



A CONTACT INVARIANT IN SUTURED MONOPOLE HOMOLOGY

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Abstract

We define an invariant of contact 3-manifolds with convex boundary using Kronheimer and Mrowka's sutured monopole Floer homology theory (*SHM*). Our invariant can be viewed as a generalization of Kronheimer and Mrowka's contact invariant for closed contact 3-manifolds and as the monopole Floer analogue of Honda, Kazez, and Matić's contact invariant in sutured Heegaard Floer homology (*SFH*). In the process of defining our invariant, we construct maps on *SHM* associated to contact handle attachments, analogous to those defined by Honda, Kazez, and Matić in *SFH*. We use these maps to establish a bypass exact triangle in *SHM* analogous to Honda's in *SFH*. This paper also provides the topological basis for the construction of similar gluing maps in sutured instanton Floer homology, which are used in Baldwin and Sivek [*Selecta Math. (N.S.)*, **22**(2) (2016), 939–978] to define a contact invariant in the instanton Floer setting.

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1. Introduction

Floer-theoretic invariants of contact structures—in particular, those defined by Kronheimer and Mrowka in [26] and by Ozsváth and Szabó in [41]—have led to a number of spectacular results in low-dimensional topology over the last decade or so. Kronheimer and Mrowka's invariant, defined using Taubes's work on the Seiberg–Witten equations for symplectic 4-manifolds, assigns to a closed contact 3-manifold (Y, ξ) a class $\psi(Y, \xi)$ in the monopole Floer homology $\widetilde{HM}_{\bullet}(-Y, \mathfrak{s}_{\xi})$,

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where \mathfrak{s}_{ξ} is the Spin^{*c*} structure associated to ξ . (This formulation of Kronheimer and Mrowka's invariant first appears in [25], actually.) Ozsváth and Szabó's invariant similarly takes the form of a class $c^+(Y, \xi)$ in the Heegaard Floer homology $HF^+(-Y, \mathfrak{s}_{\xi})$, but is defined using Giroux's correspondence between contact structures and open books.

Honda, Kazez, and Matić introduced an important generalization of Ozsváth and Szabó's construction in [20], using a *relative* version of Giroux's correspondence to define an invariant of *sutured contact manifolds*, which are triples of the form (M, Γ, ξ) where (M, ξ) is a contact 3-manifold with convex boundary and $\Gamma \subset \partial M$ is a multicurve dividing the characteristic foliation of ξ on ∂M . (Technically, the invariant in [20] generalizes the 'hat' version of Ozsváth and Szabó's invariant. Also, it is worth mentioning that the term *sutured contact manifold* is used slightly differently in [9].) Their invariant assigns to (M, Γ, ξ) a class $EH(M, \Gamma, \xi)$ in the sutured Heegaard Floer homology $SFH(-M, -\Gamma)$. The work in [20] and its sequel [19] has enhanced our understanding of Legendrian knots [43], knot Floer homology [12], functoriality in SFH [22], and bordered Heegaard Floer homology [53], and has revealed interesting categorical structure in contact topology [17]. This categorical structure has, in turn, had important applications to the categorification of quantum groups [49, 50].

In this paper, we define an invariant of sutured contact manifolds in Kronheimer and Mrowka's sutured monopole Floer homology (*SHM*), generalizing their invariant for closed contact manifolds in the same way that Honda, Kazez, and Matić's contact invariant generalizes that of Ozsváth and Szabó on the Heegaard Floer side. In other words,

our invariant : ψ :: EH : c^+ .

Although our contact invariant can be thought of as the monopole Floer analogue of Honda, Kazez, and Matić's *EH* invariant, our construction is quite different from theirs (not surprising, considering the different constructions of ψ and c^+). One advantage of our construction is that it does not rely on the full strength of the relative Giroux correspondence, using only the existence of partial open books. Moreover, we show that our contact invariant is 'natural' in the sense that it is preserved by the canonical isomorphisms relating the different sutured monopole homology groups associated to a given sutured contact manifold, something which has not been completely established on the Heegaard Floer side.

As a byproduct of our construction, we define 'gluing' maps in *SHM* associated to contact handle attachments, analogous to those in *SFH* defined by Honda *et al.* [19]. As we shall see, Kronheimer and Mrowka's approach to sutured Floer theory via the *closure* operation allows for a conceptually simpler construction of these maps than in *SFH*. We use these gluing maps to establish a monopole

Floer analogue of Honda's bypass exact triangle in *SFH*—the centerpiece of his *contact category* [17]. Moreover, our approach shows that these bypass triangles are instances of the usual surgery exact triangle in Floer homology, suggesting that Honda's contact category fits naturally into a larger category of closed manifolds.

Our work on defining gluing maps in *SHM* also provides the topological foundation for a similar gluing map construction in Kronheimer and Mrowka's sutured instanton Floer homology. We use this construction in [2] to define the first invariant of contact manifolds in the instanton Floer setting.

Beyond providing new insights into developments that have sprung from Honda, Kazez, and Matić's work, intrinsic advantages of the monopole Floer perspective have enabled us to prove results with no counterparts on the Heegaard Floer side. This point is illustrated in [4], where we use the contact invariant defined in this paper to construct new invariants of Legendrian and transverse knots in monopole knot homology. The functoriality of Kronheimer and Mrowka's invariant ψ under exact symplectic cobordism leads to a proof that our Legendrian invariant is functorial with respect to Lagrangian concordance (see [42] for a similar result), something which is not independently known to be true of the analogous 'LOSS' invariant in knot Floer homology [37] (see Section 1.3).

Below, we outline the constructions of our contact invariant and our gluing maps, elaborating on several points in the discussion above. We discuss future work at the end.

1.1. A contact invariant in *SHM*. Suppose (M, Γ) is a balanced sutured manifold. Consider the manifold obtained by gluing a thickened surface $F \times I$ to M by a map which identifies $\partial F \times I$ with a tubular neighborhood of $\Gamma \subset \partial M$. Under mild assumptions, this manifold has two diffeomorphic boundary components. Gluing these together by some diffeomorphism, one obtains a closed 3-manifold Y with a distinguished surface $R \subset Y$. Kronheimer and Mrowka call a pair (Y, R) obtained in this way a *closure* of (M, Γ) . Its *genus* refers to the genus of R.

Suppose now that (Y, R) is a closure of (M, Γ) with genus at least two and η is an embedded, nonseparating 1-cycle in R. Let \mathcal{R} be the Novikov ring over \mathbb{Z} . As defined in [28], the *sutured monopole homology* of (M, Γ) is the \mathcal{R} -module given by the portion of the 'twisted' monopole Floer homology of Y in the 'bottommost' Spin^c structures relative to R,

$$\underline{SHM}(M,\Gamma) := \widecheck{HM}_{\bullet}(Y|R;\Gamma_{\eta}) := \bigoplus_{(c_{1}(\mathfrak{s}),[R])=2-2g(R)} \widecheck{HM}_{\bullet}(Y,\mathfrak{s};\Gamma_{\eta}).$$
(1)

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(In [1, 28] the construction used top-most Spin^{*c*} structures instead, but this makes no difference due to the conjugation symmetry of HM_{\bullet} . Also, Γ_{η} refers to a local system on the Seiberg–Witten configuration space $\mathcal{B}(Y, \mathfrak{s})$ with fiber \mathcal{R} specified by η .) Kronheimer and Mrowka showed that $\underline{SHM}(M, \Gamma)$ is well defined up to isomorphism. Moreover, the combined results of Kronheimer and Mrowka [28, Lemma 4.9], Taubes [44–48], Colin, Ghiggini, and Honda [6–8], and Lekili [35] show that

$$\underline{SHM}(M,\Gamma) \cong SFH(M,\Gamma) \otimes \mathcal{R}.$$
(2)

(See also Kutluhan, Lee, and Taubes [30–34].)

In [1], we introduced a refinement of this construction which assigns to (M, Γ) an \mathcal{R} -module that is well defined up to *canonical* isomorphism, modulo multiplication by units in \mathcal{R} . Our refinement begins with a modification of Kronheimer and Mrowka's notion of closure. For us, a (marked) closure is a tuple \mathscr{D} which records the data (Y, R, η) , as well as things like an explicit smooth structure on Y and smooth embeddings of M and R into Y. The sutured monopole homology $\underline{SHM}(\mathscr{D})$ of a closure \mathscr{D} of (M, Γ) is then defined in terms of (Y, R, η) as in (1). For any two closures $\mathscr{D}, \mathscr{D}'$ of (M, Γ) , we constructed an isomorphism

$$\underline{\Psi}_{\mathscr{D},\mathscr{D}'}:\underline{SHM}(\mathscr{D})\to\underline{SHM}(\mathscr{D}'),$$

which is well defined up to multiplication by a unit in $\ensuremath{\mathcal{R}}$ and satisfies the transitivity

$$\underline{\Psi}_{\mathscr{D},\mathscr{D}''} \doteq \underline{\Psi}_{\mathscr{D}',\mathscr{D}''} \circ \underline{\Psi}_{\mathscr{D},\mathscr{D}'}.$$

(Here, ' \doteq ' means 'equal up to multiplication by a unit'.) We view these maps as canonical isomorphisms relating the \mathcal{R} -modules assigned to the different closures of (M, Γ) . These maps and modules are organized into what we call a *projectively transitive system*, denoted by **SHM** (M, Γ) . It is this system we are referring to in this paper when we talk about the *sutured monopole homology* of (M, Γ) .

Now, suppose (M, Γ, ξ) is a sutured contact manifold. To define the contact invariant, we introduce the notion of a *contact closure* of (M, Γ, ξ) , which is a closure \mathscr{D} of (M, Γ) together with a contact structure $\overline{\xi}$ on Y extending ξ and satisfying certain conditions. One of these conditions is that the surface R is convex with negative region an annulus, which guarantees that

$$\langle c_1(\mathfrak{s}_{\bar{\xi}}), [R] \rangle = 2 - 2g(R)$$

by basic convex surface theory. But this implies that $\widetilde{HM}_{\bullet}(-Y, \mathfrak{s}_{\bar{\xi}}; \Gamma_{-\eta})$ is a direct summand of $\underline{SHM}(-\mathcal{D})$, where $-\mathcal{D}$ is the closure of $(-M, -\Gamma)$ induced by reversing the orientations on *Y*, *R*, and η . It therefore makes sense to define

$$\psi(\mathscr{D},\bar{\xi}) := \psi(Y,\bar{\xi}) \in \widecheck{HM}_{\bullet}(-Y,\mathfrak{s}_{\bar{\xi}};\Gamma_{-\eta}) \subset \underline{SHM}(-\mathscr{D}),$$

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Our main result is, roughly speaking, that the classes $\psi(\mathcal{D}, \overline{\xi})$ define an invariant of (M, Γ, ξ) up to canonical isomorphism. For the sake of exposition, we have broken this result into the following two theorems (see Theorems 3.14 and 3.15 for more precise statements).

THEOREM 1.1. If $(\mathcal{D}, \overline{\xi})$ and $(\mathcal{D}', \overline{\xi}')$ are contact closures of (M, Γ, ξ) , then

$$\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}(\psi(\mathscr{D},\bar{\xi})) \doteq \psi(\mathscr{D}',\bar{\xi}')$$

for $g(\mathcal{D}) = g(\mathcal{D}')$.

THEOREM 1.2. If $(\mathcal{D}, \overline{\xi})$ and $(\mathcal{D}', \overline{\xi}')$ are contact closures of (M, Γ, ξ) , then

 $\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}(\psi(\mathscr{D},\bar{\xi}))\doteq\psi(\mathscr{D}',\bar{\xi}')$

whenever $g(\mathcal{D})$ and $g(\mathcal{D}')$ are sufficiently large.

In the lexicon of projectively transitive systems, Theorem 1.1 is equivalent to the statement that, for each g, the collection of classes $\{\psi(\mathcal{D}, \overline{\xi}) \mid g(\mathcal{D}) = g\}$ defines an *element*

$$\psi^{g}(M, \Gamma, \xi) \in \underline{\mathbf{SHM}}(-M, -\Gamma).$$

Meanwhile, Theorem 1.2 is equivalent to the statement that these elements stabilize in the sense that $\psi^g(M, \Gamma, \xi) = \psi^h(M, \Gamma, \xi)$ for *g*, *h* sufficiently large. Our contact invariant is defined to be this stable element, which we denote by

$$\psi(M, \Gamma, \xi) \in \underline{\mathbf{SHM}}(-M, -\Gamma).$$

The key facts in the proof of Theorem 1.1 are that (1) contact closures of the same genus are related by Legendrian surgery and (2) $\Psi_{-\mathscr{D},-\mathscr{D}'}$ is the map induced by the associated Stein cobordism. (This is a considerable simplification of the real story.) Theorem 1.1 therefore follows from the functoriality of Kronheimer and Mrowka's contact invariant with respect to exact symplectic cobordism (see Theorem 2.21). For closures of different genera, $\Psi_{-\mathscr{D},-\mathscr{D}'}$ is defined in terms of a *splicing* cobordism which does not admit, in any obvious way, the structure of an exact symplectic cobordism. So, the previous argument cannot be used to prove Theorem 1.2. Our proof relies instead on our gluing map construction together with what we call the 'existence' part of the relative Giroux correspondence. We outline this proof in detail in the next subsection after describing these gluing maps.

Our contact invariant shares several features with Honda, Kazez, and Matić's invariant. For example, it is preserved by contact isotopy and *flexibility*, and vanishes for overtwisted contact structures (see Corollaries 3.18 and 3.19 and Theorem 3.22 for more precise statements).

We also prove the following theorem relating our invariant to Kronheimer and Mrowka's contact invariant for closed manifolds (stated more precisely in Proposition 3.23). Below, (Y, ξ) is a closed contact 3-manifold and $(Y(1), \xi|_{Y(1)})$ is the sutured contact manifold obtained from it by removing a Darboux ball.

THEOREM 1.3. There exists a map

$$\underline{\mathbf{SHM}}(-Y(1)) \to \widetilde{HM}_{\bullet}(-Y) \otimes \mathcal{R}$$

which sends $\psi(Y(1), \xi|_{Y(1)})$ to $\psi(Y, \xi) \otimes 1$.

As explained in Remark 3.25, this map can be thought of as a monopole Floer analogue of the natural map in Heegaard Floer homology relating the 'hat' and 'plus' versions of Ozsváth and Szabó's contact invariant.

The following is an immediate corollary (see Corollary 3.24).

COROLLARY 1.4. If (Y, ξ) is strongly symplectically fillable, then $\psi(Y(1), \xi|_{Y(1)}) \neq 0$.

Before moving on, it is worth mentioning that Kronheimer and Mrowka also define a version of *SHM* without local coefficients. However, local coefficients are necessary in this paper, both for naturality purposes (in defining the canonical isomorphisms for closures of different genera) and because the contact class $\psi(\mathcal{D}, \bar{\xi})$ always vanishes without them (see Remark 3.28).

1.2. A gluing map in *SHM*. Below, we describe a gluing map on *SHM* for contact handles. Our main results in this direction are the following (combining Propositions 4.2, 4.3, 4.5, 4.6, and Corollary 4.15).

THEOREM 1.5. Suppose (M', Γ', ξ') is obtained from (M, Γ, ξ) by attaching a contact *i*-handle, for some $i \in \{0, 1, 2, 3\}$. Then there exists a map

 $\mathscr{H}_i: \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M', -\Gamma')$

which sends $\psi^{g}(M, \Gamma, \xi)$ to $\psi^{g}(M', \Gamma', \xi')$ for g sufficiently large.

COROLLARY 1.6. The map \mathcal{H}_i sends $\psi(M, \Gamma, \xi)$ to $\psi(M', \Gamma', \xi')$.

It is worth pointing out that these maps depend *only* on the smooth data involved in the handle attachments; in particular, they do not depend on the contact structures ξ or ξ' .

These maps are defined in terms of natural cobordisms between closures: for i = 0, 1, we show that a contact closure of (M', Γ', ξ') can also be viewed naturally as a contact closure of (M, Γ, ξ) , and we define \mathcal{H}_i to be the isomorphism induced by the identity map on monopole Floer homology. For i = 2, the curve of attachment in ∂M gives rise to a Legendrian knot in any contact closure of (M, Γ, ξ) . We prove that the result of contact (+1)-surgery along such a knot can be viewed naturally as a contact closure of (M', Γ', ξ') , and we define \mathcal{H}_2 in terms of the map on Floer homology induced by the corresponding 2handle cobordism. Finally, for i = 3, we prove that one obtains a contact closure of (M, Γ, ξ) by taking a connected sum of a contact closure of (M', Γ', ξ') with the tight $S^1 \times S^2$, and we define \mathcal{H}_3 in terms of the map on Floer homology induced by the corresponding 1-handle cobordism.

Theorem 1.5 is reminiscent of the main result of [19]. Suppose (M, Γ) is a sutured submanifold of (M', Γ') and ξ is a contact structure on $M' \setminus \operatorname{int}(M)$ with dividing set $\Gamma \cup \Gamma'$. Suppose further that ξ_M is a contact structure on M which agrees with ξ near ∂M . In [19], Honda, Kazez, and Matić construct a map

$$\Phi_{\xi}$$
: SFH($-M, -\Gamma$) \rightarrow SFH($-M', -\Gamma'$),

depending only on ξ , which sends $EH(M, \Gamma, \xi_M)$ to $EH(M', \Gamma', \xi_M \cup \xi)$. (Modulo incorporating the naturality results of [23].) We can use Theorem 1.5 to define an analogous map in *SHM*, starting from the observation that $(M' \setminus int(M), \Gamma \cup \Gamma', \xi)$ can be obtained from a vertically invariant contact structure on $\partial M \times I$ by attaching contact handles. Given such a contact handle decomposition *H*, we define

$$\Phi_{\xi,H}: \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M', -\Gamma')$$
(3)

to be the corresponding composition of contact handle attachment maps. Corollary 1.6 implies that this map sends contact invariant to contact invariant. We conjecture the following.

CONJECTURE 1.7. The map $\Phi_{\xi,H}$ is independent of the handle decomposition H.

We next outline the proof of Theorem 1.2, as promised. As mentioned above, our proof relies upon the 'existence' part of the relative Giroux correspondence, which states that every sutured contact manifold admits a compatible partial open book decomposition. (The full statement of the relative Giroux correspondence comprises this 'existence' part, whose proof is well established, together with the 'uniqueness' part, which states that any two such partial open book decompositions are related by positive stabilization. Full details of the 'uniqueness' part have not yet appeared.) This implies, in particular, that for every (M, Γ, ξ) , there is a compact surface *S* with nonempty boundary such that (M, Γ, ξ) can be obtained from the tight sutured contact manifold

$$H(S) = (S \times [-1, 1], \partial S \times \{0\}, \xi_S)$$

by attaching contact 2-handles. The corresponding composition of contact 2-handle maps,

$$\mathscr{H} : \underline{\mathbf{SHM}}(-H(S)) \to \underline{\mathbf{SHM}}(-M, -\Gamma),$$

therefore sends $\psi^g(H(S))$ to $\psi^g(M, \Gamma, \xi)$ for g sufficiently large. Now, suppose that

 $(\mathscr{D}_{S}, \overline{\xi}_{S}), (\mathscr{D}'_{S}, \overline{\xi}'_{S}) \text{ and } (\mathscr{D}, \overline{\xi}), (\mathscr{D}', \overline{\xi}')$

are contact closures of H(S) and (M, Γ, ξ) , respectively, with

 $g = g(\mathscr{D}_S) = g(\mathscr{D})$ and $h = g(\mathscr{D}'_S) = g(\mathscr{D}').$

The morphism \mathscr{H} encodes maps $\mathscr{H}_{-\mathscr{D}_S,-\mathscr{D}}$ and $\mathscr{H}_{-\mathscr{D}_S',-\mathscr{D}'}$ which make the diagram

$$\underbrace{\underline{SHM}(-\mathcal{D}_{S})}_{\underline{\Psi}_{-\mathcal{D}_{S},-\mathcal{D}'_{S}}} \underbrace{\underline{SHM}(-\mathcal{D})}_{\underbrace{\Psi}_{-\mathcal{D}_{S},-\mathcal{D}'_{S}}} \underbrace{\underline{SHM}(-\mathcal{D}'_{S})}_{\underbrace{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}} \underbrace{\underline{SHM}(-\mathcal{D}')}_{\underline{\mathcal{H}_{-\mathcal{D}'_{S},-\mathcal{D}'_{S}}}}$$

commute, up to multiplication by a unit. Theorem 1.5 can be translated as saying that

$$\mathscr{H}_{-\mathscr{D}_{S},-\mathscr{D}}(\psi(\mathscr{D}_{S},\bar{\xi}_{S})) \doteq \psi(\mathscr{D},\bar{\xi}) \quad \text{and} \quad \mathscr{H}_{-\mathscr{D}_{S}',-\mathscr{D}'}(\psi(\mathscr{D}_{S}',\bar{\xi}_{S}')) \doteq \psi(\mathscr{D}',\bar{\xi}')$$

for sufficiently large g and h. To prove Theorem 1.2, it therefore suffices to show that

$$\underline{\Psi}_{-\mathscr{D}_{S},-\mathscr{D}_{S}'}(\psi(\mathscr{D}_{S},\bar{\xi}_{S})) \doteq \psi(\mathscr{D}_{S}',\bar{\xi}_{S}').$$

But this is true since $\underline{\Psi}_{-\mathscr{D}_S,-\mathscr{D}'_S}$ is an isomorphism and $\psi(\mathscr{D}_S, \overline{\xi}_S)$ and $\psi(\mathscr{D}'_S, \overline{\xi}'_S)$ generate the modules <u>*SHM*</u>($-\mathscr{D}_S$) and <u>*SHM*</u>($-\mathscr{D}'_S$), which are both isomorphic to \mathcal{R} (see Subsection 3.4).

