** Suppose that Assumptions 1, 2, and 3-$\gamma$ hold with $\gamma \in (0, 1)$ and $\alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right)$. Assume that bootstrap observations are given by (12) where $B^H$ is a fractional Brownian motion with Hurst parameter $H = \alpha_0 + 1/2$. It follows that as $n \to \infty$,

(i) $$\hat{S}_n^* \Rightarrow N(0, I_2),$$

in prob-$P$.

(ii) Suppose further, that $\gamma \cdot \min\{1, p\} > 1/2$. Then, we also have

$$\sup_{x \in \mathbb{R}^2} \left| P^* \left( \hat{S}_n^* \leq x \right) - P \left( \hat{S}_n \leq x \right) \right| \Rightarrow 0.$$ 

Thus, we can deduce a bootstrap CLT result for the bootstrap roughness parameter estimator $\hat{\alpha}^* (p, p')_t^n$ analogue of $\hat{\alpha} (p)_t^n$. To this end, let

$$\hat{\alpha}^* (p, p')_t^n = h_p \left( COF^* (p, p')_t^n \right),$$

where $h_p (\cdot)$ is defined by (9), whereas

$$COF^* (p, p')_t^n = \frac{V^* (X, B^H; p, p', 2)_t^n}{V^* (X, B^H; p, p', 1)_t^n}. \quad (21)$$

To understand the asymptotic behavior of $COF^* (p, p')_t^n$, we can write

$$COF^* (p, p')_t^n = \left( \frac{\tau_n (2)^2}{\tau_n (1)^2} \right)^{p/2} \frac{V^* (X, B^H; p, p', 2)_t^n}{V^* (X, B^H; p, p', 1)_t^n}.$$ 

From Assumption 2, we have

$$\left( \frac{\tau_n (2)^2}{\tau_n (1)^2} \right)^{p/2} \to 2^{\frac{3 \gamma + 1}{2}},$$

and thus by Theorem 3.1, part (i) of Lemma 3.1, in conjunction with (13), and by using equation
(5) with \( v = 1, 2 \), we can deduce that

\[
\frac{\hat{V}^* (X, B^H; p, p', 2)^n_t}{\hat{V}^* (X, B^H; p, p', 1)^n_t} \overset{p}{\to} 1, \quad \text{in prob-\( \mathbb{P} \).}
\]

It follows that, by applying the delta method on the CLT results of Theorem 3.1, we can characterize the distribution of \( \hat{\alpha}^* (p, p')_t^n \). These results are summarized in the following theorem.

**Theorem 3.2** Suppose that Assumptions 1, 2, and 3-\( \gamma \) hold with \( \gamma \in (0, 1) \) and \( \alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right) \). Assume that bootstrap observations are given by (12) where \( B^H \) is a fractional Brownian motion with Hurst parameter \( H = \alpha_0 + 1/2 \). We have that,

(i) For \( p \geq 2 \), as \( n \to \infty \),

\[
T^*_{\hat{\alpha}, n} = \Delta_n^{-1/2} \frac{(\hat{\alpha}^* (p, p')_t^n - \check{\alpha} (p, p')_t^n)}{\sqrt{\hat{V}^* (\hat{\alpha})_t}} \overset{d}{\to} N (0, 1), \quad \text{in prob-\( \mathbb{P} \),}
\]

where

\[
\check{\alpha} (p, p')_t^n = h_p \left( \hat{COF} (p, p')_t^n \right), \tag{22}
\]

with

\[
\hat{COF} (p, p')_t^n = \left( \frac{\tau_n (2)^{p/2}}{\tau_n (1)^{p/2}} \right) \left| \frac{\hat{\sigma}(p', 2)_t^n p}{\hat{\sigma}(p', 1)_t^n p} \right|^p = \left( \frac{V (X; p', 2)_t^n}{V (X; p', 1)_t^n} \right)^{p/p'}.
\]

The estimator of the asymptotic variance \( \hat{V}^* (\hat{\alpha})_t \) is defined as

\[
\hat{V}^* (\hat{\alpha})_t = \frac{1}{(p \log (2))^2} \check{\zeta}^* (X, B^H; p, p')_t^n, \tag{23}
\]

with

\[
\check{\zeta}^* (X, B^H; p, p')_t^n
\]

\[
 = \frac{\lambda_{p,n}^{11}}{\left[ \hat{E}^* (V^* (X, B^H; p, p', 1)_t^n) \right]^2} \frac{(\hat{\sigma}(p', 1)_t^n p)^2}{(\hat{\sigma}(p', 1)_t^n p)^2} + \frac{\lambda_{p,n}^{22}}{\left[ \hat{E}^* (V^* (X, B^H; p, p', 2)_t^n) \right]^2} \frac{(\hat{\sigma}(p', 2)_t^n p)^2}{(\hat{\sigma}(p', 2)_t^n p)^2}
\]

\[
- 2 \frac{\lambda_{p,n}^{12}}{\hat{E}^* (V^* (X, B^H; p, p', 1)_t^n) \hat{E}^* (V^* (X, B^H; p, p', 2)_t^n)} \frac{|\hat{\sigma}(p', 1)_t^n p|^p |\hat{\sigma}(p', 2)_t^n p|^p}{\hat{\sigma}(p', 1)_t^n p |\hat{\sigma}(p', 2)_t^n p|}.
\]

(ii) Suppose further, that \( \gamma \cdot \min \{1, p \} > 1/2 \) and \( \alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right) \). Now, for \( p \geq 2 \), as \( n \to \infty \),

\[
\sup_{x \in \mathbb{R}} \left| P^* \left( T^*_{\hat{\alpha}, n} \leq x \right) - P \left( T_{\hat{\alpha}, n} \leq x \right) \right| \to 0,
\]

in probability-\( \mathbb{P} \), where \( T_{\hat{\alpha}, n} \) is defined in (11).

Theorem 3.2 provides theoretical justification for using the bootstrap distribution of \( T^*_{\hat{\alpha}, n} \) to estimate the entire distribution of \( T_{\hat{\alpha}, n} \). Once again, it is worth emphasizing that these results hold
under general BSS model described by (1), which allows for time-varying volatility. As the proofs of Theorem 3.1 and 3.2 show, the asymptotic validity of the local fractional bootstrap depends mainly on the availability of a CLT result for \( T_n \), defined by (29) (i.e., the leading term driving the limiting result in (6)), and the fact that \( \hat{\Sigma}^* (X, B^H; p, p')_t^n \) consistently estimate \( \Sigma^* (X, B^H; p, p')_t^n \), which hold directly under the conditions of Theorems 3.1 and 3.2.

**Remark 3** Note that under the alternative, i.e., \( H_1 : \alpha = \alpha_1 \) with \( \alpha_1 \in (-\frac{1}{2}, \frac{1}{2}) \) such that \( \alpha_1 \neq \alpha_0 \) and under the conditions of Theorem 3.2, the bootstrap statistic

\[
T^*_{\hat{\alpha}, n} \overset{d^*}{\to} N (0, 1), \text{ in probability.}
\]

The fact that (we can show) \( T^*_{\hat{\alpha}, n} \to \infty \) under the alternative, but we still have \( T^*_{\hat{\alpha}, n} \overset{d^*}{\to} N (0, 1) = O_p^* (1) \) as \( n \to \infty \), in probability, ensures that the bootstrap test has unit power asymptotically. See, e.g., Dovonon et al. (2018) for similar discussion on this property of the bootstrap test in context of Brownian semimartingales, see also Christensen et al. (2018).

**Remark 4** The bootstrap statistic \( T^*_{\hat{\alpha}, n} \) is feasible and straightforward to calculate. We give the details in Appendix A.

### 3.1 Bootstrap Implementation

We can use the bootstrap method proposed above to test hypotheses on the roughness of the sample paths of a BSS process. Consider the following, where the null hypothesis is \( H_0 : \alpha = \alpha_0 \) for some \( \alpha_0 \in (-\frac{1}{2}, \frac{1}{2}) \), whereas the alternative hypothesis is \( H_1 : \alpha \neq \alpha_0 \). For a given time period \([0, t] \) with step size \( \Delta_n = \frac{t}{n} \) we suppose we have \( n + 1 \in \mathbb{N} \) observations \( X = (X_0, X_{\Delta_n}, \ldots, X_{n\Delta_n}) \) of a BSS process. Below, \( B \) is the number of bootstrap replications (e.g., \( B = 999 \)).

#### Algorithm for hypothesis testing using the Local Fractional Bootstrap

1. From the data \( X \), compute the estimate of the roughness parameter \( \alpha \) given by

\[
\hat{\alpha} (p)_n^t = h_p (COF (p)_n^t),
\]

where \( h_p (\cdot) \) and \( COF (p)_n^t \) are given in (9) and (10), respectively. Then, compute an estimator of the asymptotic variance \( V (\hat{\alpha})_n^t = \lim_{n \to \infty} \text{Var} (\hat{\alpha} (p)_n^t) \), given by

\[
\hat{V} (\hat{\alpha})_t = n \frac{m_{2p}^{-1} V (X_0, X_{2p}, 1)_t^n (-1, 1) \Lambda_2 (-1, 1)^T}{(p \log (2) V (X_0, p, 1)_n^2)^2}.
\]

2. Simulate \( n + 1 \) observations \( B^H_0, B^H_{\Delta_n}, \ldots, B^H_{n\Delta_n} \) of a fractional Brownian motion with Hurst parameter \( H = \alpha_0 + 1/2 \) that are independent of the data \( X \).
3. Using the simulated sample \((B^H_0, B^H_1, \ldots, B^H_n)\), compute the estimate of the bootstrap roughness parameter \(\hat{\alpha}^* (p)_t^n\), given by
\[
\hat{\alpha}^* (p, p')_t^n = h_p (\text{COF}^* (p, p')_t^n),
\]
where \(h_p (\cdot)\) and \(\text{COF}^* (p, p')_t^n\) are given in (9) and (24), respectively.

4. The actual test relies on the bootstrap studentized statistic. Thus, compute
\[
T^*_\ell = \Delta_n^{-1/2} \left( \hat{\alpha}^* (p, p')_t^n - \hat{\alpha} (p, p')_t^n \right) \sqrt{\hat{V}^* (\hat{\alpha})_t},
\]
where \(\alpha (p, p')_t^n\) is given by (22), whereas \(\hat{\alpha}^* (p, p')_t^n\) is obtained in step 3, and \(\hat{V}^* (\hat{\alpha})_t\) is defined in (23).

5. Repeat steps 2–4 \(B\) times and store the values of \(T^*_{\ell, n, j}, j = 1, \ldots, B\).

6. Reject \(H_0 : \alpha = \alpha_0\), when
\[
\alpha_0 \notin \text{IC}_{\text{perc–}t, 1-\gamma}^* = \left[ \hat{\alpha} (p)_t^n - n^{-1/2} q^*_{1-\gamma/2} \sqrt{\hat{V} (\hat{\alpha})_t}, \hat{\alpha} (p)_t^n - n^{-1/2} q^*_{\gamma/2} \sqrt{\hat{V} (\hat{\alpha})_t} \right],
\]
where \(q^*_{\gamma/2}\) and \(q^*_{1-\gamma/2}\) are the \(\gamma/2\) and \(1 - \gamma/2\) quantiles of the bootstrap distribution of \(T^*_{\ell, n}\), respectively.

4 Monte Carlo simulation study

In this section, we evaluate the finite sample performance of the test based on local fractional bootstrap and compare it to the performance of the CLT-based test. In our simulations we take \(g\) to be the gamma kernel, i.e. \(g(x) = x^\alpha e^{-\lambda x}\) for \(x > 0\) and with \(\lambda = 1\). For an in-depth analysis of the theoretical properties of the gamma kernel, see Barndorff-Nielsen (2012, 2016). We consider \(\alpha \in \{-\frac{1}{3}, -\frac{1}{6}, 0, \frac{1}{6}, \frac{1}{3}\}\); recall that the CLT for the COF estimator may not hold when \(\alpha \in \left[\frac{1}{4}, \frac{1}{3}\right]\). We experimented with several different values of \(\lambda\) and \(\alpha\), but the results were in all cases very similar to what we find below. We consider three specifications for the stochastic volatility process:

- constant volatility (NoSV),
- one-factor stochastic volatility (SV1F),
- two-factor stochastic volatility (SV2F).

The details of these specifications, along with the simulation procedure, are explained in Appendix C. Our investigations concern the finite sample size of the test \(H_0 : \alpha = \alpha_0\) against the two-sided alternative \(H_1 : \alpha \neq \alpha_0\) at (nominal) 5% level. We also calculate the size-adjusted power.
of the test at 5% level where the (now false) null hypothesis is $H_0 : \alpha = 0$.\(^3\) The null hypothesis $H_0 : \alpha = 0$ is particularly interesting as $\alpha = 0$ is a necessary condition for the semimartingality of $X$. Further, in the case of the gamma kernel $g(x) = x^\alpha e^{-\lambda x}$ that we consider here, $\alpha = 0$ implies that the BSS process actually is an Ornstein-Uhlenbeck process.

Tables 1 and 2 contain the results of our Monte Carlo study and detail the finite sample properties of both the CLT and the local fractional bootstrap. Table 1 presents rejection rates of $H_0$ when $H_0$ is true (i.e., the size), while Table 2 displays rejection rates of $H_0$ when $H_1$ is true (i.e., the power). Some clear conclusions can be drawn. Firstly, the bootstrap method offers clear gains in the size of the test when the number of observations, $n$, is small. Secondly, the power of the CLT is slightly better for $\alpha < 0$, while the opposite is true for $\alpha \geq 0$. Finally, the presence or absence of SV does not alter results very much, except in the case of SV2F — i.e., very active stochastic volatility — where the methods lose some power. Interestingly, both methods work well also in the case $\alpha = 1/3$, which is excluded in the theory presented above. However, this is likely due to the particular kernel used for the BSS process in this simulation study; other specifications might result in invalid inference when $\alpha \geq 1/4$.

5 Empirical applications

In this section, we apply the local fractional bootstrap method presented above to two relevant empirical data sets. As we saw in the previous section, the bootstrap method is crucial for achieving the correct empirical size of the hypothesis test $H_0 : \alpha = \alpha_0$, especially when the number of observations $n$ is small. In both of our applications, theoretical arguments suggest specific null hypotheses to be true, and we examine how the CLT and bootstrap fare in confirming or rejecting these hypotheses.