From this proof sketch, one also finds that the contact invariant $\psi(M, \Gamma, \xi) \in$ <u>SHM</u> $(-M, -\Gamma)$ is characterized by

$$\psi(M, \Gamma, \xi) = \mathscr{H}(1), \tag{4}$$



where $\mathbf{1} = \psi(H(S))$ is the *generator* of <u>SHM</u> $(-H(S)) \cong \mathcal{R}$. It is therefore natural to ask whether one can *define* a contact invariant in this way, forgetting about contact closures and Kronheimer and Mrowka's contact invariant entirely. In other words, a partial open book decomposition \mathfrak{ob} compatible with (M, Γ, ξ) determines a surface *S*, a map \mathcal{H} , and a class

$$\psi(\mathfrak{ob}) := \mathscr{H}(\mathbf{1}) \in \underline{\mathbf{SHM}}(-M, -\Gamma),$$

and the question is whether one can show, without appealing to the existing monopole Floer apparatus for closed contact manifolds, that $\psi(\mathfrak{ob}) = \psi(\mathfrak{ob}')$ for any two such partial open book decompositions. Although we do not show it in this paper, it turns out this can be done using the full relative Giroux correspondence (both the 'existence' and the 'uniqueness' parts). In fact, this idea is the basis for our construction in [2] of a contact invariant in sutured instanton Floer homology.

We end with a synopsis of our bypass exact triangle in *SHM*. A *bypass move* is a certain local modification of the dividing set of a sutured manifold (see Figure 23). Every such move can be achieved by attaching a *bypass* (roughly, half of a thickened overtwisted disk) to the manifold along an arc in its boundary. In turn, this bypass attachment can be achieved by attaching a contact 1-handle followed by a contact 2-handle in a manner determined by the arc (see Figure 24). So, the contact handle attachment maps of Theorem 1.5 allow us to define similar maps for bypass attachments.

In [17], Honda studies a certain 3-periodic sequence of bypass moves which he calls a *bypass triangle* (see Figure 25), and he shows that the *SFH* groups of sutured manifolds related by a bypass triangle fit into an exact triangle. This *bypass exact triangle* is the main feature of his *contact category*, which is envisioned as an algebraic approach to contact geometry. This contact category, though still a work in progress, has been studied for a variety of purposes, including as an approach to categorifying certain quantum groups [49–51].

In this paper, we establish a monopole Floer analogue of Honda's bypass exact triangle (see Theorem 5.2 for a more precise statement):

THEOREM 1.8. Suppose $\Gamma_1, \Gamma_2, \Gamma_3 \subset \partial M$ is a 3-periodic sequence of sutures related by the moves in a bypass triangle. Then there is an exact triangle



in which each arrow is the corresponding bypass attachment map. (We only prove this over $\mathcal{R} \otimes \mathbb{Z}/2\mathbb{Z}$.)

Recall that each bypass attachment map is the composition of a 1-handle map with a 2-handle map. But, on the level of closures, a 1-handle map is essentially the identity and a 2-handle map is the cobordism map associated to integral surgery on a knot. It is perhaps not surprising then that our bypass exact triangle is really just the usual surgery exact triangle in monopole Floer homology in disguise. This suggests that Honda's contact category may be a natural subcategory of some larger category of closed 3-manifolds defined without reference to contact structures (perhaps one with an interesting A_{∞} structure).

1.3. Related work. Below, we describe some related results and several goals for future work. In our article [3], we prove that our contact invariant 'agrees' with Honda, Kazez, and Matić's EH invariant. Forgetting about naturality, we can view $\psi(M, \Gamma, \xi)$ as given by

$$\psi(M, \Gamma, \xi) := \psi(Y, \overline{\xi}) \in HM_{\bullet}(-Y|-R; \Gamma_{-n}) =: SHM(-M, -\Gamma)$$

for any contact closure $(Y, R, \eta, \overline{\xi})$ of (M, Γ, ξ) . We prove the following:

THEOREM 1.9 [3]. There exists an isomorphism

$$SHM(-M, -\Gamma) \to SFH(-M, -\Gamma) \otimes \mathcal{R}$$

which sends $\psi(M, \Gamma, \xi)$ to $EH(M, \Gamma, \xi) \otimes 1$.

This theorem leads to a new proof of the invariance of EH up to isomorphism, independent of the less understood 'uniqueness' part of the relative Giroux correspondence. Combined with our work in [4], it also shows that the 'LOSS' invariant in knot Floer homology satisfies a certain functoriality with respect to Lagrangian concordance.

Unsurprisingly, our strategy for proving Theorem 1.9 relies on the combined work of Taubes [44–48] and Colin *et al.* [6–8], which shows that there is an isomorphism

$$HM_{\bullet}(-Y|-R;\Gamma_{-\eta}) \to HF^+(-Y|-R;\Gamma_{-\eta})$$

sending $\psi(Y, \bar{\xi})$ to $c^+(Y, \bar{\xi})$, together with the work of Lekili [35], which establishes an isomorphism

$$HF^+(-Y|-R; \Gamma_{-n}) \to SFH(-M, -\Gamma) \otimes \mathcal{R}.$$

To prove Theorem 1.9, it thus suffices to prove that Lekili's isomorphism sends $c^+(Y, \bar{\xi})$ to $EH(M, \Gamma, \xi) \otimes 1$. In fact, we prove this using a slight modification of Lekili's isomorphism, together with a characterization of $c^+(Y, \bar{\xi})$ similar to that of $\psi(M, \Gamma, \xi) = \psi(Y, \bar{\xi})$ in (4).

Another immediate goal involves Kronheimer and Mrowka's *monopole knot* homology, defined in [28]. Their theory assigns to a knot K in a closed 3-manifold Y the isomorphism class of \mathcal{R} -modules

$$\underline{KHM}(Y, K) := \underline{SHM}(Y \smallsetminus \nu(K), m \cup -m),$$

where v(K) is a tubular neighborhood of the knot and *m* is an oriented meridian on the boundary of this knot complement (see [1] for our 'natural' refinement of this construction.) It follows from the work of Taubes *et al.* that monopole knot homology is isomorphic to the 'hat' version of knot Floer homology,

$$\underline{KHM}(Y, K) \cong \widehat{HFK}(Y, K) \otimes \mathcal{R}.$$

Our aim is to use the bypass attachment maps defined here to construct a version of monopole knot homology analogous to the more powerful 'minus' version of knot Floer homology. Our approach is based on the work of Etnyre *et al.* [12] described below.

Suppose *K* is an oriented Legendrian knot in (Y, ξ) and let $M_n = (Y \setminus v(K), \Gamma_n)$ be the complement of the *n*-fold negative stabilization of *K*. Then M_n can be thought of as obtained from M_{n-1} by gluing on a layer $(T^2 \times I, \xi_-)$ called a *negative basic slice*. Etnyre, Vela-Vick, and Zarev define $\underline{SFH}(-Y, K)$ to be the direct limit of the sequence

$$SFH(-M_0) \xrightarrow{\phi_{\xi_-}} SFH(-M_1) \xrightarrow{\phi_{\xi_-}} SFH(-M_2) \to \dots,$$

where the Φ_{ξ_-} are the gluing maps associated to these basic slice attachments. This limit $\underline{SFH}(-Y, K)$ is a module over $(\mathbb{Z}/2\mathbb{Z})[U]$, where the *U*-action is induced by maps

$$\Phi_{\xi_+}$$
: SFH $(-M_n) \rightarrow$ SFH $(-M_{n-1})$

associated to gluing on layers $(T^2 \times I, \xi_+)$ called *positive* basic slices. The authors of [12] show that $\overrightarrow{SFH}(K)$ is isomorphic to $HFK^-(-Y, K)$ as a $(\mathbb{Z}/2\mathbb{Z})[U]$ -module.

Since these basic slice attachments are equivalent to bypass attachments, we can use our bypass attachment maps to define a similar limit module in *SHM*. To define an $\mathcal{R}[U]$ -module structure on this limit, one must show that the bypass attachment maps corresponding to the positive and negative basic slices commute. This is work in progress. Once complete, it will be interesting to compare

this limit theory with $HFK^{-}(-Y, K)$ and with a similar invariant defined by Kutluhan [29] in terms of filtrations on the monopole Floer complex of -Y.

Another major goal is to prove Conjecture 1.7, which posits that the map $\Phi_{\xi,H}$ in (3) is independent of H. This would imply, in particular, that the maps associated to the positive and negative basic slice attachments above commute as desired. More importantly, it would allow us to to assign well-defined maps to cobordisms between sutured manifolds in the monopole Floer setting—in the language of [1], to extend <u>SHM</u> to a functor from **CobSut** to \mathcal{R} -**PSys**. Our approach is based on the work of Juhász [22] outlined below.

As defined in [22], a cobordism from (M_1, Γ_1) to (M_2, Γ_2) consists of a smooth 4-manifold W with boundary $\partial W = -M_1 \cup Z \cup M_2$, together with a contact structure ξ on Z with dividing set $\Gamma_1 \cup \Gamma_2$ on $\partial Z = -\partial M_1 \cup \partial M_2$. Juhász assigns to such a cobordism a map

$$F_W$$
: $SFH(-M_1, -\Gamma_1) \rightarrow SFH(-M_2, -\Gamma_2)$,

defined as the composition $F_W = F'_W \circ \Phi_{\xi}$, where

$$\Phi_{\xi}: SFH(-M_1, -\Gamma_1) \to SFH(-M_1 \cup H, -\Gamma_2)$$
(5)

is the contact gluing map defined by Honda, Kazez, and Matić, and

$$F'_W: SFH(-M_1 \cup H, -\Gamma_2) \to SFH(-M_2, -\Gamma_2)$$
(6)

is a map defined via more standard Heegaard Floer techniques.

Once we prove Conjecture 1.7, we will have an *SHM* analogue of the map in (5). Moreover, we can already define a monopole Floer analogue of the map in (6). Indeed, since the sutured manifolds $(-M_1 \cup H, -\Gamma_2)$ and $(-M_2, -\Gamma_2)$ have the same (sutured) boundaries, there is a natural way of turning *W* into a cobordism \overline{W} between their closures. We define the analogue of F'_W to be the map in monopole Floer homology induced by \overline{W} . With analogues of the maps in (5) and (6), we can then define an analogue of Juhász's map F_W via composition as above.

The last project we mention here concerns defining a monopole Floer version of bordered Heegaard Floer homology. In [53], Zarev showed that the homologies of Lipshitz, Ozsváth, and Thurston's bordered Heegaard Floer invariants [36] can be expressed as direct sums of certain sutured Floer homology groups. Furthermore, he showed that the multiplication in the homology of the DGA associated to a parametrized surface in bordered Floer homology can be expressed in terms of the sutured cobordism maps defined by Juhász in [22]. Once we define analogous sutured cobordism maps in *SHM*, as described above, we will be able to define corresponding homology-level bordered invariants in the monopole Floer setting.

Of course, simply knowing the homology-level multiplications for the surface DGA and the bordered modules is not enough for a pairing theorem (a central feature of any good bordered theory), but it would be an important start.

As mentioned previously, the ideas in this paper are used to define similar contact handle attachment maps in the instanton Floer setting in [2]. These maps give rise to an analogous bypass exact triangle in that setting. We plan to use them in future work to construct sutured cobordism maps and bordered invariants in instanton Floer homology as well, following the strategy outlined above.

1.4. Organization. In Section 2, we review projectively transitive systems, the construction of sutured monopole homology, Kronheimer and Mrowka's invariant of closed contact 3-manifolds, and some convex surface theory. In Section 3, we define the classes $\psi^g(M, \Gamma, \xi)$ and $\psi(M, \Gamma, \xi)$ and establish some of their basic properties. Much of Section 3 is devoted to preliminary work on *contact preclosures* that is used in Section 4 to prove Theorem 1.1—that $\psi^g(M, \Gamma, \xi)$ is well defined for each g. In Section 4, we prove Theorem 1.1 and define the contact handle attachment maps in *SHM*. We then use these maps to prove Theorem 1.2—that $\psi(M, \Gamma, \xi)$ is well defined. In Section 5, we prove Theorem 1.8—that *SHM* satisfies a bypass exact triangle.

2. Preliminaries

In this section, we review the notion of a projectively transitive system, the construction of sutured monopole homology, and basic properties of Kronheimer and Mrowka's contact invariant, and we collect some facts from convex surface theory.

2.1. Projectively transitive systems. In **[1]** we introduced *projectively transitive systems* to make precise the idea of a collection of modules being canonically isomorphic up to multiplication by a unit. We recount their definition and related notions below.

DEFINITION 2.1. Suppose M_{α} and M_{β} are modules over a unital commutative ring \mathcal{R} . We say that elements $x, y \in M_{\alpha}$ are *equivalent* if $x = u \cdot y$ for some $u \in \mathcal{R}^{\times}$. Likewise, homomorphisms

$$f, g: M_{\alpha} \to M_{\beta}$$

are *equivalent* if $f = u \cdot g$ for some $u \in \mathbb{R}^{\times}$.

REMARK 2.2. We will write $x \doteq y$ or $f \doteq g$ to indicate that two elements or homomorphisms are equivalent, and will denote their equivalence classes by [x] or [f].

Note that *composition* of equivalence classes of homomorphisms is well defined, as is the *image* of the equivalence class of an element under an equivalence class of homomorphisms.

DEFINITION 2.3. Let \mathcal{R} be a unital commutative ring. A *projectively transitive* system of \mathcal{R} -modules consists of a set A together with:

- (1) a collection of \mathcal{R} -modules $\{M_{\alpha}\}_{\alpha \in A}$ and
- (2) a collection of equivalence classes of homomorphisms $\{g_{\beta}^{\alpha}\}_{\alpha,\beta\in A}$ such that:
 - (a) elements of the equivalence class g^{α}_{β} are isomorphisms from M_{α} to M_{β} ,
 - (b) $g^{\alpha}_{\alpha} = [\mathrm{id}_{M_{\alpha}}],$

(c)
$$g^{\alpha}_{\gamma} = g^{\beta}_{\gamma} \circ g^{\alpha}_{\beta}$$
.

REMARK 2.4. The equivalence classes of homomorphisms in a projectively transitive system of \mathcal{R} -modules can be thought of as specifying canonical isomorphisms between the modules in the system that are well defined up to multiplication by units in \mathcal{R} .

The class of projectively transitive systems of \mathcal{R} -modules forms a category \mathcal{R} -**PSys** with the following notion of morphism.

DEFINITION 2.5. A morphism of projectively transitive systems of \mathcal{R} -modules

$$F: (A, \{M_{\alpha}\}, \{g_{\beta}^{\alpha}\}) \to (B, \{N_{\gamma}\}, \{h_{\delta}^{\gamma}\})$$

is a collection of equivalence classes of homomorphisms $F = \{F_{\gamma}^{\alpha}\}_{\alpha \in A, \gamma \in B}$ such that:

- (1) elements of the equivalence class F_{γ}^{α} are homomorphisms from M_{α} to N_{γ} ,
- (2) $F_{\delta}^{\beta} \circ g_{\beta}^{\alpha} = h_{\delta}^{\gamma} \circ F_{\gamma}^{\alpha}$.

Note that *F* is an *isomorphism* iff the elements in each equivalence class F_{γ}^{α} are isomorphisms.

REMARK 2.6. A collection of equivalence classes of homomorphisms $\{F_{\gamma}^{\alpha}\}$ with indices ranging over any nonempty subset of $A \times B$ can be uniquely completed

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to a morphism as long as this collection satisfies the compatibility in (2.5) where it makes sense.

DEFINITION 2.7. An *element* of a projectively transitive system of \mathcal{R} -modules

$$x \in \mathcal{M} = (A, \{M_{\alpha}\}, \{g_{\beta}^{\alpha}\})$$

is a collection of equivalence classes of elements $x = \{x_{\alpha}\}_{\alpha \in A}$ such that:

(1) elements of the equivalence class x_{α} are elements of M_{α} ,

(2) $x_{\beta} = g^{\alpha}_{\beta}(x_{\alpha}).$

REMARK 2.8. As in Remark 2.6, a collection of equivalence classes of elements $\{x_{\alpha}\}$ with indices ranging over any nonempty subset of A can be uniquely completed to an element of \mathcal{M} as long as this collection satisfies the compatibility in (2.7) where it makes sense.

We say that x is a *unit* in \mathcal{M} if each M_{α} is isomorphic to \mathcal{R} and each x_{α} is the equivalence class of a generator. As there is a well-defined notion of scalar multiplication for projectively transitive systems, we may also talk about *primitive* elements of \mathcal{M} . The *zero* element $0 \in \mathcal{M}$ is the collection of equivalence classes of the elements $0 \in M_{\alpha}$. Finally, it is clear how to define the image F(x) of an element $x \in \mathcal{M}$ under a morphism $F : \mathcal{M} \to \mathcal{N}$ of projectively transitive systems of \mathcal{R} -modules.

REMARK 2.9. In an abuse of notation, we will also use \mathcal{R} to denote the distinguished system in \mathcal{R} -**PSys** given by

$$\mathcal{R} = (\{\star\}, \{\mathcal{R}\}, \{[\mathrm{id}_{\mathcal{R}}]\})$$

consisting of the single \mathcal{R} -module \mathcal{R} together with the equivalence class of the identity map. There is an obvious correspondence between elements of a projectively transitive system of \mathcal{R} -modules \mathcal{M} and morphisms $\mathcal{R} \to \mathcal{M}$.

As the category \mathcal{R} -**PSys** contains kernels and images, there is a straightforward notion of an exact sequence of projectively transitive systems of \mathcal{R} -modules. Concretely, suppose

$$\mathcal{M} = (A, \{M_{\alpha}\}, \{g_{\beta}^{\alpha}\}), \quad \mathcal{N} = (B, \{N_{\gamma}\}, \{h_{\delta}^{\gamma}\}), \quad \mathcal{P} = (C, \{P_{\epsilon}\}, \{i_{\zeta}^{\epsilon}\})$$

are projectively transitive systems of \mathcal{R} -modules. It is easy to see that a sequence

$$\mathcal{M} \xrightarrow{F} \mathcal{N} \xrightarrow{G} \mathcal{P}$$

is exact at \mathcal{N} if there exist $\alpha \in A$, $\gamma \in B$, $\epsilon \in C$ and representatives $\hat{F}^{\alpha}_{\gamma}$, $\hat{G}^{\gamma}_{\epsilon}$ of the equivalence classes F^{α}_{γ} , G^{γ}_{ϵ} such that the sequence of \mathcal{R} -modules

$$M_{lpha} \xrightarrow{\hat{F}^{lpha}_{\gamma}} N_{\gamma} \xrightarrow{\hat{G}^{\gamma}_{\epsilon}} P_{\epsilon}$$

is exact at N_{γ} .

2.2. Sutured monopole homology. In this subsection, we describe our refinement of Kronheimer and Mrowka's sutured monopole homology, as defined in [1].

DEFINITION 2.10. A balanced sutured manifold (M, Γ) is a compact, oriented, smooth 3-manifold M with a collection Γ of disjoint, oriented, smooth curves in ∂M called *sutures*. Let $R(\Gamma) = \partial M \setminus \Gamma$, oriented as a subsurface of ∂M . We require that:

- (1) neither M nor $R(\Gamma)$ has closed components,
- (2) $R(\Gamma) = R_{+}(\Gamma) \sqcup R_{-}(\Gamma)$ with $\partial R_{+}(\Gamma) = -\partial R_{-}(\Gamma) = \Gamma$,

(3)
$$\chi(R_+(\Gamma)) = \chi(R_-(\Gamma)).$$

An *auxiliary surface* for (M, Γ) is a compact, connected, oriented surface F with g(F) > 0 and $\pi_0(\partial F) \cong \pi_0(\Gamma)$. Suppose F is an auxiliary surface for (M, Γ) , $A(\Gamma)$ is a closed tubular neighborhood of Γ in ∂M , and

$$h: \partial F \times [-1, 1] \to A(\Gamma)$$

is an orientation-reversing diffeomorphism which sends $\partial F \times \{\pm 1\}$ to $\partial (R_{\pm}(\Gamma) \setminus A(\Gamma))$. The *preclosure* of *M* associated to *F*, $A(\Gamma)$, and *h* is the smooth 3-manifold

$$M' = M \bigcup_{h} F \times [-1, 1]$$

formed by gluing $F \times [-1, 1]$ to M according to h and rounding corners. Condition (3) in Definition 2.10 ensures that M' has two diffeomorphic boundary components, ∂_+M' and ∂_-M' . In particular, an easy calculation shows that

$$g(\partial_{\pm}M') = \frac{|\Gamma| - \chi(R_{+}(\Gamma)) + 2g(F)}{2}.$$
(7)

We may glue $\partial_+ M'$ to $\partial_- M'$ by some diffeomorphism to form a closed manifold *Y* containing a distinguished surface

$$R := \partial_+ M' = -\partial_- M' \subset Y.$$



DEFINITION 2.11 [1]. A marked closure of (M, Γ) is a tuple $\mathcal{D} = (Y, R, r, m, \eta)$ consisting of:

- (1) a closed, oriented, 3-manifold Y,
- (2) a closed, oriented, surface R with $g(R) \ge 2$,
- (3) an oriented, nonseparating, embedded curve $\eta \subset R$,
- (4) a smooth, orientation-preserving embedding $r : R \times [-1, 1] \hookrightarrow Y$,
- (5) a smooth, orientation-preserving embedding $m : M \hookrightarrow Y \setminus int(Im(r))$ such that:
 - (a) m extends to a diffeomorphism

$$M\bigcup_{h} F \times [-1,1] \to Y \setminus \operatorname{int}(\operatorname{Im}(r))$$

for some $A(\Gamma)$, F, h, as above,

(b) *m* restricts to an orientation-preserving embedding

$$R_+(\Gamma) \smallsetminus A(\Gamma) \hookrightarrow r(R \times \{-1\}).$$

The genus $g(\mathcal{D})$ refers to the genus of *R*.