5.1 High-frequency futures price data

Here, we consider testing $H_0 : \alpha = 0$ for the price of a financial asset, the E-mini S&P 500 futures contract. Note that, at least theoretically, on no-arbitrage grounds (Delbaen and Schachermayer, 1994, Theorem 7.2) one would expect $H_0$ to be true, since $\alpha \neq 0$ implies that the BSS process is not a semimartingale (e.g., Corcuera et al., 2013), breaching the no free lunches with vanishing risk (NFLVR) condition.

Our data consists of high-frequency\(^4\) observations of the price of E-mini S&P 500 futures contract.

---

\(^3\)The size-adjusted power was obtained in the following way: Using Monte Carlo simulations we found critical values that would result in the CLT obtaining the same size as the bootstrap (see Table 1 for these size numbers); these critical values were then used to determine the power of the CLT-based test. As the bootstrap test seems to be correctly sized for all $n$ this was not size-corrected. By using the actual size of the bootstrap test (instead of the nominal 5%) to calculate the size-adjusted critical value for the CLT-based test, the power properties of the two tests become comparable.

\(^4\)The data have been recorded with one-second time stamp precision.
Table 1: Rejection rates under $H_0$

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<th>Panel A: NoSV</th>
<th>$n$</th>
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Simulation study of the finite sample properties of the test $H_0 : \alpha = \alpha_0$ against the alternative $H_1 : \alpha \neq \alpha_0$, using the CLT and the local fractional bootstrap. The simulations are done under $H_0$, i.e. we consider the size of the tests. The nominal size is 5% and the numbers shown are the rejection rates of $H_0$ over 5000 Monte Carlo simulations, each with $B = 999$ bootstrap replications. We set $p = p' = 2$ and $\lambda = 1$. 

Table 2: Rejection rates under $H_1$

Panel A: NoSV

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Panel B: SV1F

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Panel C: SV2F

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<td>0.2834</td>
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<td>0.4332</td>
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Simulation study of the finite sample properties of the test $H_0 : \alpha = 0$ against the alternative $H_1 : \alpha \neq 0$, using the CLT and the local fractional bootstrap. The simulations are done under the alternative, i.e. we consider the power of the tests, with the true value of $\alpha$ used in the simulations being the $\alpha$ indicated in the respective column. For the bootstrap, the nominal size is 5%, while the CLT has been size-adjusted as explained in the text: the critical value used is the critical value that results in the CLT having the same size as the bootstrap test (given in Table 1). The numbers shown are the rejection rates of $H_0$ over 5,000 Monte Carlo simulations, each with $B = 999$ bootstrap replications. We set $p = p' = 2$ and $\lambda = 1$.
tract, traded on CME Globex electronic trading platform, from January 3, 2005 until December 31, 2014. We exclude weekends and holidays and retain only full trading days, resulting in 2,495 days in our sample. Although the E-mini S&P 500 contract is traded almost around the clock, we restrict attention to the most liquid time period which is when the NYSE is open, i.e., to the 6.5 hours from 9:30 a.m. to 4 p.m. EST.

We study the data at various time scales. More concretely, we resample the price every $\Delta \in \{30, 60, 120, 300, 600\}$ seconds, which results in $n = 780, 390, 195, 78, 39$ prices per day, respectively. We then test $H_0 : \alpha = 0$ for each day, using both the CLT and local fractional bootstrap, against the two-sided alternative $H_1 : \alpha \neq 0$. The results are presented in Panel A of Table 3, where we give the rejection rates of $H_0$, i.e., the fraction of days where we reject $H_0$ in favor of $H_1$. In the table, we report yearly rejection rates of $H_0$ from 2005 to 2014 (with roughly 250 days per year) and the overall rejection rate for the entire sample (i.e., over 2,495 days). We find that at short time scales (i.e., $\Delta = 30$ or $\Delta = 60$ seconds), both the CLT and bootstrap reject $H_0 : \alpha = 0$ significantly more often than what the nominal size of 5% would suggest if $H_0$ were true. While seemingly surprising from the arbitrage point of view, this result is naturally explained by market microstructure (MMS) noise effects (Hansen and Lunde, 2006). At very short time scales, high-frequency data are known exhibit negative autocorrelations that are compatible with the case $\alpha < 0$ nested in the alternative hypothesis, albeit unlikely to be arbitrageable in practice.

At longer time scales, i.e., when $\Delta$ is at least 5 minutes, one would expect the MMS effects to subdue and rejections of $H_0$ to occur nearly at the nominal rate. Panel A of Table 3 confirms that this is indeed the case. Further, we also observe that the bootstrap method rejects less often than the CLT, the bootstrap being closer to the nominal 5% rejection rate under $H_0$. When $\Delta = 600$ seconds, we have only $n = 39$ observations per day, and in view of the Monte Carlo results presented in Table 1, we would expect the CLT to be oversized in this case. As seen in the Table 3, the CLT indeed rejects $H_0$ more frequently here, the rejection rate in the entire sample being 9.06%, while the bootstrap essentially retains the nominal size, rejecting on 5.06% of the days. The same conclusion holds for $\Delta = 300$ seconds. This is encouraging as any MMS effects should be negligible at these time scales for a liquid asset like E-mini.

Sampling prices less frequently, in particular when $\Delta = 300$ seconds or $\Delta = 600$ seconds, we have only a small number of observations per day, $n = 78$ and $n = 39$, respectively. Given the simulation results for the empirical power of the tests in Table 2, one might suspect that the low rejection rates for the E-mini data are due to the methods suffering from low power.

\footnote{Indeed, as shown in Bennedsen (2018), MMS noise in the observations will bias estimates of $\alpha$ downwards, which makes a plausible explanation for the elevated rejection rates. In simulations (not reported here, but available on request) we confirmed that this is in fact the case: noise in the observations will cause both the CLT and bootstrap to over-reject when the null is true.}

\footnote{We thank an anonymous referee for pointing this out.}
this concern, we conduct an analysis analogous to the one of Panel A of Table 3, where we use data over a week (i.e., 5 days), instead of a day, for each estimate of $\alpha$. Overnight returns were discarded when calculating the power variations, since they would appear anomalous. Effectively, this setup yields a five-fold increase in the number of observations used for each test of $H_0$. The results are given in Panel B of Table 3. The conclusions we can draw are as expected: we reject $H_0$ more frequently at short time scales — presumably due to the increased power gained by having more observations — and we still reject $H_0$ close to the nominal 5% rate at longer time scales, where we do not expect MMS effects to be significant (i.e., for $\Delta = 300$ seconds and $\Delta = 600$ seconds). Again we see that the CLT rejects slightly more often than the bootstrap, although it is now closer to the nominal rejection rate, at least when $\Delta = 600$ seconds.

**Remark 5** It should be noted, that the methods employed in this section — both the CLT and local fractional bootstrap — are theoretically not valid when the observed process has jumps, which might a priori be the case for the price process of a financial asset, such as the one studied here. It is conceivable that one could derive jump-robust inference methods based on multipower variations of BSS processes, similar to those developed in the semimartingale case (e.g., Barndorff-Nielsen and Shephard, 2004), but the asymptotic theory for BSS processes is lacking in this respect, so this extension is beyond the scope of this paper. We believe, however, that it is quite unlikely that jumps are influencing the analyses presented here to any meaningful degree. In fact, Christensen et al. (2014) and Bajgrowicz et al. (2016) have recently presented compelling evidence of the relative infrequency of jumps in asset prices, especially for highly liquid assets similar to the E-mini futures contract studied here.