REMARK 2.12. It follows from the formula in (7) that (M, Γ, ξ) admits a genus g marked closure for every

$$g \ge \max\left(2, \frac{|\Gamma| - \chi(R_+(\Gamma)) + 2}{2}\right).$$

We will denote this maximum by $g(M, \Gamma)$.

REMARK 2.13. For a marked closure \mathscr{D} as in Definition 2.11, the pair $(Y, r(R \times \{t\}))$ is a closure of (M, Γ) in the sense of Kronheimer and Mrowka for any $t \in [-1, 1]$.

REMARK 2.14. Suppose $\mathscr{D} = (Y, R, r, m, \eta)$ is a marked closure of (M, Γ) . Then, the tuple

$$-\mathscr{D} := (-Y, -R, r, m, -\eta),$$

obtained by reversing the orientations of *Y*, *R*, and η , is a marked closure of $-(M, \Gamma) := (-M, -\Gamma)$, where, *r* and *m* are the induced embeddings of $-R \times [-1, 1]$ and -M into -Y.

NOTATION 2.15. For the rest of this paper, \mathcal{R} will be the *Novikov ring over* \mathbb{Z} , given by

$$\mathcal{R} = \left\{ \sum_{\alpha} c_{\alpha} t^{\alpha} \, \middle| \, \alpha \in \mathbb{R}, \, c_{\alpha} \in \mathbb{Z}, \, \#\{\beta < n | c_{\beta} \neq 0\} < \infty \text{ for all } n \in \mathbb{Z} \right\}.$$

Following Kronheimer and Mrowka [28], we made the following definition in [1].

DEFINITION 2.16. Given a marked closure $\mathscr{D} = (Y, R, r, m, \eta)$ of (M, Γ) , the *sutured monopole homology of* \mathscr{D} is the \mathcal{R} -module

$$\underline{SHM}(\mathscr{D}) := HM_{\bullet}(Y|R; \Gamma_{\eta}).$$

Here, $\widetilde{HM}_{\bullet}(Y|R; \Gamma_{\eta})$ is shorthand for the monopole Floer homology of *Y* in the 'bottom-most' Spin^{*c*} structures relative to $r(R \times \{0\})$,

$$\widetilde{HM}_{\bullet}(Y|R; \Gamma_{\eta}) := \bigoplus_{\substack{\mathfrak{s} \in \operatorname{Spin}^{c}(Y)\\ \langle c_{1}(\mathfrak{s}), [r(R \times \{0\})] \rangle = 2 - 2g(R)}} \widetilde{HM}_{\bullet}(Y, \mathfrak{s}; \Gamma_{r(\eta \times \{0\})}), \tag{8}$$

where, for each Spin^{*c*} structure \mathfrak{s} , $\Gamma_{r(\eta \times \{0\})}$ is the local system on the Seiberg–Witten configuration space $\mathcal{B}(Y, \mathfrak{s})$ with fiber \mathcal{R} specified by the curve $r(\eta \times \{0\}) \subset Y$, as defined in [28, Section 2.2]. (As mentioned in the introduction, both [28] and [1] used top-most Spin^{*c*} structures, but this makes no difference in the construction or proofs of invariance and naturality.)

In [28], Kronheimer and Mrowka proved that the isomorphism class of $\underline{SHM}(\mathcal{D})$ is an invariant of (M, Γ) . We strengthened this in [1], proving that the sutured monopole homology groups of any two marked closures of (M, Γ) are canonically isomorphic, up to multiplication by a unit in \mathcal{R} . Specifically, for any two marked closures $\mathcal{D}, \mathcal{D}'$ of (M, Γ) , we construct an isomorphism

$$\underline{\Psi}_{\mathscr{D},\mathscr{D}'}:\underline{SHM}(\mathscr{D})\to\underline{SHM}(\mathscr{D}'),$$

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well defined up to multiplication by a unit in \mathcal{R} , such that the modules in $\{\underline{SHM}(\mathcal{D})\}_{\mathcal{D}}$ and the equivalence classes of maps in $\{\underline{\Psi}_{\mathcal{D},\mathcal{D}'}\}_{\mathcal{D},\mathcal{D}'}$ form a projectively transitive system of \mathcal{R} -modules. (The collection of marked closures is a proper class rather than a set and so cannot technically serve as the indexing object for a projectively transitive system. One can remedy this by requiring that *Y* and *R* be submanifolds of Euclidean space. We will not worry about such issues.) We will review the construction of these maps in Section 4.

DEFINITION 2.17. The sutured monopole homology of (M, Γ) is the projectively transitive system of \mathcal{R} -modules <u>SHM</u> (M, Γ) given by the modules and the equivalence classes above.

Sutured monopole homology is functorial in the following sense. Suppose

$$f:(M,\Gamma)\to (M',\Gamma')$$

is a diffeomorphism of sutured manifolds and $\mathscr{D}' = (Y', R', r', m', \eta')$ is a marked closure of (M', Γ') . Then

$$\mathscr{D}'_f := (Y', R', r', m' \circ f, \eta') \tag{9}$$

is a marked closure of (M, Γ) . Let

$$\operatorname{id}_{\mathscr{D}'_{\mathfrak{C}},\mathscr{D}'}: \underline{SHM}(\mathscr{D}'_{\mathfrak{f}}) \to \underline{SHM}(\mathscr{D}')$$

be the identity map on $\underline{SHM}(\mathscr{D}'_f) = \underline{SHM}(\mathscr{D}')$. The equivalence classes of these identity maps can be completed to a morphism (as in Remark 2.6)

$$\underline{\mathbf{SHM}}(f):\underline{\mathbf{SHM}}(M,\,\Gamma)\to\underline{\mathbf{SHM}}(M',\,\Gamma'),$$

which is an invariant of the isotopy class of f. We proved in [1] that these morphisms behave as expected under composition of diffeomorphisms, so that <u>SHM</u> defines a functor from **DiffSut** to \mathcal{R} -**PSys**, where **DiffSut** is the category of balanced sutured manifolds and isotopy classes of diffeomorphisms between them.

Recall that a *product sutured manifold* is a sutured manifold (M, Γ) obtained from a product $(S \times [-1, 1], \partial S \times \{0\})$ by rounding corners, for some surface *S* with boundary. Product sutured manifolds have simple Floer homology, as expressed below. This fact will be important for us at several points in this paper.

PROPOSITION 2.18. If (M, Γ) is a product sutured manifold, then <u>SHM</u> $(M, \Gamma) \cong \mathcal{R}$.

Proof. Let *F* be an auxiliary surface for (M, Γ) with $g(F) \ge 2$. Thinking of (M, Γ) as obtained from $(S \times [-1, 1], \partial S \times \{0\})$ by rounding corners, we can form a preclosure of (M, Γ) by gluing $F \times [-1, 1]$ to $S \times [-1, 1]$ according to a map

$$h:\partial F\times [-1,1]\to \partial S\times [-1,1]$$

of the form $f \times id$ for some diffeomorphism $f : \partial F \to \partial S$. This preclosure is then a product $M' = (S \cup F) \times [-1, 1]$. To form a marked closure, we take $R = S \cup F$ and glue $R \times [-1, 1]$ to M' by the 'identity' maps

$$R \times \{\pm 1\} \to S \times \{\mp 1\}.$$

An oriented, nonseparating curve $\eta \subset S \cup F$ gives a marked closure

$$\mathscr{D} = ((S \cup F) \times S^1, (S \cup F), r, m, \eta).$$

Here, we are thinking of S^1 as the union of two copies of [-1, 1], and r and m as the obvious embeddings. Therefore,

$$\underline{SHM}(\mathscr{D}) := \widecheck{HM}_{\bullet}((S \cup F) \times S^{1} | (S \cup F); \Gamma_{\eta}) \cong \mathcal{R},$$

by [28, Lemma 4.7]. The proposition follows.

REMARK 2.19. In Section 5, we will work over the Novikov field

$$\mathcal{R}/2\mathcal{R} := \mathcal{R} \otimes_{\mathbb{Z}} \mathbb{Z}/2\mathbb{Z}$$

in order to use the surgery exact triangle in monopole Floer homology, which has not been established in characteristic 0. This might alarm the reader familiar with [28], where, when working with local coefficients, Kronheimer and Mrowka require that \mathcal{R} (which is not necessarily the Novikov ring in their case) have no \mathbb{Z} -torsion. This condition is imposed to ensure that certain Tor terms arising in the Künneth theorem vanish. It turns out, however, that we are safe when working in characteristic 2 and using the Novikov field $\mathcal{R}/2\mathcal{R}$, as these Tor terms still vanish; see [42, Section 2.2] for details.

2.3. The monopole Floer contact invariant. In [26], Kronheimer and Mrowka defined an invariant of contact structures on closed 3-manifolds which assigns to a closed contact manifold (Y, ξ) a class

$$\psi(Y,\xi) \in \widecheck{HM}_{\bullet}(-Y,\mathfrak{s}_{\xi})$$

which depends only on the isotopy class of the contact structure ξ . We will use the same notation for the version of this invariant in monopole Floer homology

with coefficients in a local system. Below, we review three important properties of this invariant.

The first is that the invariant vanishes for overtwisted contact structures.

THEOREM 2.20 [26]. If (Y, ξ) is overtwisted, then $\psi(Y, \xi) = 0$.

Next, recall that a *weak symplectic filling* of a closed contact 3-manifold (Y, ξ) is a symplectic manifold (X, ω) such that $Y = \partial X$ and $\omega|_{\xi} > 0$.

THEOREM 2.21 [25, 26]. If (Y, ξ) has a weak symplectic filling (X, ω) , then

$$\psi(Y,\xi) \in \widecheck{HM}_{\bullet}(-Y,\mathfrak{s}_{\xi};\Gamma_{-\eta})$$

is a primitive class (in particular, nonzero) for any local system $\Gamma_{-\eta}$ with fiber \mathcal{R} given by a curve $\eta \subset Y$ which is Poincaré dual to $[\omega] \in H^2(Y; \mathbb{R})$.

Finally, suppose (Y_-, ξ_-) and (Y_+, ξ_+) are closed contact 3-manifolds and recall that an *exact symplectic cobordism* from (Y_-, ξ_-) to (Y_+, ξ_+) is an exact symplectic manifold $(X, \omega = d\lambda)$ with boundary $\partial X = Y_+ \sqcup -Y_-$ for which the restrictions $\lambda|_{Y_{\pm}}$ are contact forms for ξ_{\pm} .

THEOREM 2.22 [21]. Suppose (X, ω) is an exact symplectic cobordism from (Y_-, ξ_-) to (Y_+, ξ_+) . Then, viewing X as a cobordism from $-Y_+$ to $-Y_-$, the induced map

 $\widecheck{HM}_{\bullet}(X): \widecheck{HM}_{\bullet}(-Y_{+}) \to \widecheck{HM}_{\bullet}(-Y_{-})$

sends $\psi(Y_+, \xi_+)$ *to* $\pm \psi(Y_-, \xi_-)$ *.*

We will frequently apply this theorem via the following corollary.

COROLLARY 2.23. Suppose (Y', ξ') is the result of contact (+1)-surgery on a Legendrian knot in (Y, ξ) and let W be the corresponding 2-handle cobordism from Y to Y'. Then, the map

$$\widecheck{HM}_{\bullet}(-W): \widecheck{HM}(-Y) \to \widecheck{HM}(-Y')$$

sends $\psi(Y, \xi)$ to $\pm \psi(Y, \xi')$.

Proof. If (Y', ξ') is the result of contact (+1)-surgery on $K \subset (Y, \xi)$, then (Y, ξ) is the result of contact (-1)-surgery on a parallel knot $K' \subset (Y', \xi')$. Let X be the Weinstein 2-handle cobordism corresponding to the latter surgery. By

Theorem 2.22, the map

$$\widecheck{HM}_{\bullet}(X) : \widecheck{HM}(-Y) \to \widecheck{HM}(-Y')$$

sends $\psi(Y,\xi)$ to $\pm \psi(Y,\xi')$. But, as a cobordism from -Y to -Y', X is isomorphic to -W.

REMARK 2.24. In [21], Theorem 2.22 is stated for monopole Floer homology with coefficients in \mathbb{F}_2 . However, the theorem also holds over \mathbb{Z} and with local coefficients, up to multiplication by a unit in both cases (the same proof extends to these settings without modification).

2.4. Convex surfaces and contact manifolds with boundary. Here, we record some facts about characteristic foliations and convex surfaces, largely in order to standardize vocabulary. We will assume our reader is familiar with most of this material, and any proofs are postponed until Appendix A. For more comprehensive treatments, see [15, 16, 18].

Suppose *S* is a smooth surface and \mathfrak{F} is a singular foliation of *S*. An embedded multicurve $\Gamma \subset S$ is said to *divide* \mathfrak{F} if:

- (1) Γ is transverse to the leaves of \mathfrak{F} ,
- (2) $S \setminus \Gamma$ is a disjoint union of *positive* and *negative* regions $S_+ \sqcup S_-$,
- (3) there is a volume form ω and vector field w on S such that
 - (a) w directs \mathfrak{F} ,
 - (b) w points transversely out of S_+ along Γ ,
 - (c) $\pm \mathcal{L}_w(\omega) > 0$ on S_{\pm} .

Given an embedded surface $S \subset (M, \xi)$, the *characteristic foliation* S_{ξ} is the singular foliation of S obtained by integrating the vector field $TS \cap \xi$. Giroux showed in [15] that S_{ξ} determines ξ in a neighborhood of S, up to contactomorphism fixing S.

A contact vector field is one whose flow preserves ξ . An embedded surface $S \subset M$ is convex if there exists a contact vector field transverse to S. Given a contact vector field v transverse to S, the *dividing set* on S associated to v is the multicurve

$$\Gamma = \{ p \in S \mid v_p \in \xi_p \}.$$

This multicurve divides S_{ξ} in the sense above. In particular, we orient Γ so that

$$\partial \overline{S}_{+} = -\partial \overline{S}_{-} = -\Gamma.$$

Conversely, any multicurve which divides S_{ξ} is the dividing set of some contact vector field (see [13, Theorem 4.8.5]). The space of such multicurves is contractible (see [38]); in particular, the isotopy class of Γ is independent of v.

A contact structure on $S \times \mathbb{R}$ is called *vertically invariant* if ∂_t is a contact vector field. A contact vector field v transverse to $S \subset (M, \xi)$ defines (after cutting off v away from S using a Hamiltonian) a tubular neighborhood $S \times \mathbb{R}$ of $S = S \times \{0\}$ in which v is identified with ∂_t . We will refer to such a neighborhood as a *vertically invariant neighborhood* of S.

Giroux's Flexibility Theorem below expresses the idea that the crucial information about a contact structure in the neighborhood of a convex surface S is encoded by the dividing set.

THEOREM 2.25 [15]. Suppose $S \subset (M, \xi)$ is a convex surface with dividing set Γ for some contact vector field v. Let \mathfrak{F} be a singular foliation divided by Γ and let N be any neighborhood of S. Then there is an isotopy of embeddings $\varphi_r : S \to N$, $r \in [0, 1]$, such that

- (1) φ_0 is the inclusion $S \subset M$,
- (2) each $\varphi_r(S)$ is transverse to v (hence, convex) with dividing set $\varphi_r(\Gamma) = \Gamma$,
- (3) the characteristic foliation $(\varphi_1(S))_{\xi}$ agrees with $\varphi_1(\mathfrak{F})$.

We will rely heavily on Giroux's Uniqueness Lemma below.

LEMMA 2.26 [16]. Suppose *S* is a surface and ξ_0 and ξ_1 are two contact structures on $S \times [0, 1]$ which induce the same characteristic foliations on $S \times \{0, 1\}$. Suppose each $S \times \{t\}$ is convex with respect to both ξ_0 and ξ_1 , and contains a multicurve Γ_t which varies continuously with *t* and divides the characteristic foliations $(S \times \{t\})_{\xi_0}$ and $(S \times \{t\})_{\xi_1}$. Then ξ_0 and ξ_1 are isotopic by an isotopy which is stationary on $S \times \{0, 1\}$.

REMARK 2.27. The isotopy Giroux constructs is not necessarily stationary on $S \times \{0, 1\}$. However, one can arrange this (see [13, Lemma 4.9.2]).

Suppose *M* is a manifold with boundary and \mathfrak{F} is a singular foliation of ∂M . Let Cont(M, \mathfrak{F}) be the set of contact structures on *M* for which ∂M is convex with $(\partial M)_{\xi} = \mathfrak{F}$. The following is due to Honda [18, Proposition 4.2].

PROPOSITION 2.28. If \mathfrak{F}_0 and \mathfrak{F}_1 are two characteristic foliations of ∂M divided by the same multicurve Γ , then there is a canonical bijection $f_{01} : \pi_0(\text{Cont}(M, \mathfrak{F}_0)) \to \pi_0(\text{Cont}(M, \mathfrak{F}_1)).$



Figure 1. The neighborhood $\partial S \times [0, 1]_s \times [-1, 1]_t \subset S \times [-1, 1]_t$ for a convex surface *S* with collared Legendrian boundary. The arcs in bold belong to the dividing sets associated to the contact vector fields ∂_t and ∂_s ; the others are rulings and divides. Note that the divides share endpoints with the dividing sets.

In the above proposition, the term 'canonical' means that $f_{00} = \text{id}$ and $f_{02} = f_{12} \circ f_{01}$. Moreover, this bijection sends tight contact structures to tight contact structures. We outline the proof of this proposition in Appendix A (our proof is slightly different in form but not in substance from Honda's) as elements of the proof will be useful later on.

The convex surfaces considered to this point have been closed. A convex surface in (M, ξ) with *collared Legendrian boundary* is a properly embedded surface $S \subset M$ with Legendrian boundary, equipped with a collar neighborhood $\partial S \times [0, 1]$ of $\partial S = \partial S \times \{0\}$ on which ξ is [0, 1]-invariant (see [18]). In particular, the curves $\partial S \times \{s\}$ are Legendrian; these curves are called *rulings*. Moreover, there is an even number of Legendrian arcs in $\partial S \times [0, 1]$ of the form $\{p\} \times [0, 1]$ for $p \in \partial S$; these are called *divides*. Note that, for any transverse contact vector field v, the dividing set on $\partial S \times [0, 1]$ consists of arcs parallel to and alternating with the divides, as in Figure 1.

LEMMA 2.29. Suppose *S* is a surface with boundary, and let Γ be a nonempty collection of oriented, disjoint, properly embedded curves and arcs on *S* such that $S \setminus \Gamma = S_+ \sqcup S_-$ with

$$\partial \overline{S}_+ = -\partial \overline{S}_- = \Gamma.$$

Then there exists a [-1, 1]-invariant contact structure on $S \times [-1, 1]$ for which each $S \times \{t\}$ is convex with collared Legendrian boundary $\partial S \times [0, 1] \times \{t\}$ and dividing set $\Gamma \times \{t\}$.

Although this result is well known to experts, we sketch a proof in Appendix A since we could not find one in the literature.

REMARK 2.30. Note that, for any contact structure as in Lemma 2.29, ∂_t and ∂_s are contact vector fields on $\partial S \times [0, 1]_s \times [-1, 1]_t \subset S \times [-1, 1]_t$.

The lemma below asserts that, for a given Γ , there is essentially only one contact structure on $S \times [-1, 1]$ satisfying the conditions in Lemma 2.29.

LEMMA 2.31. Suppose ξ and ξ' are contact structures on $S \times [-1, 1]$ as in Lemma 2.29. Then, up to flexibility, ξ and ξ' are isotopic.

See Remark A.3 for a precise definition of the phrase 'up to flexibility'. Although Lemma 2.31 is also familiar to experts, we include a proof in Appendix A in order to more precisely describe the isotopy alluded to in the lemma; see the following remark.

REMARK 2.32. It will be clear from the proof that the isotopy alluded to in Lemma 2.31 can be taken to be of the form $\varphi_r \times id$ near $\partial S \times [-1, 1]$, for some isotopy φ_r of (S, Γ) .