### 5.2 Turbulence data

In our second application, we study a time series of one-dimensional hot-wire anemometer measurements of the longitudinal component of a turbulent velocity field in the atmospheric boundary layer, measured 35 meters above ground level. The time series consists of $2 \times 10^7$ observations, sampled at a rate of 5 kHz. In other words, there are 20 million observations, measured over a period of $T = 4000$ seconds with 5000 observations recorded per second. This time series was also studied in Corcuera et al. (2013) and Barndorff-Nielsen et al. (2014), and we refer to Dhruva (2000) for further details on how it was recorded.

When timewise data on turbulence is modeled using a BSS process whose kernel function satisfies Assumption 1(i), Kolmogorov’s 5/3 scaling law (Kolmogorov, 1941) for fully developed turbulence, assuming Taylor’s frozen field hypothesis (Taylor, 1938), is compatible with the parameter value $\alpha = -1/6$ at intermediate time scales that correspond to the so-called inertial range; see also Márquez and Schmiegel (2016). By analyzing the spectral density of the time series, for
Table 3: Rejection rates of $H_0$ using high-frequency futures price data

**Panel A: Daily data**

<table>
<thead>
<tr>
<th>Year</th>
<th>$\Delta = 30$ s</th>
<th>$\Delta = 60$ s</th>
<th>$\Delta = 120$ s</th>
<th>$\Delta = 300$ s</th>
<th>$\Delta = 600$ s</th>
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<td>CLT boot</td>
<td>CLT boot</td>
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<tr>
<td>2005</td>
<td>0.6200</td>
<td>0.5800</td>
<td>0.2700</td>
<td>0.2360</td>
<td>0.0800</td>
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<tr>
<td>2006</td>
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<td>0.5240</td>
<td>0.2920</td>
<td>0.2520</td>
<td>0.1400</td>
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<td>2007</td>
<td>0.4640</td>
<td>0.4280</td>
<td>0.1280</td>
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<tr>
<td>2008</td>
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<td>0.2160</td>
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<td>2010</td>
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<td>0.4960</td>
<td>0.2360</td>
<td>0.2240</td>
<td>0.1400</td>
</tr>
<tr>
<td>2011</td>
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<td>0.3720</td>
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<td>0.1800</td>
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<tr>
<td>2012</td>
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<td>0.4880</td>
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<tr>
<td>2013</td>
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<td>0.4680</td>
<td>0.2720</td>
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<td>0.2080</td>
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<tr>
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<td>0.2735</td>
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<tr>
<td>All</td>
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<td>0.4247</td>
<td>0.2269</td>
<td>0.2049</td>
<td>0.1151</td>
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**Panel B: Weekly data**

<table>
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<tr>
<th>Year</th>
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<th>$\Delta = 120$ s</th>
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<td>0.1200</td>
</tr>
<tr>
<td>2006</td>
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<td>0.8600</td>
<td>0.6200</td>
<td>0.5400</td>
<td>0.2800</td>
</tr>
<tr>
<td>2007</td>
<td>0.6600</td>
<td>0.6600</td>
<td>0.2800</td>
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<td>0.1200</td>
</tr>
<tr>
<td>2008</td>
<td>0.4600</td>
<td>0.4400</td>
<td>0.3200</td>
<td>0.2800</td>
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<td>0.7551</td>
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<td>0.1884</td>
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Rejection rates of $H_0 : \alpha = 0$ against the alternative $H_1 : \alpha \neq 0$. Panel A: The data are sampled equidistantly every $\Delta$ time period over a day; each year has roughly 250 trading days, so that each number in the table is the average rejection rate over 250 days. The last row is the overall rejection rate for the entire sample, consisting of 2 495 trading days. Panel B: Same as in Panel A, but now the data are aggregated to weekly time series, with roughly 50 weeks in each year, so that each number represents the rejection rate over 50 weeks. The last row is the overall rejection rate for the entire sample, now consisting of 499 trading weeks. We set $p = p' = 2$ and $B = 999$ bootstrap replications.
this data the inertial range was found to be approximately between 0.1 Hz and 200 Hz (Corcuera et al., 2013, Section 5).

As in the previous application, we experiment with resampling the data at various frequencies \( f \), varying \( f \) to study the roughness properties of the time series at different time scales. More specifically, we vary \( f \) between 1 Hz and 200 Hz to include time scales both firmly within and on the border of the inertial range. The time increment \( \Delta \) used in resampling is related to \( f \) by \( \Delta = 1/f \). Motivated by Kolmogorov’s scaling law, we formulate \( H_0 : \alpha = -1/6 \) and test it against the two-sided alternative \( H_1 : \alpha \neq -1/6 \). In our analysis, we divide the sample period (of 4000 seconds) into \( M = 400 \) sub-periods of 10 seconds. We conduct the test on each sub-period individually, treating them as separate measurements of the same phenomenon, which seems reasonable given the putative stationarity of the time series. Note that after resampling at frequency \( f \), the number of observations covering each sub-period is \( n = 10f \).

Figure 1 presents results on the rejection rate of \( H_0 \), which is the relative frequency of rejections over the \( M = 400 \) sub-periods. As expected, \( H_0 \) is often rejected when the sampling rate is on the border of the inertial range (cf. the results for \( f = 200 \) Hz). When firmly inside the inertial range (\( f = 20 \) Hz), the null hypothesis is rejected in roughly 4% of the sub-periods for both methods. At these sampling frequencies, the CLT- and bootstrap-based tests largely agree; this is as expected since there are plenty of observations.

The results change as the sampling frequency is lowered, resulting in fewer observations. Indeed, we see that the CLT-based test yields rejection rates of 10.8% and 17.3% at sampling frequencies 1 and 2 Hz, respectively, while the bootstrap-based test rejects roughly at the nominal 5% rate, as we would expect from a correctly-sized test when \( H_0 \) is true. As seen also in the previous application, at low sampling frequencies (here 1 Hz, which leads to \( n = 10 \) observations), the COF estimator seems to be severely biased (the mean of the estimates of \( \alpha \) is around \(-0.475\)). In this case, the CLT-based test starts rejecting \( H_0 \) at an unplausibly high rate (around 17%) while the bootstrap-based test is more conservative with rejection rate around 6%. As we would still expect the null hypothesis \( H_0 : \alpha = -1/6 \) to be actually true at this sampling frequency, it is reassuring that the bootstrap-based test is so close to the nominal rate 5% in this, arguably extreme, case. However, this comes with the caveat that \( n = 10 \) observations might simply be too few to draw any definite conclusion on.