3. A contact invariant in sutured monopole homology

Suppose (M, Γ) is a balanced sutured manifold and ξ is a contact structure on M such that ∂M is convex and Γ divides the characteristic foliation of ∂M induced by ξ . We will refer to the triple (M, Γ, ξ) as a *sutured contact manifold*. In this section, we construct the contact invariants

$$\psi^{g}(M, \Gamma, \xi) \in \underline{\mathbf{SHM}}(-M, -\Gamma).$$

(We will show that these elements are well defined and agree for large g in Section 4.) As mentioned in the introduction, the rough idea is to extend ξ to a contact structure $\overline{\xi}$ on a genus g closure of (M, Γ) and define $\psi^g(M, \Gamma, \xi)$ in terms of the monopole Floer contact invariant of this closed contact manifold, which we call a *contact closure* of (M, Γ, ξ) . We will make this precise below.

Since parts of this section are rather long and technical, we summarize their content here. In Subsection 3.1 we discuss the notion of a *contact preclosure*, a manifold with boundary constructed by gluing an auxiliary thickened surface of fixed genus to (M, Γ, ξ) , and show that it is well defined up to contactomorphisms fixing nearly all of (M, Γ) . In Subsection 3.2 we use this to produce contact closures and define $\psi^g(M, \Gamma, \xi)$ as their monopole Floer contact invariants, where g is determined by the above choice of genus. In the remaining subsections we prove some basic properties of $\psi^g(M, \Gamma, \xi)$ (having postponed the proof of invariance to Section 4) and compute the invariants for a class of product sutured manifolds.

3.1. Contact preclosures. We begin by studying a certain class of contact structures on preclosures of M. Our goal is to extend a contact structure on (M, Γ, ξ) across a preclosure in as simple a way as possible, so that the contact invariant of the eventual contact closure (constructed in Subsection 3.2) will be insensitive to any choices we have to make. In particular, we have to make several careful perturbations of contact structures, appeals to Giroux flexibility, and edge-rounding arguments along the way so that we can glue contact manifolds together along portions of their convex boundaries which contain dividing arcs. The fact that the end result is well defined, regardless of how we choose to arrange these dividing arcs, is the content of Theorem 3.3, whose proof is rather lengthy and technical as a result of these details. Since these arguments are not revisited in the rest of the paper, a casual reader may wish to skip the proof of Theorem 3.3 for now.

DEFINITION 3.1. Let F be a connected, orientable surface with nonempty boundary and positive genus. An *arc configuration* A on F consists of an embedded, nonseparating curve c on F together with disjoint embedded arcs a_1 , ..., a_n such that:

- (1) every a_i has one endpoint on ∂F and another on c,
- (2) $\operatorname{int}(a_i) \cap (c \cup \partial F) = \emptyset$ for each *i*,
- (3) every component of ∂F contains an endpoint of some a_i .

Suppose \mathcal{A} is an arc configuration on F and let $N(\mathcal{A})$ be a regular neighborhood of \mathcal{A} . Let $\Gamma_{\mathcal{A}}$ be the collection of oriented, properly embedded arcs in F given by

$$\Gamma_{\mathcal{A}} = -\overline{(\partial N(\mathcal{A}) \smallsetminus \partial F)}.$$
(10)

Let Ξ_A be a [-1, 1]-invariant contact structure on $F \times [-1, 1]$ for which each $F \times \{t\}$ is convex with collared Legendrian boundary and dividing set $\Gamma_A \times \{t\}$. There is a unique such Ξ_A up to flexibility and isotopy, by Lemma 2.31. Note that the dividing set on $\partial F \times [-1, 1]$ is of the form $\{p_1, \ldots, p_{2n}\} \times [-1, 1]$ for points $p_i \in \partial F$. Moreover, the negative region on $F \times \{1\}$ is $N(\mathcal{A}) \times \{1\}$. See Figure 2 for an example in which this and the negative region $\partial F \times [-1, 1]$ have been shaded.

Suppose the surface *F* above is an auxiliary surface for (M, Γ) , and consider the preclosure $M' = M \bigcup_h F \times [-1, 1]$ associated to some neighborhood $A(\Gamma)$ and diffeomorphism

$$h: \partial F \times [-1, 1] \to A(\Gamma).$$



Figure 2. Left, an arc configuration on a genus one surface with two boundary components. Right, the thickened surface with the negative regions on $F \times \{1\}$ and $\partial F \times [-1, 1]$ shaded.

We would like to define a contact structure ξ' on M' in terms of Ξ_A and ξ . To do so, we first perturb ξ in a neighborhood of $A(\Gamma)$ so that h identifies Ξ_A with this perturbed contact structure. This enables us to glue $F \times [-1, 1]$ to M via h contact geometrically. We will show (Theorem 3.3) that the resulting *contact preclosure* (M', ξ') is independent, up to flexibility and contactomorphism, of the arc configuration \mathcal{A} and the other choices involved.

We start by describing the perturbation of ξ . Label the components of Γ by Γ_1 , ..., Γ_m . Each Γ_i has an annular neighborhood $B_i \subset \partial M$ on which the leaves of the characteristic foliation are cocores with no singularities. Let $B(\Gamma)$ be the union of these B_i . Let A_i be the component of $A(\Gamma)$ containing Γ_i . We will assume that $A_i \subset \text{int}(B_i)$. The map h identifies A_i with $\partial_i F \times [-1, 1]$ for some component $\partial_i F$ of ∂F . In this way, the ordering on the components of Γ induces an ordering on the components of ∂F . Let k_i be the number of arcs in \mathcal{A} with an endpoint on $\partial_i F$. The dividing set on the annulus $\partial_i F \times [-1, 1]$ thus consists of $2k_i$ cocores.

The rough idea is to perturb ξ to a contact structure ξ_h whose dividing set Γ_h restricts to $2k_i$ cocores of A_i , such that h identifies the positive region of $\partial F \times [-1, 1]$ with the negative region of $A(\Gamma)$ determined by Γ_h . We do essentially this, but work on the level of characteristic foliations rather than dividing curves for added control on the eventual contactomorphisms between different preclosures.

For i = 1, ..., m, let $C_i \subset int(A_i)$ be an annulus such that the intersection $\Gamma_i \cap C_i$ consists of $2k_i$ cocores of C_i . We next choose an isotopy

$$\varphi_r: \partial M \to \partial M, r \in [0, 1]$$

which 'straightens out' these C_i , as shown in Figure 3. Precisely, we require that $\varphi_0 = \text{id}$, that $\varphi_1(C_i) = A_i$, that *h* identifies the positive region of $\partial F \times [-1, 1]$ with the negative region of $A(\Gamma)$ determined by the dividing set $\varphi_1(\Gamma)$, and that each φ_r restricts to the identity outside of $B(\Gamma)$.



Figure 3. Left, a view of $C_i \subset B_i$, where $k_i = 3$. Right, $\varphi(\Gamma_i) = \varphi_1(\Gamma_i)$ and $\varphi_1(C_i) = A_i$. The negative regions are shaded.

Choose a vertically invariant collar $\partial M \times (-\infty, 0]$ of $\partial M = \partial M \times \{0\}$ such that Γ is the dividing set associated to ∂_t . The isotopy φ_r induces a diffeomorphism

$$\varphi: M \to M$$

as follows. Let

$$r:(-\infty,0]\to[0,1]$$

be a smooth function with

$$r(t) = \begin{cases} 0 & \text{for } t \leq -2\\ 1 & \text{for } t \geq -1. \end{cases}$$

We define φ to be the map defined by

$$\varphi(x,t) = (\varphi_{r(t)}(x),t) \tag{11}$$

for $(x, t) \in \partial M \times (-\infty, 0]$ and by the identity outside of $\partial M \times (-\infty, 0]$. Note that φ restricts to φ_1 on ∂M and to the identity outside of $B(\Gamma) \times [-2, 0]$.

Define $\xi_0 := \varphi_*(\xi)$. Let \mathfrak{F}_1 be a foliation of ∂M divided by $\varphi(\Gamma) = \varphi_1(\Gamma)$ which agrees with $h(\partial F \times [-1, 1])_{\Xi_A}$ on $A(\Gamma)$ and with $\mathfrak{F}_0 = (\partial M)_{\xi_0}$ outside of $B(\Gamma)$, as illustrated in Figure 4. We apply flexibility, as in Proposition 2.28, with respect to the collar determined by the contact vector field $\varphi_*(\partial_t)$ for ξ_0 , to obtain a contact structure $\xi_1 = f_{01}(\xi_0)$ with $(\partial M)_{\xi_1} = \mathfrak{F}_1$. In doing so, we can arrange that $\xi_1 = h_*(\Xi_A)$ on $A(\Gamma)$ (see Remark A.1). Since \mathfrak{F}_0 and \mathfrak{F}_1 agree outside of $B(\Gamma)$, we can assume that ∂_t is a contact vector field for ξ_{01} on the complement of $B(\Gamma) \times [0, 1]$ in the product $\partial M \times [0, 1]$ used to define the map f_{01} . It then follows from the construction of f_{01} that $\xi_1 = \xi$ outside of $B(\Gamma) \times [-3, 0]$, since



Figure 4. Left, a view of A_i , B_i , and $\varphi(\Gamma_i) = \varphi_1(\Gamma_i)$. Right, a view of the foliation \mathfrak{F}_1 in the portion of B_i contained within the dotted rectangle.



Figure 5. Left, gluing $\partial F \times [-1, 1]$ to *M* along $A(\Gamma)$, as viewed near some $B_i \times (-\infty, 0]$. Middle, the glued manifold. Right, the contact preclosure with convex boundary after rounding corners.

 ξ_0 and $\varphi_*(\partial_t)$ agree with ξ and ∂_t , respectively, outside of $B(\Gamma) \times [-2, 0]$. We will hereafter denote ξ_1 by ξ_h to indicate its dependence on h. We may now glue $(F \times [-1, 1], \Xi_A)$ to (M, ξ_h) via h contact geometrically. We perform this gluing, rounding corners as illustrated in Figure 5, to obtain a *contact preclosure*

$$(M',\xi') = \left(M\bigcup_{h} F \times [-1,1], \xi_h \cup \Xi_{\mathcal{A}}\right)$$

of (M, Γ, ξ) .

REMARK 3.2. The dividing set for ξ' consists of two parallel nonseparating curves on each component $\partial_{\pm}M'$ of $\partial M'$. The negative region on $\partial_{+}M'$ is the annulus bounded by these curves and retracts onto a regular neighborhood of

 $c \times \{1\}$, where c is the curve in \mathcal{A} . Likewise, the positive region on $\partial_{-}M'$ is an annulus which retracts onto a neighborhood of $c \times \{-1\}$.

The rest of this subsection is devoted to proving the well definedness of (M', ξ') . Our main result is the following.

THEOREM 3.3. Suppose (M'_1, ξ'_1) and (M'_2, ξ'_2) are contact preclosures of (M, Γ, ξ) defined using auxiliary surfaces of the same genus. Then, up to flexibility, (M'_1, ξ'_1) and (M'_2, ξ'_2) are contactomorphic by a map isotopic to one that restricts to the identity on $M \setminus N(\Gamma)$ for some regular neighborhood $N(\Gamma)$ of Γ .

Proof. First, suppose all choices in the constructions of (M'_1, ξ'_1) and (M'_2, ξ'_2) are the same except for that of the vertically invariant collar of ∂M used to define ξ_h . Suppose $\xi_{h,1}$ and $\xi_{h,2}$ are the contact structures on M defined from two different collars. The connectedness of the space of such collars implies that $\xi_{h,1}$ and $\xi_{h,2}$ are isotopic by an isotopy stationary on ∂M . It follows that (M'_1, ξ'_1) and (M'_2, ξ'_2) are contactomorphic by a map isotopic to one that restricts to the identity on M, as desired. It therefore suffices to prove Theorem 3.3 in the case that (M'_1, ξ'_1) and (M'_2, ξ'_2) are defined using the same collar. We will assume below that this is the case. We will also continue to think of the contact structure Ξ_A as being completely determined by the arc configuration A. This is fine for the purpose of this proof: since any two such Ξ_A are related by flexibility and isotopy as in Lemma 2.31 and Remark 2.32, the contact preclosures formed from any two such Ξ_A are related as claimed in the theorem, assuming all other choices are the same.

Below, we prove Theorem 3.3 in the case that (M'_1, ξ'_1) and (M'_2, ξ'_2) are built using auxiliary surfaces with *isomorphic* arc configurations.

DEFINITION 3.4. Suppose A_1 and A_2 are arc configurations on F_1 and F_2 , and suppose the boundary components of each F_j have been ordered. We say that A_1 and A_2 are *isomorphic* if there is a diffeomorphism from (F_1, A_1) to (F_2, A_2) which respects these boundary orderings.

For k = 1, 2, suppose (M'_k, ξ'_k) is defined using the auxiliary surface F_k , the arc configuration \mathcal{A}_k , the neighborhoods $A(\Gamma)_k = \bigcup_i A_{i,k}$ and $B(\Gamma)_k = \bigcup_i B_{i,k}$, and the diffeomorphism h_k . For i = 1, ..., m, let B_i be an annular neighborhood of Γ_i containing $B_{i,1} \cup B_{i,2}$ on which the leaves of $(\partial M)_{\xi}$ are cocores with no singularities, and let $B(\Gamma) = \bigcup_i B_i$. Let us assume that \mathcal{A}_1 and \mathcal{A}_2 are isomorphic (where the boundary components of F_k are ordered according to h_k and the ordering of the components of Γ , as usual) by an isomorphism

$$g:(F_1,\mathcal{A}_1)\to(F_2,\mathcal{A}_2).$$

Note that g induces a canonical isotopy class of contactomorphisms

$$\tilde{g}: (F_1 \times [-1,1], \mathcal{Z}_{\mathcal{A}_1}) \to (F_2 \times [-1,1], \mathcal{Z}_{\mathcal{A}_2})$$

for which $h_2 \circ \tilde{g} \circ h_1^{-1}$ restricts to a diffeomorphism from $A_{i,1}$ to $A_{i,2}$ for $i = 1, \dots, m$. Let

$$\varphi_r: \partial M \to \partial M, r \in [0, 1],$$

be an isotopy supported in $B(\Gamma)$, such that $\varphi_0 = \text{id}$ and φ_1 restricts to the map

$$h_2 \circ \tilde{g} \circ h_1^{-1} : A(\Gamma)_1 \to A(\Gamma)_2.$$

Let

 $\varphi: M \to M$

be the diffeomorphism of M extending φ_1 defined as in (11). By construction, the characteristic foliations of ξ_{h_1} and $(\varphi_*)^{-1}(\xi_{h_2})$ on ∂M agree on $A(\Gamma)_1$ and outside of $B(\Gamma)$. Let ξ'_{h_1} be a contact structure obtained from ξ_{h_1} by flexibility such that

$$(\partial M)_{\xi'_{h_1}} = (\partial M)_{(\varphi_*)^{-1}(\xi_{h_2})}$$

and such that ξ'_{h_1} agrees with ξ_{h_1} on $A(\Gamma)_1 \times [-3, 0]$ and outside of $B(\Gamma) \times [-3, 0]$. The contact preclosure (M'_1, ξ''_1) constructed from ξ'_{h_1} is then related to (M'_1, ξ'_1) by flexibility.

To complete the proof of Theorem 3.3 in this case, it therefore suffices to show that (M'_1, ξ''_1) is contactomorphic to (M'_2, ξ'_2) by a map isotopic to one that restricts to the identity outside of $B(\Gamma) \times [-3, 0]$. For this, it suffices to show that (M, ξ'_{h_1}) is contactomorphic to (M, ξ_{h_2}) by a map isotopic to one which restricts to the identity outside of $B(\Gamma) \times [-3, 0]$, through maps which restrict to $h_2 \circ \tilde{g} \circ h_1^{-1}$ on $A(\Gamma)_1$. Indeed, a contactomorphism from (M, ξ'_{h_1}) to (M, ξ_{h_2}) of this form extends to the desired contactomorphism from (M'_1, ξ''_1) to (M'_2, ξ'_2) by the map \tilde{g} . Since $(\varphi_*)^{-1}(\xi_{h_2})$ is already contactomorphic to ξ_{h_2} by such a map (namely, $\varphi)$, it suffices to show that ξ'_{h_1} and $(\varphi_*)^{-1}(\xi_{h_2})$ are isotopic by an isotopy stationary on ∂M . To see this, let d_i be one of the boundary components of B_i . For each t, the multicurve $\bigcup_i (d_i \times \{t\})$ divides the characteristic foliations on $\partial M \times \{t\}$ induced by ξ'_{h_1} and $(\varphi_*)^{-1}(\xi_{h_2})$. Since these two contact structures induce the same characteristic foliations on ∂M and agree outside of $\partial M \times [-3, 0]$, Lemma 2.26 implies that ξ'_{h_1} and $(\varphi_*)^{-1}(\xi_{h_2})$ are isotopic by an isotopy stationary on ∂M (and outside of $\partial M \times [-3, 0]$), as desired.

It remains to prove Theorem 3.3 in the case that (M'_1, ξ'_1) and (M'_2, ξ'_2) are defined using auxiliary surfaces of the same genus with *nonisomorphic* arc configurations. For this, we will need a way of relating nonisomorphic configurations.



Figure 6. A standard arc configuration in a neighborhood of c.

DEFINITION 3.5. Suppose $\mathcal{A} = \{c, a_1, \ldots, a_m\}$ is an arc configuration on a surface F with ordered boundary components $\partial_1 F, \ldots, \partial_m F$, and suppose the arcs have been labeled so that a_i is the (unique) arc meeting $\partial_i F$. Suppose further that when c is traversed according to one of its two orientations, the arcs a_1, \ldots, a_m appear 'locally' to the left of c and in that cyclic order, as depicted in Figure 6. Such an arc configuration is called *standard*.

LEMMA 3.6. If A_1 and A_2 are standard arc configurations on surfaces F_1 and F_2 of the same genus and with the same number of boundary components, then A_1 and A_2 are isomorphic.

Proof. For k = 1, 2, let F'_k be the surface obtained by cutting F_k open along the curve and arcs in \mathcal{A}_k . The first condition in Definition 3.5 implies that F'_1 and F'_2 have the same genus and two boundary components. Moreover, one boundary component of F'_k is partitioned into segments labeled by elements of \mathcal{A}_k and boundary components of F_k ; the other is labeled solely by the curve in \mathcal{A}_k . The second condition in Definition 3.5 implies that there is an orientation-preserving homeomorphism from F'_1 to F'_2 which preserves this labeling (with respect to the natural bijections between elements of \mathcal{A}_1 and \mathcal{A}_2 and between components of ∂F_1 and ∂F_2). The lemma follows.

We now define two 'moves' on arc configurations: *addition* is the process of adding one arc to a configuration while *deletion* is the process of deleting arcs from a configuration until there is exactly one arc meeting each boundary component. It is easy to see that one can transform any arc configuration into a standard one via a finite sequence of these moves: one first uses deletion to obtain a configuration in which there is exactly one arc meeting each boundary component and then alternates additions with deletions to turn this configuration into a standard one, as illustrated in Figure 7. It follows that arbitrary arc configurations on surfaces of the same genus and with the same number of



Figure 7. Making an arc configuration standard through an alternating sequence of additions and deletions. The four boundary components are labeled as shown on the left.

boundary components can be made isomorphic after finitely many additions and deletions. Thus, to complete the proof of Theorem 3.3, it suffices to show that the theorem holds for contact preclosures built from arc configurations related by deletion (for an arc configuration with exactly one arc meeting each boundary component, an addition is the inverse of a deletion).

Fix an auxiliary surface F, the neighborhoods $A(\Gamma)$ and $B(\Gamma)$, and the diffeomorphism h. Let \mathcal{A}_1 be an arbitrary arc configuration on F and suppose \mathcal{A}_2 is obtained from \mathcal{A}_1 by deletion. The dividing set $\Gamma_{\mathcal{A}_2}$ is normally defined in terms of the boundary of a regular neighborhood of \mathcal{A}_2 , as in (10). Below, we will instead imagine $\Gamma_{\mathcal{A}_2}$ as coming from the boundary of a regular neighborhood of a certain graph \mathcal{A}'_1 on F,

$$\Gamma_{\mathcal{A}_2} = -\overline{(\partial N(\mathcal{A}_1') \smallsetminus \partial M)}.$$

This graph \mathcal{A}'_1 is obtained by retracting arcs of \mathcal{A}_1 a short distance into F until there is exactly one arc meeting each boundary component, as shown in Figure 8. We retract precisely those arcs that are deleted when forming \mathcal{A}_2 from \mathcal{A}_1 . Although \mathcal{A}'_1 is not an arc configuration in general, a neighborhood of this graph retracts onto a neighborhood of \mathcal{A}_2 , so these two ways of defining $\Gamma_{\mathcal{A}_2}$ result in isotopic dividing sets.

Below, we will use the notation $\xi_{h,k}$ in place of ξ_h to denote the contact structure on *M* defined using the map *h* and the arc configuration A_k . Our goal is to prove Theorem 3.3 for the contact preclosures

$$(M'_{1},\xi'_{1}) = \left(M\bigcup_{h} F \times [-1,1],\xi_{h,1} \cup \Xi_{\mathcal{A}_{1}}\right)$$
(12)

$$(M'_{2},\xi'_{2}) = \left(M\bigcup_{h} F \times [-1,1], \xi_{h,2} \cup \Xi_{\mathcal{A}_{2}}\right).$$
(13)

We start by specifying the data needed to define the contact structures $\xi_{h,j}$. As usual, we will assume that the dividing set of Ξ_{A_1} on the annulus $\partial_i F \times [-1, 1]$



Figure 8. Top: left, the arc configuration A_1 near a component $\partial_i F$; right, the corresponding portion of $(F \times [-1, 1], \mathcal{Z}_{A_1})$. Bottom: left, the graph A'_1 obtained from A_1 by retracting all but one of the arcs meeting each boundary component of F; right, the corresponding portion of $(F \times [-1, 1], \mathcal{Z}_{A_2})$.

consists of $2k_i$ cocores. Note that the dividing set of Ξ_{A_2} on each $\partial_i F \times [-1, 1]$ consists of just 2 cocores.

For i = 1, ..., m, let $D_i \subset int(A_i)$ be an annulus which intersects Γ_i in 2 cocores, and let $D(\Gamma) = \bigcup_i D_i$. Let $C_{i,1} \subset int(D_i)$ be an annulus which intersects Γ_i in $2k_i$ cocores. In particular, we require that one component of $D_i \cap \Gamma_i$ intersects $C_{i,1}$ in 1 cocore while the other intersects $C_{i,1}$ in $2k_i - 1$ cocores. Finally, let $C_{i,2} \subset int(D_i)$ be an annulus which intersects Γ_i in 2 cocores. See Figure 9 for an illustration of these annuli after straightening below. The annuli $C_{i,1}$ and $C_{i,2}$ will be used to define the contact structures $\xi_{h,1}$ and $\xi_{h,2}$ in the usual way while the D_i are auxiliary annuli that will be used to relate (M'_1, ξ'_1) and (M'_2, ξ'_2) .

Let \mathfrak{F} be a foliation of ∂M divided by Γ which contains the boundary components d_i^{\pm} of D_i as unions of leaves and agrees with $(\partial M)_{\xi}$ outside of $B(\Gamma)$. Let ξ' be the contact structure with $(\partial M)_{\xi'} = \mathfrak{F}$ obtained from ξ by flexibility. Note that the curves d_i^{\pm} are Legendrian with respect to ξ' . Choose a vertically invariant collar $\partial M \times (-\infty, 0]$ of ∂M with respect to ξ' . We can arrange (by choosing \mathfrak{F} more carefully) that ξ' is invariant in the $[-\epsilon, \epsilon]$ -direction for some small tubular neighborhoods $d_i^{\pm} \times [-\epsilon, \epsilon] \subset \partial M$ of the $d_i^{\pm} = d_i^{\pm} \times \{0\}$. This implies that the annuli (with corners) given by

$$E_i = (d_i^+ \times [-4, 0]_t) \cup (D_i \times \{-4\}_t) \cup (d_i^- \times [-4, 0]_t) \subset \partial M \times (-\infty, 0]_t$$

are convex.



Figure 9. A view from within B_i of the annuli D_i , $C_{i,1}$, and $C_{i,2}$ after straightening by φ_1 on the left and φ_2 on the right. In particular, $\varphi_1(C_{i,1}) = \varphi_2(C_{i,2}) = A_i$ and $\varphi_1(D_i) = \varphi_2(D_i)$.

We now construct the isotopies of ∂M which 'straighten out' the annuli $C_{i,1}$ and $C_{i,2}$. For k = 1, 2, let

$$\varphi_{r,k}: \partial M \to \partial M, r \in [0, 1],$$

be an isotopy supported in $B(\Gamma)$ such that $\varphi_{0,k} = \text{id}, \varphi_{1,k}(C_{i,k}) = A_i$, and h identifies the positive region on $\partial_i F \times [-1, 1]$ with respect to $\Xi_{\mathcal{A}_k}$ with the negative region on A_i determined by $\varphi_{1,k}(\Gamma)$. We will additionally require that $\varphi_{r,1} = \varphi_{r,2}$ in a neighborhood of the curves d_i^{\pm} and outside $D(\Gamma)$. Let

$$\varphi_k: M \to M$$

be the diffeomorphism of *M* extending $\varphi_{1,k}$ defined as in (11)), and define $\xi_{0,k} := (\varphi_k)_*(\xi')$. Note that $\xi_{0,1} = \xi_{0,2}$ outside of

$$\varphi_1(D(\Gamma) \times [-3,0]) = \varphi_2(D(\Gamma) \times [-3,0])$$
(14)

and in neighborhoods of the annuli $G_i = \varphi_1(E_i) = \varphi_2(E_i)$.

For k = 1, 2, let $\mathfrak{F}_{1,k}$ be a foliation of ∂M divided by $\varphi_k(\Gamma)$ which agrees on $A(\Gamma)$ with the image of the characteristic foliation $(\partial F \times [-1, 1])_{\Xi_{A_k}}$ under h and with $\mathfrak{F}_{0,k} := (\partial M)_{\xi_{0,k}}$ outside of $B(\Gamma)$. We will additionally require that $\mathfrak{F}_{1,1}$ and $\mathfrak{F}_{1,2}$ agree outside of $\varphi_1(D(\Gamma)) = \varphi_2(D(\Gamma))$. Let $\xi_{1,k}$ be the contact structure with $(\partial M)_{\xi_{1,k}} = \mathfrak{F}_{1,k}$ obtained from $\xi_{0,k}$ by flexibility, using the collar determined by the contact vector field $(\varphi_k)_*(\partial_t)$ for $\xi_{0,k}$. As usual, we let $\xi_{h,k} := \xi_{1,k}$. We can arrange that the annuli G_i are convex for both $\xi_{h,1}$ and $\xi_{h,2}$ and, moreover, that $\xi_{h,1}$ and $\xi_{h,2}$ agree in neighborhoods of these annuli and outside the neighborhood of



Figure 10. Left and right, the regions $\partial F \times [0, 1] \times [-1, 1]$ in $\mathbb{Z}_{\mathcal{A}_1}$ and $\mathbb{Z}_{\mathcal{A}_2}$.

 Γ in (14). Let $N(\Gamma)$ denote the component of $M \setminus \bigcup_i G_i$ containing Γ . Then, in particular, $\xi_{h,1} = \xi_{h,2}$ on $M \setminus N(\Gamma)$. We will record this fact as

$$(M \smallsetminus N(\Gamma), \xi_{h,1}) = (M \smallsetminus N(\Gamma), \xi_{h,2})$$
(15)

for later use.

We now prove Theorem 3.3 for the contact preclosures (M'_1, ξ'_1) and (M'_2, ξ'_2) formed from $\xi_{h,1}$ and $\xi_{h,2}$ as in (12) and (13). Since the convex surfaces

$$F \times \{t\} \subset (F \times [-1, 1], \Xi_{\mathcal{A}_1})$$

have collared Legendrian boundary, there is a collar $\partial F \times [0, 1] \subset F$ such that Ξ_{A_1} is invariant in the [0, 1]-direction on

$$\partial F \times [0, 1] \times [-1, 1] \subset F \times [-1, 1].$$

We can arrange that $\mathcal{Z}_{\mathcal{A}_2}$ is invariant in the same direction on the smaller neighborhood

$$\partial F \times [0, 1/2] \times [-1, 1] \subset F \times [-1, 1],$$

and that

$$((F \setminus (\partial F \times [0, 1])) \times [-1, 1], \Xi_{\mathcal{A}_1}) = ((F \setminus (\partial F \times [0, 1])) \times [-1, 1], \Xi_{\mathcal{A}_2}).$$
(16)

Note that the annuli

$$H_i = \partial_i F \times \{1\} \times [-1, 1]$$
 and $H'_i = \partial_i F \times \{1/2\} \times [-1, 1]$

are convex with collared Legendrian boundary with respect to both Ξ_{A_1} and Ξ_{A_2} . See Figure 10 for an illustration of these annuli.


Figure 11. Top: left, $(M, \xi_{h,1})$ on a portion of $B_i \times (-\infty, 0]$; right, the corresponding portion of (M', ξ'_1) gotten by attaching $(F \times [-1, 1], \mathcal{Z}_{\mathcal{A}_1})$. Bottom, the analogous pictures for $(M, \xi_{h,2})$ and (M', ξ'_2) . The lightly shaded regions on the top and bottom are meridional disks for the tori $T_{i,1}$ and $T_{i,2}$.

For k = 1, 2, the annuli G_i and H_i , together with two annuli in $\partial M'_k$, bound a solid torus $T_{i,k}$ in M'_k , as shown in Figure 11. Moreover, the complement $(M'_k \setminus \bigcup_i T_{i,k}, \xi'_k)$ is the union of the pieces in (15) and (16), which implies that

$$\left(M_1'\smallsetminus \bigcup_i T_{i,1},\xi_1'\right)=\left(M_2'\smallsetminus \bigcup_i T_{i,2},\xi_2'\right).$$

To prove Theorem 3.3, it therefore suffices to show that, after rounding corners, $(T_{i,1}, \xi'_1)$ is contactomorphic to $(T_{i,2}, \xi'_2)$, up to flexibility. But after rounding corners, $T_{i,1}$ and $T_{i,2}$ are solid tori with convex boundaries with dividing sets consisting of two parallel curves of slope -1, as shown in Figure 12 for $T_{i,2}$. As there is a unique tight solid torus with these boundary conditions, up to flexibility and contactomorphism, all that remains is to show that $(T_{i,1}, \xi'_1)$ and $(T_{i,2}, \xi'_2)$ are tight.



Figure 12. Left, the dividing set on $\partial T_{i,2}$. Right, the dividing set after rounding corners; it consists of two curves of slope -1 drawn in red and blue.

LEMMA 3.7. For k = 1, 2, the solid torus $(T_{i,k}, \xi'_k)$ is tight.

Proof. For k = 1, this follows from the fact that $(T_{i,1}, \xi'_1)$ can be embedded as a contact submanifold of some vertically invariant neighborhood of B_i in which the characteristic foliation on each copy of B_i agrees with that of $\xi_{h,1}$. To see that such a neighborhood is tight, note that it is related by flexibility to a vertically invariant neighborhood of B_i in which the characteristic foliation on each copy of B_i consists of cocores. The latter is, in some sense, a standard neighborhood of a dividing curve: it embeds as a neighborhood of any dividing curve on any convex surface in any contact manifold, and is therefore tight. The former neighborhood of B_i is thus tight as well since flexibility preserves tightness. To see that $(T_{i,1}, \xi'_1)$ embeds into such a neighborhood, note that $T_{i,1}$ is contained in a union

$$\left(B_i \times (-\infty, 0]_s \bigcup_h \partial F \times [0, 1]_s \times [-1, 1], \xi_{h, 1} \cup \Xi_{\mathcal{A}_1}\right),$$
(17)

where $\xi_{h,1}$ on $B_i \times (-\infty, 0]_s$ is invariant in the ∂_s -direction. Here, $\partial_s = (\varphi_1)_*(\partial_t)$, where ∂_t is the contact vector field for the vertically invariant collar $\partial M \times (-\infty, 0]$ for ξ' discussed earlier. Since Ξ_{A_1} is invariant in the $[0, 1]_s$ -direction, the union in (17) can be embedded in a vertically invariant neighborhood $B_i \times (-\infty, 1]_s$.

For k = 2, let $T'_{i,2}$ be the solid torus in M'_2 bounded by G_i , H'_i , and two annuli in $\partial M'_2$. By the reasoning above (considering Ξ_{A_2} rather than Ξ_{A_1}), the solid torus $(T'_{i,2}, \xi'_2)$ embeds into a vertically invariant neighborhood of B_i and is therefore tight. Note that $(T_{i,2}, \xi'_2)$ is obtained by gluing $(\partial_i F \times [1/2, 1] \times [-1, 1], \Xi_{A_2})$ to $(T'_{i,2}, \xi'_2)$ along H'_i . After rounding corners, the first piece is contactomorphic to the [1/2, 1]-invariant contact structure specified by the dividing set of Ξ_{A_2} on H'_i . Indeed, both are tight solid tori with convex boundaries and dividing sets consisting of two parallel curves of slope -1. It follows that $(T_{i,2}, \xi'_2)$ is contactomorphic to the torus obtained from $(T'_{i,2}, \xi'_2)$ by attaching a vertically invariant neighborhood of some portion of $\partial T'_{i,2}$. Thus, $(T_{i,2}, \xi'_2)$ is contactomorphic to $(T'_{i,2}, \xi'_2)$, and, hence, tight.

This concludes the proof of Theorem 3.3.

The corollary below follows easily from the proof of Theorem 3.3.

COROLLARY 3.8. Suppose (M, Γ, ξ_1) and (M, Γ, ξ_2) are related by flexibility, with contact preclosures (M'_1, ξ'_1) and (M'_2, ξ'_2) defined using auxiliary surfaces of the same genus. Then, up to flexibility, (M'_1, ξ'_1) and (M'_2, ξ'_2) are contactomorphic by a map smoothly isotopic to one that restricts to the identity on $M \setminus N(\Gamma)$ for some regular neighborhood $N(\Gamma)$ of Γ .

3.2. Contact closures and the invariants $\psi^g(M, \Gamma, \xi)$ and $\psi(M, \Gamma, \xi)$. Suppose (M', ξ') is a contact preclosure of (M, Γ, ξ) . As mentioned in Remark 3.2, the dividing set for ξ' consists of two parallel nonseparating curves on each component $\partial_{\pm}M'$ of $\partial M'$. One can therefore glue $\partial_{+}M'$ to $\partial_{-}M'$ (after applying flexibility, of course) by a map which identifies the positive region on $\partial_{+}M'$ with the negative region on $\partial_{-}M'$ to form a closed contact manifold $(Y, \bar{\xi})$ with a distinguished convex surface $R := \partial_{+}M' = -\partial_{-}M'$. We call a triple $(Y, R, \bar{\xi})$ formed in this way a *simple contact closure* of (M, Γ, ξ) . One might then attempt to define an invariant of ξ in terms of the contact invariant $\psi(Y, \bar{\xi})$. We do essentially this but, for naturality purposes, need the following slightly more involved notion of contact closure.

DEFINITION 3.9. A *contact closure* of (M, Γ, ξ) consists of a closure $\mathscr{D} = (Y, R, r, m)$ of (M, Γ) together with a contact structure $\overline{\xi}$ on Y such that

- (1) *m* restricts to a contact embedding of $(M \setminus N(\Gamma), \xi)$ into $(Y, \overline{\xi})$ for some regular neighborhood $N(\Gamma)$ of Γ ,
- (2) this restriction of m extends to a contactomorphism

$$(M',\xi') \to (Y \setminus \operatorname{int}(\operatorname{Im}(r)),\overline{\xi})$$

for some contact preclosure (M', ξ') of (M, Γ, ξ) .

(3) $r^*(\bar{\xi})$ is a contact structure on $R \times [-1, 1]$ obtained, via flexibility, from one that is invariant in the [-1, 1]-direction.

REMARK 3.10. Note that (M, Γ, ξ) admits a genus g contact closure for every $g \ge g(M, \Gamma)$.

REMARK 3.11. For a contact closure $(\mathcal{D}, \overline{\xi})$ as in Definition 3.9, the triple $(Y, r(R \times \{t\}), \overline{\xi})$ is a simple contact closure of (M, Γ, ξ) as described at the top for any $t \in [0, 1]$. In particular, each $r(R \times \{t\})$ is convex with negative region an annulus bounded by essential curves.

DEFINITION 3.12. A *marked* contact closure of (M, Γ, ξ) is a marked closure $\mathscr{D} = (Y, R, r, m, \eta)$ of (M, Γ) together with a contact structure $\overline{\xi}$ on Y such that $((Y, R, r, m), \overline{\xi})$ is a contact closure as in Definition 3.9 and $r(\eta \times \{0\})$ is dual to the core of the negative annular region of $r(R \times \{0\})$.

Suppose $(\mathcal{D} = (Y, R, r, m, \eta), \overline{\xi})$ is a marked contact closure of (M, Γ, ξ) of genus g. Let $r(R \times \{0\})_{\pm}$ denote the positive and negative regions of $r(R \times \{0\})$. It is a standard result in convex surface theory that

$$\langle c_1(\mathfrak{s}_{\tilde{\xi}}), r(R \times \{0\}) \rangle_Y = \chi(r(R \times \{0\})_+) - \chi(r(R \times \{0\})_-),$$

which is equal to 2 - 2g in this case since $r(R \times \{0\})_{-}$ is an annulus. It follows that

$$\langle c_1(\mathfrak{s}_{\bar{\xi}}), r(-R \times \{0\}) \rangle_{-Y} = 2 - 2g,$$

which implies that

$$\widecheck{HM}_{\bullet}(-Y,\mathfrak{s}_{\bar{\xi}};\Gamma_{-\eta})\subset \widecheck{HM}_{\bullet}(-Y|-R;\Gamma_{-\eta})=\underline{SHM}(-\mathscr{D}),$$

where $-\mathcal{D}$ is the corresponding marked closure of $(-M, -\Gamma)$. In particular,

$$\psi(Y,\bar{\xi}) \in \underline{SHM}(-\mathscr{D}).$$

This leads to the following definition.

DEFINITION 3.13. Given a marked contact closure $(\mathscr{D} = (Y, R, r, m, \eta), \overline{\xi})$ of (M, Γ, ξ) of genus $g \ge g(M, \Gamma)$, we define $\psi^g(M, \Gamma, \xi)$ to be the element of **SHM** $(-M, -\Gamma)$ determined by the equivalence class of

$$\psi(\mathscr{D},\bar{\xi}) := \psi(Y,\bar{\xi}) \in \underline{SHM}(-\mathscr{D}),$$

in the sense of Remark 2.8.

In Section 4, we will prove that $\psi^g(M, \Gamma, \xi)$ is well defined for each *g*, per the following theorem.

THEOREM 3.14. If $(\mathcal{D}, \overline{\xi})$ and $(\mathcal{D}', \overline{\xi}')$ are two marked contact closures of (M, Γ, ξ) of the same genus, then

$$\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}(\psi(\mathscr{D},\bar{\xi})) \doteq \psi(\mathscr{D}',\bar{\xi}').$$

Furthermore, we will show that for g sufficiently large, the contact elements $\psi^{g}(M, \Gamma, \xi)$ are equal, per the following theorem.

THEOREM 3.15. For every (M, Γ, ξ) , there is an integer $N(M, \Gamma, \xi)$ such that if $(\mathcal{D}, \overline{\xi})$ and $(\mathcal{D}', \overline{\xi}')$ are marked contact closures of (M, Γ, ξ) of genus at least $N(M, \Gamma, \xi)$, then

$$\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}(\psi(\mathscr{D},\bar{\xi})) \doteq \psi(\mathscr{D}',\bar{\xi}').$$

This theorem motivates the following definition.

DEFINITION 3.16. We define

$$\psi(M, \Gamma, \xi) := \psi^g(M, \Gamma, \xi) \in \mathbf{SHM}(-M, -\Gamma)$$

for any $g \ge N(M, \Gamma, \xi)$.

We will prove Theorems 3.14 and 3.15 in Section 4.

3.3. Properties. Below, we assume Theorems 3.14 and 3.15 hold in order to state and prove some basic properties about our contact invariants. We state these results for the invariants ψ^{g} . By Theorem 3.15, they also hold for the invariant ψ .

LEMMA 3.17. Suppose f is a contactomorphism from (M, Γ, ξ) to (M', Γ', ξ') . Then the induced map

SHM(f) : SHM(
$$-M, -\Gamma$$
) \rightarrow SHM($-M', -\Gamma'$)

sends $\psi^g(M, \Gamma, \xi)$ to $\psi^g(M', \Gamma', \xi')$.

Proof. Essentially, a contactomorphism gives rise to contactomorphic closures. More precisely, suppose $(\mathscr{D}', \bar{\xi}')$ is a marked contact closure of (M', Γ', ξ') . Since f is a contactomorphism, $(\mathscr{D}'_f, \bar{\xi}')$, as defined in (9), is a marked contact closure of (M, Γ, ξ) . According to the definition of <u>SHM</u>(f) in Subsection 2.2, it suffices to show that the identity map

$$\operatorname{id}_{-\mathscr{D}'_f,-\mathscr{D}'}: \underline{SHM}(-\mathscr{D}'_f) \to \underline{SHM}(-\mathscr{D}')$$

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sends $\psi(\mathscr{D}'_f, \overline{\xi}')$ to $\psi(\mathscr{D}', \overline{\xi}')$. But this is immediate since

$$\psi(\mathscr{D}'_f, \bar{\xi}') = \psi(Y', \bar{\xi}') = \psi(\mathscr{D}', \bar{\xi}').$$

Since the map $\underline{SHM}(f)$ only depends on the isotopy class of f, we have the following.

COROLLARY 3.18. Suppose (M, Γ, ξ) and (M, Γ, ξ') are sutured contact manifolds such that ξ and ξ' are isotopic through diffeomorphisms fixing Γ . Then $\psi^{g}(M, \Gamma, \xi) = \psi^{g}(M, \Gamma, \xi')$.