6 Conclusion

We have proposed a novel bootstrap method of conducting inference on the roughness index \( \alpha \) of a Brownian semistationary process using the change-of-frequency estimator. While our simulation study indicates that the performance of both the CLT- and bootstrap-based tests is generally good,
Figure 1: Estimates of $\alpha$ and test of $H_0 : \alpha = -1/6$ against $H_1 : \alpha \neq -1/6$ from 400 experiments using the turbulence data described in the text, see also Dhruva (2000). The data is sampled at frequency $f$. The plots depict the estimated value of $\alpha$ from a given experiment. The particular experiments where $H_0$ was rejected by both the CLT and LFB are shown by red squares; the experiments where only the CLT, but not the LFB, rejected are green diamonds; the experiments where only the LFB, but not the CLT, rejected are magenta asterisks; and the experiments where no method rejects $H_0$ are blue circles. We used $p = p' = 2$ and $B = 999$ bootstrap replications. The black horizontal line indicates the null value $\alpha = -1/6$. 
the bootstrap approach improves the size properties of the test of \( H_0 : \alpha = \alpha_0 \) when the number of observations is moderate or small.

As an application, we applied the method to test for \( H_0 : \alpha = 0 \) with a time series of intraday prices of the E-mini S&P 500 futures contract and to test for \( H_0 : \alpha = -1/6 \) with a time series of measurements of atmospheric turbulence. With both data sets, we observed what the simulation results already indicated: the CLT rejects the respective null hypotheses, that we expect to be true on theoretical grounds, too often when the number of observations is limited, while the local fractional bootstrap retains the correct size. We conclude that the local fractional bootstrap is a powerful alternative to the CLT when drawing inference on the roughness index \( \alpha \), and it appears to be essential at lower observation frequencies.

Finally, we note that while in this paper we have focused on BSS processes, the local fractional bootstrap method should be applicable to other “fractional” processes such as the fractional Brownian motion (fBm), fractional Ornstein-Uhlenbeck process, and the like. We leave such extensions for future work.

References


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A Feasibility of the bootstrap statistic of Theorem 3.2

The bootstrap statistic $T^*_{\alpha,n}$ is feasible: it is only a function of the original sample of the observed data $\{X_i \Delta_n\}$, the fractional Brownian motion generated in Step 2, $\{B^H_{i \Delta_n}\}$, and their absolute moments $\left\{E \left| 2B^H_{i\Delta_n} - 2B^H_{(i-v)\Delta_n} + B^H_{(i-2v)\Delta_n} \right|^p \right\}$. To see this, write

$$\alpha^*(p,p')_t = h_p \left( COF^*(p,p')_t \right),$$

where $h_p$ is a function depending on $p$. This demonstrates that the bootstrap statistic is feasible.
where \( h_p(\cdot) \) and \( COF^*(p,p')_t^n \) are given in (9) and (21), respectively. Given (21) and (15), it follows that
\[
COF^*(p,p')_t^n = \left( \frac{\tau_n(2)^2}{\tau_n(1)^2} \right)^{p/2} \frac{V^*(X,B^H;p,p',2)_t^n}{V^*(X,B^H;p,p',1)_t^n} = \frac{\mu(p,1)_t^n}{\mu(p,2)_t^n} \frac{V(B^H;p,2)_t^n}{V(B^H;p,1)_t^n} \left( \frac{V(X;p',2)_t^n}{V(X;p',1)_t^n} \right)^{p/p'}.
\]
(24)

Similarly, we can write \( \hat{V}^*(\hat{\alpha})_t \) of Theorem 3.2, cf. equation (23), through
\[
\hat{V}^*(\hat{\alpha})_t = \frac{1}{(p \log(2))^2} \zeta^* (B^H;p)_t^n,
\]
with
\[
\zeta^* (B^H;p)_t^n = A + B + C,
\]
where
\[
A = \Delta_n^{-1} (\mu(p,1)_t^n)^{-4} \left( V(B^H;p,1)_t^n \right)^2 Var \left( V(B^H;p,1)_t^n \right),
\]
\[
B = \Delta_n^{-1} (\mu(p,2)_t^n)^{-4} \left( V(B^H;p,2)_t^n \right)^2 Var \left( V(B^H;p,2)_t^n \right),
\]
\[
C = C_1 \cdot C_2,
\]
and
\[
C_1 = -2(\mu(p,1)_t^n)^{-2}(\mu(p,2)_t^n)^{-2} V(B^H;p,1)_t^n V(B^H;p,2)_t^n V(BH;p,1)_t^n V(BH;p,2)_t^n,
\]
\[
C_2 = \Delta_n^{-1} Cov \left( V(B^H;p,1)_t^n, V(B^H;p,2)_t^n \right).
\]

Expressions for \( \mu(p,v) \) for \( p > 0 \) and \( Var \left( V(B^H;p,v)_t^n \right), Cov \left( V(B^H;p,1)_t^n, V(B^H;p,2)_t^n \right) \) for \( p = 2 \) can be found in the next section, Appendix B. When \( p \neq 2 \), we do not have these latter expressions in closed-form, but they can be approximated straightforwardly by Monte Carlo simulation, cf., e.g., Appendix B in Bennedsen (2018).

**B  Expressions for \( \Lambda_p, \lambda^{i,j}_{p,n} \), and \( \mu(p,v)_t^n \)**

In both the ordinary CLT (11) as well as the bootstrap CLT there are various terms that are necessary to derive when implementing the methods. In particular, the ordinary CLT requires calculation of \( \Lambda_p = \{\lambda^{i,j}_p\}_{1 \leq i,j \leq 2} \) while the bootstrap CLT requires calculation of \( \{\lambda^{i,j}_{p,n}\}_{1 \leq i,j \leq 2} \) as well as \( \mu(p,v)_t^n = E^* \left( V(B^H;p,v)_t^n \right) \) for \( v = 1,2 \), see Remark 4. Although the calculations involved are quite straightforward, they are tedious. For the convenience of the reader, we supply the expressions for these terms here. In what follows we denote by \( n = \lfloor t/\Delta_n \rfloor \) the total number of observations.
Recall the specifications
\[
\lambda_{p,n}^{11} = \Delta^{-1} \text{var} \left( \tilde{V} (B^H; p, 1)_1^n \right),
\]
\[
\lambda_{p,n}^{22} = \Delta^{-1} \text{var} \left( \tilde{V} (B^H; p, 2)_1^n \right),
\]
\[
\lambda_{p,n}^{12} = \Delta^{-1} \text{cov} \left( \tilde{V} (B^H; p, 1)_1^n, \tilde{V} (B^H; p, 2)_1^n \right),
\]
and \(\lambda_{p,n}^{ij} = \lim_{n \to \infty} \lambda_{p,n}^{ij} \). Analytical expressions are only known for \(p = 2\), which is arguably the most relevant in empirical applications as it corresponds to using squared increments when calculating power variations. We therefore only consider \(p = 2\) here but, as mentioned above, the expressions can be easily approximated by Monte Carlo simulation; we refer to Appendix B of Bennedsen (2018) for the details.