The following corollary should be thought of as saying that $\psi^g(M, \Gamma, \xi)$ is essentially independent of the particular choice of multicurve Γ dividing $(\partial M)_{\xi}$.

COROLLARY 3.19. Suppose (M, Γ, ξ) and (M, Γ', ξ) are sutured contact manifolds with the same underlying contact manifold but different dividing sets. Then there is a canonical isomorphism

$$\underline{\Psi}_{\xi,\Gamma,\Gamma'}: \underline{\mathbf{SHM}}(-M,-\Gamma) \to \underline{\mathbf{SHM}}(-M,-\Gamma')$$

sending $\psi^g(M, \Gamma, \xi)$ to $\psi^g(M, \Gamma', \xi)$.

Proof. Since the set of multicurves dividing $(\partial M)_{\xi}$ is connected, there is an isotopy

$$\varphi_r: \partial M \to \partial M, r \in [0, 1],$$

such that $\varphi_0 = \text{id}$, each φ_r preserves $(\partial M)_{\xi}$, and $\varphi_1(\Gamma_i) = \Gamma'_i$. Suppose $\partial M \times (-\infty, 0]$ is a vertically invariant collar of ∂M , and extend φ_r to a diffeomorphism

$$\varphi: M \to M$$

as in (11). It is easy to see, using Lemma 2.26, that ξ and $\varphi_*(\xi)$ are isotopic by an isotopy stationary on ∂M . It then follows from Lemma 3.17 and Corollary 3.18 that

$$\underline{\Psi}_{\xi,\Gamma,\Gamma'} := \underline{\mathbf{SHM}}(\varphi) : \underline{\mathbf{SHM}}(-M,-\Gamma) \to \underline{\mathbf{SHM}}(-M,-\Gamma')$$

sends $\psi^g(M, \Gamma, \xi)$ to $\psi^g(M, \Gamma', \xi)$. That this isomorphism is 'canonical' amounts to showing that it does not depend on the choices of φ or the collar (that it is well defined), and that

$$\underline{\Psi}_{\xi,\Gamma,\Gamma''} = \underline{\Psi}_{\xi,\Gamma',\Gamma''} \circ \underline{\Psi}_{\xi,\Gamma,\Gamma'}$$
(18)

for any three multicurves Γ , Γ' , Γ'' dividing $(\partial M)_{\xi}$. The connectedness of the space of such collars implies that φ is independent, up to isotopy stationary on ∂M ,

Σ

of the collar. Thus, **SHM**(φ) is independent of the collar. With that established, let us fix some collar, and suppose φ^1 and φ^2 are diffeomorphisms of M as defined above. The contractibility of the space of multicurves dividing $(\partial M)_{\xi}$ implies that φ^1 and φ^2 are isotopic. It follows that

$$\underline{\mathbf{SHM}}(\varphi^1) = \underline{\mathbf{SHM}}(\varphi^2).$$

Thus, $\underline{\Psi}_{\xi,\Gamma,\Gamma'}$ is well defined. Now, suppose φ and φ' are diffeomorphisms of M of the sort used to define the maps $\underline{\Psi}_{\xi,\Gamma,\Gamma'}$ and $\underline{\Psi}_{\xi,\Gamma',\Gamma''}$. The transitivity in (18) follows immediately from the fact that $\varphi'' := \varphi' \circ \varphi$ is a diffeomorphism of the sort used to define $\Psi_{\sharp \Gamma \Gamma''}$.

The corollary below indicates the invariance of ψ^{g} with respect to flexibility.

COROLLARY 3.20. Suppose (M, Γ, ξ) and (M, Γ, ξ') are related by flexibility. Then $\psi^{g}(M, \Gamma, \xi) = \psi^{g}(M, \Gamma, \xi').$

Proof. Suppose $(\mathcal{D} = (Y, R, r, m, \eta), \overline{\xi})$ is a marked contact closure of (M, Γ, ξ) . Corollary 3.8, together with Theorem 2.25, implies that $\overline{\xi}$ is isotopic to a contact structure $\overline{\xi}'$ for which $(\mathcal{D}, \overline{\xi}')$ is a marked contact closure of (M, Γ, ξ') . Then $\psi^{g}(M, \Gamma, \xi) = \psi^{g}(M, \Gamma, \xi')$ since $\psi(\mathscr{D}, \overline{\xi}) = \psi(\mathscr{D}, \overline{\xi}')$. \square

REMARK 3.21. The results above allow us to largely ignore, when dealing with the invariants ψ^g and ψ , the differences between contact structures related by flexibility or isotopy. Accordingly, we will frequently work on the level of dividing sets rather than characteristic foliations and will often think of dividing sets as *isotopy classes* of multicurves.

Note if (M, Γ, ξ) is overtwisted, then so is any contact closure $(\mathcal{D}, \overline{\xi})$ of (M, Γ, ξ) ξ). This implies that $\psi(\mathcal{D}, \overline{\xi}) = 0$, by Theorem 2.20. The theorem below follows immediately.

THEOREM 3.22. If (M, Γ, ξ) is overtwisted, then $\psi^g(M, \Gamma, \xi) = 0$.

Given a closed contact 3-manifold (Y, ξ) , let Y(p) denote the sutured contact manifold obtained from Y by removing a Darboux ball centered at p. It is not hard to show that there is a canonical isotopy class of contactomorphisms relating any two such manifolds for a given point p, justifying our notation. When it is not important to keep track of p, we will write Y(1) instead (as in the introduction), indicating that we have removed one Darboux ball. More generally, Y(n) will refer to the (contactomorphism type of the) sutured contact manifold obtained by removing *n* disjoint Darboux balls.

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We will prove the following in Section 4.

PROPOSITION 3.23. There is a morphism

$$F_p: \underline{\mathbf{SHM}}(-Y(p)) \to HM_{\bullet}(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$$

which sends $\psi^g(Y(p))$ to $\psi(Y, \xi) \otimes \mathbf{1}$, where $\mathbf{1}$ refers to the equivalence class of $1 \in \mathcal{R}$.

Since the monopole Floer invariant $\psi(Y, \xi)$ is nonzero for strongly symplectically fillable contact structures (see [21]), we have the following immediate corollary.

COROLLARY 3.24. If (Y, ξ) is strongly symplectically fillable, then $\psi^g(Y(p)) \neq 0$.

REMARK 3.25. The morphism in Proposition 3.23 can be thought of an analogue of the natural map in Heegaard Floer homology,

$$\tilde{H}\tilde{F}(-Y) \to HF^+(-Y),$$

which sends $c(Y, \xi)$ to $c^+(Y, \xi)$. Indeed, the modules comprising the systems <u>SHM</u>(-Y(p)) and $\widetilde{HM}_{\bullet}(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$ are isomorphic to $\widehat{HF}(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$ and $HF^+(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$, respectively.

Suppose K is a Legendrian knot in the interior of (M, Γ, ξ) and that (M', Γ', ξ') is the result of contact (+1)-surgery on K. We will prove the following in Section 4.

PROPOSITION 3.26. There is a morphism

 F_K : SHM $(-M, -\Gamma) \rightarrow$ SHM $(-M', -\Gamma')$

which sends $\psi^{g}(M, \Gamma, \xi)$ to $\psi^{g}(M', \Gamma', \xi')$.

3.4. Examples. Below, we compute the contact invariants of the Darboux ball and *product sutured contact handlebodies* more generally. As above, we state these results in terms of the invariants ψ^{g} , but they also hold for the invariant ψ by Theorem 3.15.

We start by constructing a genus g marked contact closure of the Darboux ball (B^3, S^1, ξ_{std}) for each

$$g \geqslant g(B^3, S^1) = 2$$



Figure 13. Left, $(D^2 \times [-1, 1], \xi_{D^2})$ with the negative region shaded. Right, the Darboux ball obtained by rounding corners.

(where the dividing set S^1 is a single equatorial curve on ∂B^3). Consider the [-1, 1]-invariant contact structure ξ_{D^2} on $D^2 \times [-1, 1]$ for which each $D^2 \times \{t\}$ is convex with collared Legendrian boundary and the dividing set on $D^2 \times \{1\}$ consists of a single properly embedded arc, as shown in Figure 13. The product sutured contact manifold $(D^2 \times [-1, 1], \partial D^2 \times \{0\}, \xi_{D^2})$ is contactomorphic to (B^3, S^1, ξ_{std}) after rounding corners. One advantage of thinking of the Darboux ball in this way is that, in doing so, we have, in effect, automatically perturbed ξ_{std} as required for forming contact preclosures.

Indeed, let *F* be a genus $g \ge 2$ surface with one boundary component, and let $\mathcal{A} = \{c, a\}$ be an arc configuration on *F* with a single arc. We may form a contact preclosure of the Darboux ball by gluing $(F \times [-1, 1], \mathcal{Z}_{\mathcal{A}})$ to $(D^2 \times [-1, 1], \xi_{D^2})$ according to a map

$$h: \partial F \times [-1, 1] \to \partial D^2 \times [-1, 1]$$

of the form $f \times id$ for some diffeomorphism $f : \partial F \to \partial D^2$, as in Figure 14. The result is a [-1, 1]-invariant contact structure ξ' on $M' = (D^2 \cup F) \times [-1, 1]$. Each $(D^2 \cup F) \times \{t\}$ is convex with negative region an annular neighborhood $A(c) \times \{t\}$ of the curve $c \times \{t\}$. To form a marked contact closure, we take $R = (D^2 \cup F)$ and glue $R \times [-1, 1]$, equipped with the [-1, 1]-invariant contact structure with negative region $A(c) \times \{t\}$ on each $R \times \{t\}$, to M' by the 'identity' maps

$$R \times \{\pm 1\} \to (D^2 \cup F) \times \{\mp 1\}.$$

Let η be a curve in R dual to the core of A(c). The resulting contact closure is $(\mathcal{D}, \overline{\xi})$ with

$$\mathscr{D} = ((D^2 \cup F) \times S^1, (D^2 \cup F), r, m, \eta),$$

where $\bar{\xi}$ is an S^1 -invariant contact structure for which the negative region on each fiber is a copy of A(c). Here, we are thinking of S^1 as the union of two copies of [-1, 1], and *r* and *m* as the obvious embeddings.



Figure 14. Left, the arc configuration \mathcal{A} on F with g(F) = 2. Middle, gluing $(F \times [-1, 1], \Xi_{\mathcal{A}})$ to $(D^2 \times [-1, 1], \xi_{D^2})$ with the negative region shaded. Right, $(D^2 \cup F)$ with the annulus A(c) shaded.

PROPOSITION 3.27. The invariant $\psi^g(B^3, S^1, \xi_{std})$ is a unit in <u>SHM</u> $(-B^3, -S^1) \cong \mathcal{R}$.

Proof. It follows from work of Niederkrüger and Wendl (see [**39**, Theorem 5]) that the contact manifold $((D^2 \cup F) \times S^1, \overline{\xi})$ is weakly symplectically fillable by some (W, ω) . According to their construction, we may choose the curve η so that $r(\eta \times \{0\})$ is, up to a scalar multiple, the Poincaré dual of $[\omega|_{(D^2 \cup F) \times S^1}]$. Since $\underline{SHM}(-\mathcal{D})$ is defined with respect to the local system $\Gamma_{-\eta}$, it follows from Theorem 2.21 that the contact class $\psi(\mathcal{D}, \overline{\xi})$ is a primitive element of $\underline{SHM}(-\mathcal{D})$. The proposition then follows from the fact that $\underline{SHM}(-\mathcal{D}) \cong \mathcal{R}$, by Proposition 2.18.

REMARK 3.28. The proof of Proposition 3.27 highlights the need for working with twisted coefficients: the contact structure $\bar{\xi}$ above is only weakly fillable and, indeed, Wendl shows in [52, Corollary 2] that its untwisted ECH contact invariant vanishes, from which it follows that $\psi(\mathcal{D}, \bar{\xi}) \in SHM(-\mathcal{D})$ vanishes as well.

Below, we compute the contact invariants of product manifolds built from general surfaces.

Let S be a genus k surface with $l \ge 1$ boundary components. Consider the [-1, 1]-invariant contact structure ξ_S on $S \times [-1, 1]$ for which each $S \times \{t\}$ is



Figure 15. Left, $(S \times [-1, 1], \xi_S)$, with negative region shaded, for k = 2, l = 3. Right, the convex boundary of the product sutured contact handlebody H(S) obtained by rounding corners.

convex with collared Legendrian boundary and the dividing set on $S \times \{1\}$ consists of k boundary parallel arcs, one for each component of ∂S , oriented in the same direction as the boundary. See Figure 15. Let H(S) be the *product sutured contact handlebody* of genus 2k + l - 1 obtained from $(S \times [-1, 1], \partial S \times \{0\}, \xi_S)$ by rounding corners. Note that H(S) is precisely the sort of contact handlebody that appears in the Heegaard splitting associated to an open book with page S.

We have the following generalization of Proposition 3.27.

PROPOSITION 3.29. The invariant $\psi^{g}(H(S))$ is a unit in <u>SHM</u> $(-H(S)) \cong \mathcal{R}$.

Proof. This proof is virtually identical to that of Proposition 3.27. We start by constructing a genus g marked contact closure of H(S) for every

$$g \ge g(H(S)) = \max\{2, k+l\} = \max\{2, g(S) + |\partial S|\}.$$
(19)

Let *F* be a surface with *l* boundary components, and let $\mathcal{A} = \{c, a_1, \ldots, a_l\}$ be an arc configuration on *F* with one arc meeting each boundary component. We form a genus k + l + g(F) - 1 contact preclosure of H(S) by gluing $(F \times [-1, 1], \mathcal{E}_{\mathcal{A}})$ to $(S \times [-1, 1], \xi_S)$ and then proceed as in the case of the Darboux ball to construct a marked contact closure of the form $(\mathcal{D}, \overline{\xi})$ with

$$\mathscr{D} = ((S \cup F) \times S^1, (S \cup F), r, m, \eta),$$

where $\bar{\xi}$ is an S¹-invariant contact structure for which the negative region on each fiber is a nonseparating annulus. These are exactly the same S¹-invariant

contact manifolds as were considered in the proof of Proposition 3.27. Thus, for an appropriate choice of η , the contact class $\psi(\mathscr{D}, \overline{\xi})$ is a unit in $\underline{SHM}(-\mathscr{D}) \cong \mathcal{R}$.

4. The well definedness of $\psi^g(M, \Gamma, \xi)$ and $\psi(M, \Gamma, \xi)$

We prove Theorems 3.14 and 3.15 in the next several subsections. Before proving Theorem 3.15, we use Subsection 4.2 to define maps on <u>SHM</u> associated to contact handle attachments and prove Propositions 3.26 and 3.23.

4.1. The well definedness of $\psi^g(M, \Gamma, \xi)$. We start by describing the isomorphism $\underline{\Psi}_{-\mathscr{D}_1, -\mathscr{D}_2}$ for $g(\mathscr{D}_1) = g(\mathscr{D}_2)$, as given in [1] but tailored slightly to our setting. We then prove Theorem 3.14, which implies that $\psi^g(M, \Gamma, \xi) \in \underline{SHM}(-M, -\Gamma)$ is well defined.

Suppose

$$(\mathscr{D}_1, \bar{\xi}_1) = ((Y_1, R_1, r_1, m_1, \eta_1), \bar{\xi}_1)$$
$$(\mathscr{D}_2, \bar{\xi}_2) = ((Y_2, R_2, r_2, m_2, \eta_2), \bar{\xi}_2)$$

are two marked contact closures of (M, Γ, ξ) of genus $g \ge g(M, \Gamma)$. To define $\Psi_{-\mathscr{D}_1, -\mathscr{D}_2}$, we first choose a contactomorphism

$$C: (Y_1 \setminus \operatorname{int}(\operatorname{Im}(r_1)), \overline{\xi}_1) \to (Y_2 \setminus \operatorname{int}(\operatorname{Im}(r_2)), \overline{\xi}_2)$$

which restricts to $m_2 \circ m_1^{-1}$ on $m_1(M \setminus N(\Gamma))$ for some neighborhood $N(\Gamma)$ of Γ . A contactomorphism of this form exists by Theorem 3.3. (Technically, Theorem 3.3 says that there is a contactomorphism of this form after applying flexibility to one of the complements above. However, we will ignore this point, as we can achieve the same effect by modifying one of the ξ_i via an arbitrarily small isotopy supported away from $m_i(M)$.) Let φ_{\pm} and φ be the diffeomorphisms defined by

$$\begin{split} \varphi_{\pm} &= (r_2^{\pm})^{-1} \circ C \circ r_1^{\pm} : R_1 \to R_2 \\ \varphi &= (\varphi_+)^{-1} \circ \varphi_- : R_1 \to R_1, \end{split}$$

where r_i^{\pm} is the composition

$$R_i \xrightarrow{\mathrm{id} \times \{\pm 1\}} R_i \times \{\pm 1\} \xrightarrow{r_i} Y_i$$

Remark 3.2 implies that the negative region of $\overline{\xi}_i$ on each $r_i(R_i \times \{t\})$ is of the form $r_i(A_i \times \{t\})$ for some annulus $A_i \subset R_i$. Since *C* is a contactomorphism, φ_{\pm}

sends A_1 to A_2 , which implies that φ sends A_1 to itself. Let

$$\psi: R_1 \to R_1$$

be any diffeomorphism such that ψ sends A_1 to itself and

$$(\varphi_-\circ\psi)(\eta_1)=\eta_2.$$

REMARK 4.1. The diffeomorphisms above are defined so that the triple $(Y_2, r_2(R_2 \times \{0\}), \eta_2)$ is diffeomorphic to that obtained from $(Y_1, r_1(R_1 \times \{0\}), \eta_1)$ by cutting the latter open along the surfaces $r_1(R_1 \times \{t\})$ and $r_1(R_1 \times \{t'\})$ for some t < 0 < t' and regluing by the maps $r_1 \circ \psi^{-1} \circ r_1^{-1}$ and $r_1 \circ (\varphi \circ \psi) \circ r_1^{-1}$. By expressing these maps as compositions of Dehn twists, we can realize this cutting and regluing operation via surgery. The isomorphism $\Psi_{-\mathscr{D}_1,-\mathscr{D}_2}$ is then defined in terms of 2-handle cobordism maps associated to such surgeries, as below.

Since $\varphi \circ \psi$ and ψ^{-1} fix the annulus A_1 , these diffeomorphisms are isotopic to compositions of Dehn twists about nonseparating curves $a_1, \ldots, a_m \subset R_1 \smallsetminus \partial A_1$,

$$arphi \circ \psi \sim D^{e_1}_{a_1} \circ \cdots \circ D^{e_n}_{a_n} \ \psi^{-1} \sim D^{e_{n+1}}_{a_{n+1}} \circ \cdots \circ D^{e_m}_{a_m}$$

Here D_{a_i} is a positive Dehn twist about a_i , and $e_i \in \{\pm 1\}$.

We next choose real numbers

$$-3/4 < t_m < \cdots < t_{n+1} < -1/4 < 1/4 < t_n < \cdots < t_1 < 3/4,$$

and pick some t'_i between t_i and the next greatest number in this list for every *i* such that $e_i = +1$. Let $(Y_1)_-$ be the 3-manifold obtained from Y_1 by performing (-1)-surgeries on the curves $r_1(a_i \times \{t_i\})$ for which $e_i = +1$, with respect to the framings induced by the surfaces $r_1(R_1 \times \{t_i\})$. Let X_- be the 4-manifold obtained by attaching (+1)-framed 2-handles to $(Y_1)_- \times [0, 1]$ along the curves $r_1(a_i \times \{t'_i\}) \times \{1\}$ for which $e_i = +1$. One boundary component of X_- is $-(Y_1)_-$. The other is canonically (up to isotopy) diffeomorphic to Y_1 since the (+1)-surgery on $r_1(a_i \times \{t'_i\})$ cancels the (-1)-surgery on $r_1(a_i \times \{t_i\})$. We may therefore view X_- as a cobordism from $(Y_1)_-$ to Y_1 . This cobordism gives rise to a map

$$\widetilde{HM}_{\bullet}(-X_{-}|-R_{1};\Gamma_{-\nu}):\widetilde{HM}_{\bullet}(-(Y_{1})_{-}|-R_{1};\Gamma_{-\eta_{1}})\rightarrow\widetilde{HM}_{\bullet}(-Y_{1}|-R_{1};\Gamma_{-\eta_{1}}),$$

where ν is the cylinder $\nu = r_1(\eta_1 \times \{0\}) \times [0, 1] \subset X_-$.

Similarly, let X_+ be the 4-manifold obtained from $(Y_1)_- \times [0, 1]$ by attaching (+1)-framed 2-handles along the curves $r_1(a_i \times \{t_i\}) \times \{1\}$ for which $e_i = -1$.

The boundary of X_+ is the union of $-(Y_1)_-$ with the 3-manifold $(Y_1)_+$ obtained from $(Y_1)_-$ by performing (+1)-surgeries on the curves $r_1(a_i \times \{t_i\})$ for which $e_i = -1$. Thus, X_+ gives rise to a map

$$\widecheck{H\!M}_{\bullet}(-X_{+}|-R_{1};\Gamma_{-\nu}):\widecheck{H\!M}_{\bullet}(-(Y_{1})_{-}|-R_{1};\Gamma_{-\eta_{1}})\rightarrow\widecheck{H\!M}_{\bullet}(-(Y_{1})_{+}|-R_{1};\Gamma_{-\eta_{1}}),$$

where $\nu = r_1(\eta_1 \times \{0\}) \times [0, 1] \subset X_+$ in this case. This map and the one above are shown to be isomorphisms in [1].