Let \(\rho_{v_1,v_2}^H\) be the correlation function between the second order increments of the fractional Brownian motion with Hurst index \(H\), calculated at lag \(v_1\), and the second order increment calculated at lag \(v_2\). In other words
\[
\rho_{v_1,v_2}^H(h) := \text{Corr} \left( B_{i+h}^H - 2B_{i+h-v_1}^H + B_{i+h-2v_1}^H, B_i^H - 2B_{i-v_2}^H + B_{i-2v_2}^H \right), \quad h \in \mathbb{Z}.
\]
We will need the combinations \((v_1, v_2) = (1, 1), (2, 2), (1, 2)\) and we give them for reference:
\[
\rho_{1,1}^H(h) := \frac{1}{2(4 - 2^{2H})} \left( -|h - 2|^{2H} + 4|h - 1|^{2H} - 6|h|^{2H} + 4|h + 1|^{2H} - |h + 2|^{2H} \right),
\]
\[
\rho_{2,2}^H(h) := \frac{1}{2(4 \cdot 2^{2H} - 4^{2H})} \left( -|h - 4|^{2H} + 4|h - 2|^{2H} - 6|h|^{2H} + 4|h + 2|^{2H} - |h + 4|^{2H} \right),
\]
\[
\rho_{1,2}^H(h) := \frac{-|h - 2|^{2H} + 2|h - 1|^{2H} + |h|^{2H} - 4|h + 1|^{2H} + |h + 2|^{2H} + 2|h + 3|^{2H} - |h + 4|^{2H}}{2\sqrt{1 - 2^{2H}} \sqrt{4 \cdot 2^{2H} - 4^{2H}}}.
\]
Brute force calculations will yield
\[
\lambda_{2,n}^{11} = 2\Delta_n^{4H} \sum_{i=2}^{n} \sum_{j=2}^{n} \rho_{1,1}^H(i - j)^2,
\]
\[
\lambda_{2,n}^{22} = 2\Delta_n^{4H} \sum_{i=4}^{n} \sum_{j=4}^{n} \rho_{2,2}^H(i - j)^2,
\]
\[
\lambda_{2,n}^{12} = \lambda_{2,n}^{21} = 2\Delta_n^{4H} \sum_{i=2}^{n} \sum_{j=4}^{n} \rho_{1,2}^H(i - j)^2.
\]
In the feasible implementation in Remark 4 we will actually need the unnormalized variants of \(\lambda_{2,n}^{ij}\) which are
\[
\text{Var} \left( V (B^H; p, 1)_1^n \right) = \Delta_n \lambda_{2,n}^{11} \cdot (4 - 2^{2H})^2,
\]
\[
\text{Var} \left( V (B^H; p, 2)_1^n \right) = \Delta_n \lambda_{2,n}^{22} \cdot (4 \cdot 2^{2H} - 4^{2H})^2,
\]
\[
\text{Cov} \left( V (B^H; p, 1)_1^n, V (B^H; p, 2)_1^n \right) = \Delta_n \lambda_{2,n}^{12} \cdot (4 - 2^{2H})(4 \cdot 2^{2H} - 4^{2H}).
\]
To arrive at expressions for $\lambda_{ij}^p$ we can either take limits in the above or use the theory in Nourdin et al. (2011) (see e.g. Barndorff-Nielsen et al., 2013b) to get

$$
\lambda_{11}^2 = 2 + 4 \sum_{h=1}^{\infty} \rho_{1,1}^H(h)^2,
$$

$$
\lambda_{22}^2 = 2 + 4 \sum_{h=1}^{\infty} \rho_{1,1}^H(h)^2 + 6 \rho_{1,1}^H(h) + 4 \rho_{1,1}^H(h+1) + \rho_{1,1}^H(h+2)^2,
$$

$$
\lambda_{12}^2 = 2 = \lambda_{21}^2
$$

Finally, we need to calculate $\mu(p,1)^n_t$ and $\mu(p,2)^n_t$. Straightforward calculations yield

$$
\mu(2,1)^n_t = (n-1)\Delta^2_n(4-2^{2H}),
$$

$$
\mu(2,2)^n_t = (n-3)\Delta^2_n(4 \cdot 2^{2H} - 4^{2H}),
$$

and by standard properties of the Gaussian distribution we thus have

$$
\mu(p,1)^n_t = (n-1)\Delta^H_n(4-2^{2H})^{p/2} C_p,
$$

$$
\mu(p,2)^n_t = (n-3)\Delta^H_n(4 \cdot 2^{2H} - 4^{2H})^{p/2} C_p,
$$

where

$$
C_p = 2^{p/2} \frac{\Gamma\left(\frac{p+1}{2}\right)}{\sqrt{\pi}}
$$

and $\Gamma(\cdot)$ is the gamma function.

## C Simulation design

In our Monte Carlo study presented above we have simulated $n+1 \in \mathbb{N}$ equidistant observations $X_0, X_{1/n}, X_{2/n}, \ldots, X_1$ of the BSS process

$$
X_t = \int_{-\infty}^{t} g(t-s)\sigma_s dW_s
$$

on the time interval $[0,1]$. Recall that we take $g(x) = x^\alpha e^{-\lambda x}$ where $\lambda > 0$ and $\alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right)$. Simulation of $X$ is not straightforward as the process is typically neither Gaussian nor Markovian, which rules out both exact and recursive simulation schemes. However, as shown in Bennedsen et al. (2017b), the process $X$ can be simulated efficiently and accurately using the so-called hybrid scheme, which is based on approximating $X_t$ by a Riemann sum plus Wiener integrals of a power function that mimicks the steep behavior of $g$ at zero. In particular, the hybrid scheme improves significantly simulation accuracy compared to any approximation using merely Riemann sums.
To simulate the observations $X_0, X_{1/n}, X_{2/n}, \ldots, X_1$, the hybrid scheme approximates $X_{i/n}, i = 0, 1, \ldots, n$, by

$$X_{i/n}^n := \tilde{X}_{i/n}^n + \hat{X}_{i/n}^n,$$

where

$$\tilde{X}_t^n := \sum_{k=1}^{\kappa} L_g \left( \frac{k}{n} \right) \sigma_{t-k/n} \int_{t-k/n}^{t-k/n + 1/n} (t-s)^{\alpha} dW_s,$$

$$\hat{X}_t^n := \sum_{k=\kappa+1}^{N_n} g \left( \frac{b_k^*}{n} \right) \sigma_{t-k/n} (W_{t-k/n+1/n} - W_{t-k/n}).$$

The number $N_n := \lfloor n^{1+\delta} \rfloor$, for some $\delta > 0$, determines the truncation "towards minus infinity", while $\kappa \geq 0$ denotes the number of terms that are simulated directly via Wiener integrals, cf. (26). As shown in Bennedsen et al. (2017b), $\kappa = 1$ suffices when $\alpha < 0$, but we need $\kappa = 3$ when $\alpha$ is close to $\frac{1}{2}$. In the simulations, we therefore choose $\kappa = 1$ when $\alpha < 0$ and $\kappa = 3$ when $\alpha > 0$. We also let $\delta = 0.5$. The numbers

$$b_k^* = \left( \frac{k^{\alpha+1} - (k-1)^{\alpha+1}}{\alpha + 1} \right)^{1/\alpha},$$

$k = 1, \ldots, N_n$, are the optimal points\(^\text{7}\) to evaluate $g$ at; see Proposition 2.2 of Bennedsen et al. (2017b). We refer to Bennedsen et al. (2017b) for implementation of the algorithm used to simulate (26) and (27) exactly while simultaneously simulating $\sigma_{i/n-k/n}, i, k = 0, 1, \ldots$, which may be correlated with $W$.