As suggested in Remark 4.1, there is a unique isotopy class of diffeomorphisms

$$\bar{C}:(Y_1)_+\to Y_2$$

which restricts to *C* on $Y_1 \setminus int(Im(r_1)) \subset (Y_1)_+$. Let

$$\Theta^{\bar{c}}: \widecheck{HM}_{\bullet}(-(Y_1)_+|-R_1; \Gamma_{-\eta_1}) \to \widecheck{HM}_{\bullet}(-Y_2|-R_2; \Gamma_{-\eta_2})$$

be the isomorphism on monopole Floer homology induced by \bar{C} . The map

$$\underline{\Psi}_{-\mathscr{D}_{1},-\mathscr{D}_{2}}: \widecheck{HM}_{\bullet}(-Y_{1}|-R_{1};\Gamma_{-\eta_{1}}) \to \widecheck{HM}_{\bullet}(-Y_{2}|-R_{2};\Gamma_{-\eta_{2}})$$

is defined to be the composition

$$\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2} = \Theta^{\bar{\mathcal{C}}} \circ \widecheck{HM}_{\bullet}(-X_+|-R_1;\Gamma_{-\nu}) \circ \widecheck{HM}_{\bullet}(-X_-|-R_1;\Gamma_{-\nu})^{-1}.$$

In [1], we proved that this map is independent of the choices made in its construction, up to multiplication by a unit in \mathcal{R} . Having defined $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$, we may now prove Theorem 3.14.

Proof of Theorem 3.14. It suffices to show that

$$\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}(\psi(\mathscr{D}_1,\bar{\xi}_1)) \doteq \psi(\mathscr{D}_2,\bar{\xi}_2)$$

for the marked contact closures $(\mathcal{D}_1, \overline{\xi}_1)$ and $(\mathcal{D}_2, \overline{\xi}_2)$ above. Note that the curves $r_1(a_i \times \{t_i\})$ and $r_1(a_i \times \{t_i'\})$ are *nonisolating* in $r_1(R_1 \times \{t_i\})$ and $r_1(R_1 \times \{t_i'\})$ since each component of $R_1 \setminus a_i$ intersects ∂A_1 . We can therefore make these curves Legendrian for all $i = 1, \ldots, m$ by isotoping $\overline{\xi}_1$ slightly, according to the *Legendrian Realization Principle* [18, 24]. In a slight abuse of notation, let us simply assume that these curves are Legendrian with respect to $\overline{\xi}_1$. The surface framings on these Legendrian curves agree with their contact framings since the curves are disjoint from the dividing sets on their respective surfaces (each a_i is disjoint from ∂A_1). In particular, we can arrange that the (± 1) -surgeries performed in defining $\underline{\Psi}_{-\mathcal{D}_1,-\mathcal{D}_2}$ are actually contact (± 1) -surgeries. Let $(\overline{\xi}_1)_{\pm}$ be the contact structures on $(Y_1)_{\pm}$ induced by these surgeries. Since (+1)-surgery on



$$\widecheck{HM}_{\bullet}(-X_{-}|-R_{1};\Gamma_{-\nu})(\psi((Y_{1})_{-},(\bar{\xi}_{1})_{-})) \doteq \psi(\mathscr{D}_{1},\bar{\xi}_{1})$$

by Corollary 2.23. The same corollary tells us that

$$\widetilde{HM}_{\bullet}(-X_{+}|-R_{1};\Gamma_{-\nu})(\psi((Y_{1})_{-},(\bar{\xi}_{1})_{-})) \doteq \psi((Y_{1})_{+},(\bar{\xi}_{1})_{+}).$$

Finally, we can arrange that the diffeomorphism \bar{C} is a contactomorphism, which implies

$$\Theta^{C}(\psi((Y_1)_+, (\bar{\xi}_1)_+)) \doteq \psi(\mathscr{D}_2, \bar{\xi}_2).$$

Putting these pieces together, we have that

$$\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}(\psi(\mathscr{D}_1,\bar{\xi}_1)) \doteq \psi(\mathscr{D}_2,\bar{\xi}_2).$$

completing the proof.

4.2. Contact handle attachment maps for <u>SHM</u>. In this subsection, we define maps on <u>SHM</u> associated to contact 0-, 1-, 2-, and 3-handle attachments and show that these maps preserve $\psi^g(M, \Gamma, \xi)$. We also construct the map F_p of Proposition 3.23, relating $\psi^g(Y(p))$ to the contact class $\psi(Y, \xi)$. We will use the 2-handle attachment maps in Subsection 4.3 to prove Theorem 3.15, which implies that the elements $\psi^g(M, \Gamma, \xi)$ are equal for large g and, hence, that $\psi(M, \Gamma, \xi)$ is well defined.

In the proofs that each of these maps are well defined, we will use the isomorphisms $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$ for arbitrary marked contact closures $(\mathscr{D}_1, \overline{\xi}_1)$ and $(\mathscr{D}_2, \overline{\xi}_2)$. In the case $g(\mathscr{D}_1) = g(\mathscr{D}_2)$ these are exactly as defined in Subsection 4.1, and so the reader will already see that the handle maps are well defined for closures of a fixed genus. However, when $g(\mathscr{D}_1) \neq g(\mathscr{D}_2)$ the maps $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$ involve certain 'splicing' cobordisms, whose precise description we postpone until Subsection 4.3 for readability; the reader will see that the proof in this case is identical.

4.2.1. 0-handle attachments. Attaching a contact 0-handle to (M, Γ, ξ) is equivalent to taking the disjoint union of (M, Γ, ξ) with the Darboux ball (B^3, S^1, ξ_{std}) . Let (M_0, Γ_0, ξ_0) be this disjoint union. We claim that every marked contact closure of (M_0, Γ_0, ξ_0) is a marked contact closure of (M, Γ, ξ) . To see this, think of the Darboux ball as the product sutured contact manifold $(D^2 \times [-1, 1], \partial D^2 \times \{0\}, \xi_{D^2})$, as in Subsection 3.4. Let F_0 be an auxiliary surface for (M_0, Γ_0, ξ_0) with arc configuration $\mathcal{A}_0 = \{c, a_1, \ldots, a_m\}$ so that a_1 is the unique arc

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meeting the boundary component $\partial_1 F_0$. We form a contact preclosure (M'_0, ξ'_0) of (M_0, Γ_0, ξ_0) by attaching $F_0 \times [-1, 1]$ to M_0 such that $\partial_1 F_0 \times [-1, 1]$ is glued to $\partial D^2 \times [-1, 1]$ by a map

$$h: \partial_1 F_0 \times [-1, 1] \rightarrow \partial D^2 \times [-1, 1]$$

of the form $f \times \text{id}$ for some diffeomorphism $f : \partial_1 F_0 \to \partial D^2$. Let A(c) denote the negative annular region on $\partial_+ M'_0$. Let R be a copy of $\partial_+ M'_0$. Let $(Y_0, \bar{\xi}_0)$ be the closed contact manifold obtained by gluing $R \times [-1, 1]$, equipped with the [-1, 1]-invariant contact structure with negative region $A(c) \times \{t\}$ on each $R \times \{t\}$, to M'_0 by diffeomorphisms

$$R \times \{\pm 1\} \rightarrow \partial_{\mp} M'_0$$

which identify dividing sets. Let η be a curve in *R* dual to the core of A(c). Then

$$(\mathscr{D}_0 = (Y_0, R, r, m_0, \eta), \xi_0)$$

is a marked contact closure of (M_0, Γ_0, ξ_0) , where *r* and m_0 are the obvious embeddings of $R \times [-1, 1]$ and M_0 into *Y*.

Note that (M'_0, ξ'_0) is a contact preclosure of (M, Γ, ξ) as well, formed from the auxiliary surface $F = F_0 \bigcup_f D^2$ and the arc configuration $\mathcal{A} = \{c, a_2, \ldots, a_m\}$. Thus,

$$(\mathscr{D} = (Y_0, R, r, m, \eta), \xi = \xi_0)$$

is a marked contact closure of (M, Γ, ξ) , where *m* is the restriction of m_0 to *M*. In particular, $\underline{SHM}(-\mathcal{D}) = \underline{SHM}(-\mathcal{D}_0)$. We define the 0-handle attachment map

$$\mathscr{H}_0: \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M_0, -\Gamma_0)$$

to be the morphism determined by the equivalence class of the identity map from $\underline{SHM}(-\mathcal{D})$ to $\underline{SHM}(-\mathcal{D}_0)$, which we will denote in this case by

$$\operatorname{id}_{-\mathscr{D},-\mathscr{D}_0}: \underline{SHM}(-\mathscr{D}) \to \underline{SHM}(-\mathscr{D}_0).$$

To prove that \mathscr{H}_0 is well defined, we need only show that if $(\mathscr{D}_0, \bar{\xi}_0)$ and $(\mathscr{D}'_0, \bar{\xi}'_0)$ are marked contact closures of (M_0, Γ_0, ξ_0) constructed as above, and $(\mathscr{D}, \bar{\xi})$ and $(\mathscr{D}', \bar{\xi}')$ are the corresponding marked contact closures of (M, Γ, ξ) , then the diagram



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Figure 16. Left, a portion of a vertical invariant neighborhood of ∂M near the disks D_- , $D_+ \subset \partial M$, whose boundaries are dotted. Middle, attaching the contact 1-handle. Right, the 1-handle attachment after rounding corners.

commutes, up to multiplication by a unit in \mathcal{R} . But this is clear: $\underline{\Psi}_{-\mathscr{D}_0,-\mathscr{D}'_0}$ is a composition of maps associated to 2-handle and splicing cobordisms, and $\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}$ can be defined via the exact same composition. Note that

$$\operatorname{id}_{-\mathscr{D},-\mathscr{D}_0}(\psi(\mathscr{D},\bar{\xi})) \doteq \psi(\mathscr{D}_0,\bar{\xi}_0)$$

since $\psi(\mathscr{D}, \overline{\xi}) = \psi(\mathscr{D}_0, \overline{\xi}_0)$ in <u>SHM</u> $(-\mathscr{D}) = \underline{SHM}(-\mathscr{D}_0)$. We therefore have the following.

PROPOSITION 4.2. $\mathscr{H}_0(\psi^g(M, \Gamma, \xi)) = \psi^g(M_0, \Gamma_0, \xi_0)$ for each $g \ge g(M, \Gamma)$.

4.2.2. 1-handle attachments. Suppose D_- and D_+ are disjoint embedded disks in ∂M which each intersect Γ in a single properly embedded arc. To attach a contact 1-handle to (M, Γ, ξ) along these disks, we glue $(D^2 \times [-1, 1], \xi_{D^2})$ to (M, Γ, ξ) by diffeomorphisms

$$D^2 \times \{-1\} \rightarrow D_-$$
 and $D^2 \times \{+1\} \rightarrow D_+$,

which preserve and reverse orientations, respectively, and identify dividing sets, and then we round corners, as illustrated in Figure 16. Let (M_1, Γ_1, ξ_1) be the resulting sutured contact manifold. As in the 0-handle case, we claim that every marked contact closure of (M_1, Γ_1, ξ_1) is also a marked contact closure of (M, Γ, ξ) .

The rough idea is that if F_1 is an auxiliary surface for (M_1, Γ_1) , then, in the corresponding preclosure M'_1 , the union of $F_1 \times [-1, 1]$ with the contact 1-handle is a product $F \times [-1, 1]$, where F is an auxiliary surface for (M, Γ) , so that M'_1 is also a preclosure of (M, Γ) . We make this precise as follows. Choose an auxiliary



Figure 17. Upper left, a portion of a vertically invariant neighborhood of ∂M near D_+ , D_- showing $A(\Gamma)$ and the perturbed dividing set. Upper right, the corresponding portions of M_1 and $A(\Gamma_1)$. Lower left, a portion of $F \times [-1, 1]$ with the negative regions on $F \times \{1\}$ and $\partial F \times [-1, 1]$ shaded. Lower right, the corresponding portion of $F_1 \times [-1, 1]$. The 3-balls $N \subset M'$ and $N_1 \subset M'_1$ are obtained by gluing the portions of $F \times [-1, 1]$ and $F_1 \times [-1, 1]$ shown here to the portions of M and M_1 shown here via the maps h and h_1 .

surface F_1 for (M_1, Γ_1) , a neighborhood $A(\Gamma_1)$, and a diffeomorphism

$$h_1: \partial F_1 \times [-1, 1] \to A(\Gamma_1).$$

We perturb ξ_1 as usual, so that, near the contact 1-handle, the resulting dividing set intersects $A(\Gamma_1)$ as shown in the upper right of Figure 17. We choose an arc configuration \mathcal{A}_1 on F_1 so that the negative region of $\Gamma_{\mathcal{A}_1}$ on a portion of the convex surface $F_1 \times \{1\} \subset (F_1 \times [-1, 1], \mathcal{Z}_{\mathcal{A}_1})$ glued near the 1-handle consists of neighborhoods of four arcs, as shown in the lower right of Figure 17. Let (M'_1, ξ'_1) denote the resulting contact preclosure of (M_1, Γ_1, ξ_1) .

Let γ_+ and γ_- be the arcs of ∂F_1 such that $\gamma_{\pm} \times \{1\} \subset \partial F_1 \times \{1\}$ are mapped to the contact 1-handle by h_1 . Let *F* be the surface obtained by attaching a twodimensional 1-handle to F_1 with feet at γ_{\pm} . Note that *F* is an auxiliary surface for (M, Γ) . We use it to construct a contact preclosure of (M, Γ, ξ) as follows. Let $A(\Gamma) \subset \partial M$ be a neighborhood of Γ which agrees with $A(\Gamma_1)$ outside of the attaching disks D_{\pm} . We perturb ξ so that the resulting dividing set agrees with that of the perturbed ξ_1 outside of D_{\pm} and is disjoint from $A(\Gamma)$ inside these disks, as shown in the upper left of Figure 17. By choosing h_1 more carefully to begin with, we can assume that it extends to a map

$$h: \partial F \times [-1, 1] \to A(\Gamma)$$

which agrees with h_1 away from $\gamma_{\pm} \times [-1, 1]$. Let \mathcal{A} be the arc configuration on F induced by \mathcal{A}_1 , and let (M', ξ') be the corresponding contact preclosure of (M, Γ, ξ) .

Let $N \subset M'$ be the 3-ball obtained by gluing the portion of $F \times [-1, 1]$ shown in Figure 17 to the portion of M shown there, and define $N_1 \subset M'_1$ analogously. Note that

$$(M' \setminus N, \xi') = (M'_1 \setminus N_1, \xi'_1).$$
(20)

We claim that, after rounding corners, N and N_1 are Darboux balls. This will imply that the identity map on the manifold in (20) extends (uniquely, up to isotopy) to a contactomorphism

$$(M', \xi') \to (M'_1, \xi'_1).$$

For the claim, it is enough to show that N and N_1 are tight (as there is a unique tight ball). But since N and N_1 only depend on ξ on a vertically invariant neighborhood of ∂M , it suffices to find some (M, Γ, ξ) such that all contact preclosures of (M, Γ, ξ) and (M_1, Γ_1, ξ_1) are tight. We can take (M, Γ, ξ) to be the Darboux ball (B^3, S^1, ξ_{std}) , in which case (M_1, Γ_1, ξ_1) is the product sutured contact handlebody H(S) for a surface S with genus 0 and 2 boundary components. It follows from the results in Subsections 3.4 and 4.1 that contact preclosures of both the Darboux ball and this handlebody are always tight, settling the claim.

Now, let *R* be a copy of $\partial_+ M'_1$, and let $(Y_1, \bar{\xi}_1)$ be the closed contact manifold obtained by gluing $R \times [-1, 1]$, equipped with the appropriate [-1, 1]-invariant contact structure, to M'_1 in the usual way. Consider the marked contact closure

$$(\mathscr{D}_1 = (Y_1, R, r, m_1, \eta), \xi_1)$$

of (M_1, Γ_1, ξ_1) , where η is an appropriately chosen curve on R, and r and m_1 are the obvious embeddings of $R \times [-1, 1]$ and M_1 into Y_1 . Since (M', ξ') and (M'_1, ξ'_1) are contactomorphic by the identity map outside of balls, we have that

$$(\mathscr{D} = (Y_1, R, r, m, \eta), \overline{\xi} = \overline{\xi}_1)$$

is a marked contact closure of (M, ξ) , where *m* is the restriction of m_1 to *M*. In particular, $\underline{SHM}(-\mathcal{D}) = \underline{SHM}(-\mathcal{D}_1)$. We define the 1-handle attachment map

$$\mathscr{H}_1 : \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M_1, -\Gamma_1)$$

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Figure 18. Left, a portion of a vertically invariant neighborhood of ∂M near $A(\gamma) \subset \partial M$, whose boundary is dotted. This portion is a neighborhood N of the Legendrian curve γ' . Middle, attaching the contact 2-handle. Right, the 2-handle attachment after rounding corners.

to be the morphism determined by the equivalence class of the identity map from $\underline{SHM}(-\mathcal{D})$ to $\underline{SHM}(-\mathcal{D}_1)$. The proof that \mathscr{H}_1 is well defined is then exactly as in the 0-handle case. Since the identity map $\mathrm{id}_{-\mathcal{D}_1-\mathcal{D}_1}$ sends $\psi(\mathcal{D}, \overline{\xi})$ to $\psi(\mathcal{D}_1, \overline{\xi}_1)$, we have the following.

PROPOSITION 4.3.
$$\mathscr{H}_1(\psi^g(M, \Gamma, \xi)) = \psi^g(M_1, \Gamma_1, \xi_1)$$
 for each $g \ge g(M, \Gamma)$.

4.2.3. 2-handle attachments. Suppose γ is an embedded curve in ∂M which intersects Γ in two points. Let $A(\gamma)$ be an annular neighborhood of γ intersecting Γ in two cocores. To attach a contact 2-handle to (M, Γ, ξ) along $A(\gamma)$, we glue $(D^2 \times [-1, 1], \xi_{D^2})$ to (M, Γ, ξ) by an orientation-reversing diffeomorphism

$$\partial D^2 \times [-1,1] \to A(\gamma)$$

which identifies positive regions with negative regions, and then round corners, as illustrated in Figure 18. Let (M_2, Γ_2, ξ_2) be the resulting sutured contact manifold.

Now, consider the sutured contact manifold (M_1, Γ_1, ξ_1) obtained from (M_2, Γ_2, ξ_2) by attaching a contact 1-handle along disks in the interiors of the $D^2 \times \{\pm 1\}$ boundary components of the contact 2-handle, as indicated in Figure 19, and let

$$\mathscr{H}_1 : \underline{\mathbf{SHM}}(-M_2, -\Gamma_2) \to \underline{\mathbf{SHM}}(-M_1, -\Gamma_1)$$

be the corresponding 1-handle attachment map, as defined in Subsubsection 4.2.2. It is easy to see that (M_1, Γ_1) is diffeomorphic to the sutured manifold obtained from (M, Γ) by performing ∂M -framed surgery on a copy γ' of γ in the interior of M. By the Legendrian Realization Principle, we can assume that γ'



Figure 19. Attaching a contact 1-handle to form M_1 . The circles on $D^2 \times \{\pm 1\}$ indicate where the feet of this handle are to be attached. The union of the 1-handle below with the portion of M_1 shown above is the solid torus N_1 .

is Legendrian in (M, Γ, ξ) since γ is nonisolating in ∂M . Moreover, since γ intersects Γ in exactly two points, the ∂M -framing on γ' is one more than its contact framing. Below, we argue that (M_1, Γ_1, ξ_1) is in fact contactomorphic (by a canonical isotopy class of contactomorphisms) to the result of contact (+1)-surgery on γ' .

To see this, let $N \subset M$ be the solid torus on the left in Figure 18 and let $N_1 \subset M_1$ be the solid torus obtained from N by attaching the 1- and 2-handles as indicated in Figures 18 and 19. After slight modification, N and N_1 can be made to have convex boundaries. Note that

$$(M \smallsetminus N, \Gamma, \xi) = (M_1 \smallsetminus N_1, \Gamma_1, \xi_1).$$
(21)

Furthermore, the identity map, restricted to $\partial M \setminus N = \partial M_1 \setminus N_1$, extends uniquely (up to isotopy) to a diffeomorphism

$$(\partial M, \Gamma) \to (\partial M_1, \Gamma_1).$$

It follows that the identity map on the manifold in (21) extends uniquely (up to isotopy) to a contactomorphism

$$(M \smallsetminus N', \Gamma, \xi) \rightarrow (M_1 \smallsetminus N'_1, \Gamma_1, \xi_1),$$

where $N' \subset int(N)$ is the solid torus with convex boundary obtained by removing a vertically invariant collar $\partial N \times [-\infty, 0)$ from N, and N'_1 is defined from N_1 analogously. In other words, there is a canonical contactomorphism (up to isotopy),

$$f:(M',\Gamma',\xi')\to(M_1,\Gamma_1,\xi_1),$$

where (M', Γ', ξ') is the contact manifold obtained from (M, Γ, ξ) by removing the solid torus neighborhood N' of γ' and gluing back in a solid torus contactomorphic to N'_1 according to the contact framing on γ' plus one. To show that this operation is actually a contact (+1)-surgery, all that remains is to show that N and N_1 are tight (as there is a unique tight solid torus with the given dividing set on its boundary).