For the stochastic volatility process $\sigma = (\sigma_t)_{t \in \mathbb{R}}$, we consider three different specifications: (i) constant volatility, labeled NoSV; (ii) one-factor stochastic volatility, labeled SV1F; and (iii) two-factor stochastic volatility, labeled SV2F. For the NoSV model we take for $t \in \mathbb{R}$,

$$\sigma_t = 1,$$

while we in the SV1F model take, following Barndorff-Nielsen et al. (2008),

$$\sigma_t = \exp(\beta_0 + \beta_1 \tau_t),$$

$$d\tau_t = \xi \tau_t dt + dB_t,$$

$$d[W,B]_t = \rho dt,$$

where $B$ is a standard Brownian motion and $\beta_1 = 0.125$, $\xi = -0.025$, $\beta_0 = \frac{\beta^2}{2\xi} = -0.3125$ and $\rho = -0.3$. Lastly, for the SV2F model we take, following Huang and Tauchen (2005) and Barndorff-

\(^7\) In the sense of asymptotic mean-square error.
Nielsen et al. (2008),
\[ \sigma_t = s - \exp(\beta_0 + \beta_1 \tau_{1t} + \beta_2 \tau_{2t}), \]
\[ d\tau_{1t} = \xi_1 \tau_{1t} dt + dB^1_t, \]
\[ d\tau_{2t} = \xi_2 \tau_{2t} dt + (1 + \phi \tau_{2t}) dB^2_t, \]
\[ d[W, B^1]_t = \rho_1 dt, \]
\[ d[W, B^2]_t = \rho_2 dt, \]
where \( B^1, B^2 \) are standard Brownian motions and the function \( s - \exp \) is given by
\[ s - \exp(x) = \begin{cases} \exp(x), & x \leq \log(1.5), \\ \frac{3}{2} \sqrt{1 - \log(1.5)} + \frac{x^2}{\log(1.5)}, & x > \log(1.5) \end{cases} \]
and the parameters are set to \((\beta_0, \beta_1, \beta_2)^T = (-1.20, 0.040, 1.50)^T, (\xi_1, \xi_2)^T = (-0.00137, -1.386)^T,\)
\( \phi = 0.250 \) and \( \rho_1 = \rho_2 = -0.30. \)

We note that in the NoSV case the process \( X \) is Gaussian and can thus be simulated exactly using a Cholesky decomposition of its variance-covariance matrix, which is what we do in our simulations. The stochastic processes of SV1F and SV2F can be simulated exactly using methods in Glasserman (2003), see also the Simulation Appendix to Barndorff-Nielsen et al. (2008).

D Proofs

Proof of Proposition 2.1. The proofs of the statements follow the ones referenced in Corcuera et al. (2013) almost verbatim, which in turn relies on results from Barndorff-Nielsen et al. (2013b). We note that in the case of \( \alpha = 0 \) the increments of the \( BSS \) process are asymptotically uncorrelated. Indeed, we have by Assumption 2'(i) (cf. equation (2.6) in Corcuera et al., 2013)
\[ r_n(j) := \text{corr}(G_{(j+1)\Delta_n} - 2G_j \Delta_n + G_{(j-1)\Delta_n}, G_{\Delta_n} - 2G_0 + G_{-\Delta_n}) \xrightarrow{n \to \infty} \rho_2(j), \quad j \geq 0, \]
where \( \rho_2(j) \) is the correlation function of the second order increments of a Brownian motion. Therefore,
\[ \rho_2(j) = 0, \quad j \geq 2. \]
This uncorrelatedness simplifies matters, for instance when we need to calculate \( \Lambda_p \) (see pages 85-86 in Barndorff-Nielsen et al., 2013b). The proof of Proposition 2.1 has two main parts, see the similar proofs in Barndorff-Nielsen et al. (2011, 2013b). First, we need to show the existence of a sequence \( r(j) \), such that
\[ |r_n(j)| \leq Cr(j), \quad \sum_{j=1}^{\infty} r(j)^2 < \infty, \quad (28) \]
where $C > 0$, see page 75 in Barndorff-Nielsen et al. (2013b) for the case of $\alpha \neq 0$. Given that
(e.g. Barndorff-Nielsen et al., 2013b)
\[
r_n(j) = \frac{-R \left( \frac{j+2}{n} \right) + 4R \left( \frac{j+1}{n} \right) - 6R \left( \frac{j}{n} \right) + 4R \left( \frac{j-1}{n} \right) - R \left( \frac{j-2}{n} \right)}{4R \left( \frac{1}{n} \right) - R \left( \frac{3}{n} \right)},
\]
it is not difficult to show, using Assumptions 2'(i)-(iii) and the approach from the proof of Lemma 1 in Barndorff-Nielsen et al. (2009), that the sequence
\[
r(j) = (j - 1)^{-\beta}, \quad j \geq 2,
\]
will suffice as the sequence in (28), where $\beta$ is the parameter from Assumption 2'(ii). We now turn to the second part of the proof. Define
\[
\pi^n(A) := \frac{\int_A (g(x + 2\Delta_n) - 2g(x + \Delta_n) + g(x))^2 dx}{\int_0^\infty (g(x + 2\Delta_n) - 2g(x + \Delta_n) + g(x))^2 dx}, \quad A \in \mathcal{B}(\mathbb{R}).
\]
The only remaining thing to show is that the limit theorems apply for stochastic $\sigma$, is that for all $\epsilon > 0$ we have $\pi^n((\epsilon, \infty)) \to 0$ as $n \to \infty$. Using Assumption 1’ (ii) and arguments as the ones in Barndorff-Nielsen et al. (2013b) page 74, we easily deduce this property. This concludes the proof. ■

Proof of Lemma 3.1. (i) Given (1), (15), and (16) the result follows. In particular, we have that
\[
\mathbb{E}^* \left( \tilde{V}^* (X, B^H; p, p', v)^n \right) = \frac{|\tilde{\sigma}(p', v)|_t^n}{|\tilde{\pi}(p, v)|_t^n} \mathbb{E}^* \left( \tilde{V} (B^H; p, v)^n \right)
\]
\[
= |\tilde{\sigma}(p', v)|_t^n \mathbb{E}^* \left( \tilde{V} (B^H; p, v)^n \right).
\]
(ii) Given (1), (15), and (16), we can write
\[
Var^* \left( \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 1)^n \right)
\]
\[
= \Delta_n^{-1} \left( \frac{|\tilde{\sigma}(p', 1)|_t^n}{|\tilde{\pi}(p, 1)|_t^n} \right)^2 Var^* \left( \tilde{V} (B^H; p, 1)^n \right).
\]
(iii) Follows similarly as the proof of Lemma 3.1 part (ii). (iv) Given (16), we can write
\[
Cov^* \left( \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 1)^n_t, \Delta_n^{-1/2} \tilde{V}^* (X, B^H; p, p', 2)^n_t \right)
\]
\[
= \Delta_n^{-1} \left( \frac{|\tilde{\sigma}(p', 1)|_t^n}{|\tilde{\pi}(p, 1)|_t^n} \right) \left( \frac{|\tilde{\sigma}(p', 2)|_t^n}{|\tilde{\pi}(p, 2)|_t^n} \right) Cov^* \left( \tilde{V} (B^H; p, 1)^n_t, \tilde{V} (B^H; p, 2)^n_t \right).
\]
(iv) This result follows immediately given parts (ii), (iii), and (iv) of Lemma 3.1, the assumed condition $|\tilde{\sigma}(p', v)|_t^n |2p u_c p| \int_0^1 |\sigma_s|^2 ds$, and the definition of $\tilde{\Lambda}^{(n)}_{p,t}$. ■

Proof of Theorem 3.1. Note that we can write
\[
\tilde{S}^*_n = \tilde{A}^*_n S^*_n,
\]
34
where $S_n^*$ is given by

$$S_n^* = \left( \Sigma^* (X, B^H; p, p')^n \right)^{-1/2} (\Delta_n)^{-1/2} \left( \bar{V}^* (X, B^H; p, p', 1)^n_t - \mathbb{E}^* (\bar{V}^* (X, B^H; p, p', 1)^n_{t^h}) \right),$$

and

$$\hat{A}_n^* = \left( \hat{\Sigma}^* (X, B^H; p, p')^n_t \right)^{-1/2} \left( \Sigma^* (X, B^H; p, p')^n_t \right)^{1/2}.$$

Hence, to obtain the desired result of $\hat{S}_n^*$, we may proceed in two steps:

**Step 1.** Show that $S_n^* \overset{d}{\to} N(0, I_2)$.

**Step 2.** Show that $\hat{A}_n^* \overset{P}{\to} I_2$.

For Step 1, note that we can write $S_n^*$ as follows

$$S_n^* = \left( \Sigma^* (X, B^H; p, p')^n_t \right)^{-1/2} D \cdot T_n$$

where

$$D = \begin{pmatrix} \frac{\|\hat{\sigma}(p', 1)^n_t\|}{\mathbb{P}(p, 1)^n_t} & 0 \\ 0 & \frac{\|\hat{\sigma}(p', 2)^n_t\|}{\mathbb{P}(p, 2)^n_t} \end{pmatrix},$$

and

$$T_n = (\Delta_n)^{-1/2} \left( \bar{V} (B^H; p, 1)^n_t - \mathbb{E} (\bar{V} (B^H; p, 1)^n_{t^h}) \right) \left( \bar{V} (B^H; p, 2)^n_t - \mathbb{E} (\bar{V} (B^H; p, 2)^n_{t^h}) \right).$$

Under our assumptions, we have that (Breuer and Major, 1983, Theorem 1)

$$T_n \overset{d}{\to} N(0, \Lambda_p).$$

Thus, results in Step 1 will follow if we can show that

$$\left( \Sigma^* (X, B^H; p, p')^n_t \right)^{-1/2} D = \left( D^{-1} \left( \Sigma^* (X, B^H; p, p')^n_t \right)^{1/2} \right)^{-1} \overset{P}{\to} \Lambda_p^{-1/2}.$$

To this end, note that we have

$$D^{-1} \left( \Sigma^* (X, B^H; p, p')^n_t \right)^{1/2} = \begin{pmatrix} \sqrt{\lambda_{11}^n} & 0 \\ \lambda_{12}^n & \sqrt{\lambda_{22}^n} \end{pmatrix} \equiv \Theta_{p,n},$$

where we use

$$D^{-1} = \begin{pmatrix} \frac{\mathbb{P}(p, 1)^n_t}{\|\hat{\sigma}(p', 1)^n_t\|} & 0 \\ 0 & \frac{\mathbb{P}(p, 2)^n_t}{\|\hat{\sigma}(p', 2)^n_t\|} \end{pmatrix},$$
and
\[ \left( \Sigma^* (X, B^H; p, p')_t^n \right)^{1/2} = \left( \sqrt{(\pi(p, 1)p)^{-2} \lambda_{p,n}^{11} \hat{\sigma}(p', 1)_t^n} \right) \left( \sqrt{(\pi(p, 2)p)^{-2} \lambda_{p,n}^{12} \hat{\sigma}(p', 2)_t^n} \right)^{1/2} \]

The result follows since
\[ \Theta_{p,n} \Theta_{p,n}^T = \Lambda_{p,n} = \left( \frac{\lambda_{p,n}^{11}}{\lambda_{p,n}^{12}} \frac{\lambda_{p,n}^{12}}{\lambda_{p,n}^{22}} \right) \to \Lambda_p. \]

For Step 2, it suffices to show that
\[ \left( \hat{\Sigma}^* (X, B^H; p, p')_t^n \right)^{-1} \left( \Sigma^* (X, B^H; p, p')_t^n \right) = \left( \left( \hat{\Sigma}^* (X, B^H; p, p')_t^n \right)^{-1} \left( \hat{\Sigma}^* (X, B^H; p, p')_t^n \right)^{-1} \right) \to I_2. \]

We here utilize the fact that convergence in \( L_1 \) implies convergence in probability and that all elements of the sum in \( \hat{\Sigma}_{i,j}^* \) are non-negative (where \( \hat{\Sigma}_{i,j} \) is the \((i, j)\)-th element of the matrix \( \hat{\Sigma}^* = \left( \hat{\Sigma}_{i,j}^* \right)_{1 \leq i, j \leq 2} \)). In particular, given (20) and (19), for \( 1 \leq i, j \leq 2 \), we have
\[ \mathbb{E}^* \left( \hat{\Sigma}_{i,j}^* \right) = \mathbb{E}^* \left( \hat{\Sigma}_{i,j} \right) = \Sigma_{i,j}. \]

Thus, we deduce that
\[ \hat{\Sigma}^* (X, B^H; p, p')_t^n - \Sigma^* (X, B^H; p, p')_t^n \to 0. \]

This concludes the proof of Step 2 and also that of part (a) of Theorem 3.1.

Next, we show part (ii) of Theorem 3.1. In the following, let \( \Phi(x) \) be the multivariate distribution function of \( N(0, I_2) \) on \( \mathbb{R}^2 \). By the triangle inequality, we have
\[ \sup_{x \in \mathbb{R}^2} \left| P^* \left( \hat{S}_n^* \leq x \right) - P \left( \hat{S}_n \leq x \right) \right| \leq \sup_{x \in \mathbb{R}^2} \left| P^* \left( \hat{S}_n^* \leq x \right) - \Phi(x) \right| + \sup_{x \in \mathbb{R}^2} \left| P \left( \hat{S}_n \leq x \right) - \Phi(x) \right|. \]

Hence, given part (i) of Theorem 3.1, the fact that under our assume conditions \( \hat{S}_n \) is continuous, the desired result follows by using a multivariate version of Polya’s Theorem, see, e.g., Bhattacharyya and Rao (1986).

**Proof of Theorem 3.2.** (i) Given Theorem 3.1, the result follows from an application of the delta method. (ii) Follows similarly as the proof of Theorem 3.1 part (ii). In particular, by (11), for any \( \alpha \in \left( -\frac{1}{2}, 0 \right) \cup \left( 0, \frac{1}{2} \right) \), and \( p \geq 2 \), we have
\[ T_{\alpha,n} \overset{d}{\to} N(0, 1). \]

Hence, given Theorem 3.2 part (i), Polya’s theorem, and the triangle inequality, we have
\[ \sup_{x \in \mathbb{R}} \left| P^* \left( T_{\alpha,n}^* \leq x \right) - P \left( T_{\alpha,n} \leq x \right) \right| \to 0. \]