Since *N* and *N*₁ only depend on ξ on a vertically invariant neighborhood of ∂M , it suffices to find some (M, Γ, ξ) such that both (M, Γ, ξ) and some sutured contact manifold obtained from (M, Γ, ξ) by attaching contact 2- and 1-handles as above are tight. We can take (M, Γ, ξ) to be the tight solid torus H(S) for a surface *S* with genus 0 and 2 boundary components. Etgü and Özbağcı show in [10, Example 3] that one can obtain the Darboux ball by attaching a contact 2-handle to this solid torus. We proved in Proposition 3.27 that any marked contact closure $(\mathcal{D}, \bar{\xi})$ of (B^3, S^1, ξ_{std}) has nonzero invariant $\psi(\mathcal{D}, \bar{\xi})$. This then implies, by the earlier results in this section, that any marked contact closure of the sutured contact manifold obtained from the Darboux ball by attaching a contact 1-handle also has nonzero invariant. The manifold resulting from this 1-handle attachment is therefore tight as well.

Thus, (M', Γ', ξ') is obtained from (M, Γ, ξ) via contact (+1)-surgery along the Legendrian curve γ' .

In order to define the 2-handle map \mathscr{H}_2 , we first define the morphism F_K in Proposition 3.26. Suppose

$$(\mathscr{D} = (Y, R, r, m, \eta), \xi)$$

is a marked contact closure of (M, Γ, ξ) . Let $(Y', \overline{\xi}')$ be the contact 3-manifold obtained from Y by performing contact (+1)-surgery on m(K) for some Legendrian knot $K \subset M$. Then

$$(\mathscr{D}' = (Y', R, r', m', \eta), \bar{\xi}')$$

is a contact closure of (M', Γ', ξ') , where r' is the map induced by r and m' is the embedding of M' into Y' induced by m. Let W be the 2-handle cobordism from Y to Y' corresponding to the above surgery. We define

$$F_K : \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M', -\Gamma')$$

to be the morphism induced by the map

$$HM_{\bullet}(-W|-R;\Gamma_{-\nu}):\underline{SHM}(-\mathscr{D})\to\underline{SHM}(-\mathscr{D}'),$$

where $\nu \subset W$ is the natural cylindrical cobordism from $r(\eta \times \{0\}) \subset Y$ to $r'(\eta \times \{0\}) \subset Y'$. To prove that F_K is well defined, we must show that the diagram

$$\underbrace{\underline{SHM}(-\mathscr{D}_{1}) \xrightarrow{HM_{\bullet}(-W_{1}|-R_{1};\Gamma_{-\nu_{1}})}}_{\underline{\Psi}_{-\mathscr{D}_{1},-\mathscr{D}_{2}}} \underbrace{\underline{SHM}(-\mathscr{D}_{1}')}_{\underline{\Psi}_{-\mathscr{D}_{1}',-\mathscr{D}_{2}'}} \\
\underbrace{\underline{SHM}(-\mathscr{D}_{2}) \xrightarrow{\Psi_{-\mathscr{D}_{1}',-\mathscr{D}_{2}'}}_{\underline{HM_{\bullet}(-W_{2}|-R_{2};\Gamma_{-\nu_{2}})}} \underbrace{\underline{SHM}(-\mathscr{D}_{2}')}_{\underline{SHM}(-\mathscr{D}_{2}')}$$

commutes, up to multiplication by a unit in \mathcal{R} , for any two marked contact closures $(\mathcal{D}_1, \bar{\xi}_1)$ and $(\mathcal{D}_2, \bar{\xi}_2)$ of (M, Γ, ξ) , where $(\mathcal{D}'_i, \bar{\xi}'_i)$ is the marked contact closure of (M', Γ', ξ') induced by $(\mathcal{D}_i, \bar{\xi}_i)$ and W_i is the 2-handle cobordism from Y_i to Y'_i . But this follows from the commutativity of the cobordisms used to define these maps: W_1 and W_2 are built by attaching 2-handles along curves in the regions $m_1(M)$ and $m_2(M)$, while the vertical isomorphisms are defined from cobordisms built by attaching 2-handles or splicing along tori outside of these regions. Since $\widetilde{HM}_{\bullet}(-W|-R; \Gamma_{-\nu})$ sends $\psi(\mathcal{D}, \bar{\xi})$ to $\psi(\mathcal{D}', \bar{\xi}')$, by Corollary 2.23, we have the following, which proves Proposition 3.26.

PROPOSITION 4.4. $F_K(\psi^g(M, \Gamma, \xi)) = \psi^g(M', \Gamma', \xi')$ for each $g \ge g(M, \Gamma)$.

We now define the 2-handle attachment map

$$\mathscr{H}_2: \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M_2, -\Gamma_2),$$

to be the composition of morphisms

$$\mathscr{H}_2 = \mathscr{H}_1^{-1} \circ \underline{\mathbf{SHM}}(f) \circ F_{\gamma'}.$$

That \mathscr{H}_2 is independent of γ' follows from the fact that any two such Legendrian realizations of γ are related by an ambient isotopy of M supported in N. Unpacking the composition above, we see that \mathscr{H}_2 may also be formulated as follows. Suppose $(\mathscr{D}, \overline{\xi})$ is a marked contact closure of (M, Γ, ξ) and let $(\mathscr{D}', \overline{\xi'})$ be the induced marked contact closure of the surgered manifold (M', Γ', ξ') . Then

$$(\mathscr{D}_2 = (Y', R', r', m_2, \eta'), \bar{\xi}_2 = \bar{\xi}')$$

is a marked contact closure of (M_2, Γ_2, ξ_2) , where m_2 is the restriction of $m' \circ f^{-1}$ to $M_2 \subset M_1$. Let

$$\operatorname{id}_{-\mathscr{D}',-\mathscr{D}_2}: \underline{SHM}(-\mathscr{D}') \to \underline{SHM}(-\mathscr{D}_2)$$

be the identity map on $\underline{SHM}(-\mathscr{D}') = \underline{SHM}(-\mathscr{D}_2)$. Then \mathscr{H}_2 is the morphism induced by the map

$$\operatorname{id}_{-\mathscr{D}',-\mathscr{D}_2} \circ HM_{\bullet}(-W|-R;\Gamma_{-\nu}) : \underline{SHM}(-\mathscr{D}) \to \underline{SHM}(-\mathscr{D}_2)$$

Note that Propositions 4.4 and 4.3 imply the following.

PROPOSITION 4.5.
$$\mathscr{H}_2(\psi^g(M, \Gamma, \xi)) = \psi^g(M_2, \Gamma_2, \xi_2)$$
 for each $g \ge g(M, \Gamma)$.

4.2.4. 3-handle attachments. Attaching a contact 3-handle to (M, Γ, ξ) amounts to gluing the Darboux ball to (M, Γ, ξ) along an S^2 boundary component of M with one dividing curve. Let (M_3, Γ_3, ξ_3) be the result of this gluing. We will first assume that ∂M is disconnected, so that M_3 has boundary. Let p be a point in M_3 in the interior of this Darboux ball. Then there is a canonical isotopy class of contactomorphisms

$$f: (M, \Gamma, \xi) \to (M', \Gamma', \xi'),$$

where (M', Γ', ξ') is the sutured contact manifold obtained by taking the contact connected sum of (M_3, Γ_3, ξ_3) with (B^3, S^1, ξ_{std}) at the point *p*. Let (M_0, Γ_0, ξ_0) be the disjoint union of (M_3, Γ_3, ξ_3) with (B^3, S^1, ξ_{std}) , and let

$$\mathscr{H}_0: \underline{\mathbf{SHM}}(-M_3, -\Gamma_3) \to \underline{\mathbf{SHM}}(-M_0, -\Gamma_0)$$

be the corresponding 0-handle attachment map, as defined in Subsubsection 4.2.1. Suppose

$$(\mathscr{D}_0 = (Y_0, R, r, m, \eta), \bar{\xi}_0)$$

is a marked contact closure of (M_0, Γ_0, ξ_0) . Then

$$(\mathscr{D}' = (Y', R, r, m', \eta), \bar{\xi}')$$

is a marked contact closure of (M', Γ', ξ') , where $(Y', \overline{\xi}')$ is the self contact connected sum obtained from $(Y_0, \overline{\xi}_0)$ by removing Darboux balls around m(p)and some point in $m(B^3) \subset Y_0$ and gluing in $S^2 \times I$, equipped with a tight, *I*invariant contact structure, and m' is the embedding of M' into Y' induced by m. In particular, $(Y', \bar{\xi}')$ is a contact connected sum of $(Y_0, \bar{\xi}_0)$ with the tight $S^1 \times S^2$. Now, there is a natural Stein 1-handle cobordism

$$(W, \omega) : (Y_0, \overline{\xi}_0) \to (Y', \overline{\xi}').$$

Let $\nu \subset W$ be a cylindrical cobordism from $r(\eta) \subset Y_0$ to $r(\eta) \subset Y'$. Then the map

$$\widecheck{HM}_{\bullet}(W|-R;\Gamma_{-\nu}):\underline{SHM}(-\mathscr{D}')\to\underline{SHM}(-\mathscr{D}_0)$$

sends $\psi(\mathcal{D}', \xi')$ to $\psi(\mathcal{D}_0, \xi_0)$, up to multiplication by a unit in \mathcal{R} , by Theorem 2.22. We define

$$F_{\#}: \underline{\mathbf{SHM}}(-M', -\Gamma') \to \underline{\mathbf{SHM}}(-M_0, -\Gamma_0)$$

to be the morphism determined by the equivalence class of this map. That $F_{\#}$ is well defined follows from similar considerations as before; namely, these Stein 1-handle cobordisms are attached along balls in the interiors of Y' and Y_0 and therefore commute with the 2-handle and splicing cobordisms used to define the isomorphisms in the systems **<u>SHM</u>** $(-M', -\Gamma')$ and **<u>SHM</u>(-M_0, -\Gamma_0). We define the 3-handle attachment map**

$$\mathscr{H}_3$$
: SHM $(-M, -\Gamma) \rightarrow$ SHM $(-M_3, -\Gamma_3)$

to be the composition

$$\mathscr{H}_3 = \mathscr{H}_0^{-1} \circ F_{\#} \circ \underline{\mathbf{SHM}}(f).$$

By Proposition 4.2, we have the following.

PROPOSITION 4.6.
$$\mathscr{H}_3(\psi^g(M, \Gamma, \xi)) = \psi^g(M_3, \Gamma_3, \xi_3)$$
 for each $g \ge g(M, \Gamma)$.

Suppose now that (Y, ξ) is a closed contact manifold, and let Y(p) be the sutured contact manifold obtained from (Y, ξ) by removing a Darboux ball around p. Below, we use similar ideas to construct the morphism

$$F_p: \underline{\mathbf{SHM}}(-Y(p)) \to HM_{\bullet}(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$$

in Proposition 3.23. Note that (Y, ξ) is obtained from Y(p) by a contact 3-handle attachment. Hence, there is a canonical isotopy class of contactomorphisms

$$f: Y(p) \to M$$
,

where *M* is the sutured contact manifold obtained as the contact connected sum of (Y, ξ) with (B^3, S^1, ξ_{std}) at the point *p*. Suppose

$$(\mathscr{D} = (Y_{B^3}, R, r, m, \eta), \overline{\xi})$$

is a marked contact closure of (B^3, S^1, ξ_{std}) . This naturally gives rise to a marked contact closure

$$(\mathscr{D}_M = (Y \# Y_{B^3}, R, r, m_M, \eta), \xi \# \xi)$$

of M, where m_M is the obvious extension of m. Let

$$(W,\omega):(Y,\xi)\sqcup(Y_{B^3},\bar{\xi})\to(Y\#Y_{B^3},\xi\#\bar{\xi})$$

be the natural Stein 1-handle cobordism, and let $\nu \subset W$ be a cylindrical cobordism from $r(\eta) \subset Y_{B^3}$ to $r(\eta) \subset Y \# Y_{B^3}$. The map

$$\widetilde{HM}_{\bullet}(W|-R;\Gamma_{-\nu}):\underline{SHM}(-\mathscr{D}_M)\to \widetilde{HM}_{\bullet}(-Y)\otimes_{\mathbb{Z}}\underline{SHM}(-\mathscr{D})$$
(22)

sends $\psi(\mathscr{D}_M, \xi \# \overline{\xi})$ to $\psi(Y, \xi) \otimes \psi(\mathscr{D}, \overline{\xi})$, up to multiplication by a unit in \mathcal{R} , by Theorem 2.22. Let

$$F_{\#}: \underline{\mathbf{SHM}}(-M) \to \widecheck{HM}_{\bullet}(-Y) \otimes_{\mathbb{Z}} \underline{\mathbf{SHM}}(-B^3, -S^1)$$

be the morphism determined by the equivalence class of this map. Since <u>SHM</u> $(-B^3, -S^1) \cong \mathcal{R}$, we may define F_p to be the composition

$$F_p = F_{\#} \circ \underline{\mathbf{SHM}}(f).$$

We then have the following, which proves Proposition 3.23.

PROPOSITION 4.7. $F_p(\psi^g(Y(p))) = \psi(Y,\xi) \otimes 1$ for each $g \ge g(Y(p)) = 2$. \Box

REMARK 4.8. For the map in (22), we are viewing W as a cobordism with one incoming and two outgoing boundary components. Reducible monopoles make defining maps associated to cobordisms with multiple incoming or outgoing boundary components difficult. This difficulty is typically overcome by restricting to nontorsion Spin^c structures on the boundary. In (22), however, we are not restricting the Spin^c structures on Y. Fortunately for us, Bloom has recently worked out the combinatorics needed to define maps on HM_{\bullet} associated to cobordisms with a single incoming boundary component and multiple outgoing boundary components [5]. **4.3.** The well definedness of $\psi(M, \Gamma, \xi)$. We start by describing the isomorphism $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$ in the case that $g(\mathscr{D}_1) \neq g(\mathscr{D}_2)$. The exposition here is tailored to the setting of contact closures and therefore differs slightly from that in [1]. We then use these isomorphisms and the contact handle attachment maps of Subsection 4.2 to prove Theorem 3.15, which implies that $\psi(M, \Gamma, \xi) \in \underline{SHM}(-M, -\Gamma)$ is well defined.

Suppose $(\mathcal{D}_1, \bar{\xi}_1)$ and $(\mathcal{D}_2, \bar{\xi}_2)$ are marked contact closures of (M, Γ, ξ) . Let us first consider the case in which

$$g(\mathscr{D}_2) = g(\mathscr{D}_1) + 1 = g + 1.$$

To define $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$, we first construct two additional marked contact closures as follows. Let *F* be an auxiliary surface such that the closed surface formed by gluing *F* to $R_+(\Gamma)$ has genus g + 1. Then *F* has genus at least two since \mathscr{D}_1 is formed from an auxiliary surface of genus at least one and $g(\mathscr{D}_1) = g$. It follows that there is an embedded subsurface $\Sigma \subset \operatorname{int}(F)$ of genus one with two boundary components $c_1, c_2 \subset \operatorname{int}(F)$ such that $F \smallsetminus \Sigma$ is connected. Let $\mathcal{A} = \{c, a_1, \ldots, a_m\}$ be an arc configuration on *F* contained in $F \backsim \Sigma$. Let (M', ξ') be the contact preclosure formed from *F*, \mathcal{A} , and some choices of $A(\Gamma)$ and

$$h: \partial F \times [-1, 1] \to A(\Gamma).$$

Note that the boundary components $\partial_{\pm}M'$ have genus g+1. As usual, the negative region on $\partial_{+}M'$ is an annular neighborhood A(c) of c, by Remark 3.2. Let R be a copy of $\partial_{+}M'$ and let $(Y, \overline{\xi})$ be the closed contact manifold obtained by gluing $R \times [-1, 1]$, equipped with the [-1, 1]-invariant contact structure with negative region $A(c) \times \{t\}$ on each $R \times \{t\}$, to M' by diffeomorphisms

$$R \times \{\pm 1\} \to \partial M'_{\pm} \tag{23}$$

which restrict to the 'identity' maps from $\Sigma \times \{\pm 1\} \subset R \times \{\pm 1\}$ to $\Sigma \times \{\mp 1\} \subset \partial M'_{\mp}$. Let η be a curve in R dual to the core of A(c) which restricts to a properly embedded arc on Σ . Then

$$(\mathscr{D} = (Y, R, r, m, \eta), \overline{\xi})$$

is a genus g + 1 marked contact closure of (M, Γ, ξ) , where r and m are the obvious embeddings of $R \times [-1, 1]$ and M into Y.

Let F' be the surface obtained from $\overline{F \setminus \Sigma}$ by gluing c_1 to c_2 via an orientationreversing diffeomorphism

$$f:c_1\to c_2$$

which sends $c_1 \cap \eta$ to $c_2 \cap \eta$, as shown in Figure 20. Since \mathcal{A} is disjoint from Σ , it descends to an arc configuration on F'. Let (M'', ξ'') be the contact preclosure



Figure 20. Left, a portion of the surface F with the region Σ shaded. Right, the surface F'. The arc configuration A is shown in red, intersecting η and η' along the curve c.

formed from F', A, $A(\Gamma)$, and h. Note that the boundary components $\partial M''_{\pm}$ are obtained from $\partial M'_{\pm}$ by removing $\Sigma \times \{\pm 1\}$ and gluing $c_1 \times \{\pm 1\}$ to $c_2 \times \{\pm 1\}$ by f. Let R' be a copy of $\partial M''_{\pm}$ and let $(Y', \overline{\xi}')$ be the closed contact manifold obtained by gluing $R' \times [-1, 1]$, equipped with the [-1, 1]-invariant contact structure with negative region $A(c) \times \{t\}$ on each $R \times \{t\}$, to M'' by the diffeomorphisms

$$R' \times \{\pm 1\} \rightarrow \partial M''_{\pm}$$

induced by those in (23). Then

$$(\mathscr{D}' = (Y', R', r', m', \eta'), \overline{\xi}')$$

is a genus g marked contact closure of (M, Γ, ξ) , where r' and m' are the embeddings naturally induced by r and m and $\eta' \subset R'$ is the curve induced by η .

The isomorphism $\underline{\Psi}_{-\mathscr{D}',-\mathscr{D}}$ is defined in terms of a *splicing* cobordism W, described below. Once we have defined this isomorphism, we define $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}$ as in (24). In defining W, the important observation is that the union of annuli

$$(c_i \times [-1, 1] \subset F \times [-1, 1] \subset M') \cup (c_i \times [-1, 1] \subset R \times [-1, 1])$$

is an embedded torus $T_i = c_i \times S^1 \subset Y$ for i = 1, 2. Together, these tori cut Y into pieces Y_M and Y_{Σ} with

$$-\partial Y_M = \partial Y_\Sigma = T_1 \cup T_2.$$

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Figure 21. Left, the saddle S. Right, a schematic of the splicing cobordism W.

In particular, Y_M is the piece that contains M and Y_{Σ} is the mapping torus of some diffeomorphism of Σ . Note that the closed manifold obtained from Y_M by gluing T_1 to T_2 by $f \times id$ is precisely Y', while the manifold obtained from Y_{Σ} in this way is a mapping torus $M(\Sigma')$ of some diffeomorphism of Σ' , where Σ' is the closed genus two surface obtained from Σ by gluing c_1 to c_2 by f. Let $\eta_{\Sigma'} \subset \Sigma'$ be the curve induced by η . The splicing cobordism

$$W: Y' \sqcup M(\Sigma') \to Y$$

is then defined by gluing the products $Y_M \times [0, 1]$ and $Y_{\Sigma} \times [0, 1]$ to $T_1 \times S$, where *S* is the saddle cobordism depicted in Figure 21. We glue these pieces along the 'horizontal' portions of their boundaries according to the schematic in that figure, making use of the map $f \times id$. This cobordism induces a map

$$\begin{split} \widetilde{HM}_{\bullet}(-W|-R';\,\Gamma_{-\nu}):\widetilde{HM}_{\bullet}(-Y'|-R';\,\Gamma_{-\eta'})\otimes_{\mathcal{R}}\widetilde{HM}_{\bullet}(-M(\Sigma')|-\Sigma';\,\Gamma_{-\eta_{\Sigma'}})\\ \to \widetilde{HM}_{\bullet}(-Y|-R;\,\Gamma_{-\eta}), \end{split}$$

where $\nu \subset W$ is a pair-of-pants cobordism from $\eta' \sqcup \eta_{\Sigma'}$ to η . We define

$$\underline{\Psi}_{-\mathscr{D}',-\mathscr{D}}(-)=\widecheck{HM}_{\bullet}(-W|-R';\Gamma_{-\nu})(-\otimes 1),$$

where 1 is a generator of $\widetilde{HM}_{\bullet}(-M(\Sigma')|-\Sigma'; \Gamma_{-\eta_{\Sigma'}}) \cong \mathcal{R}$. We then define

$$\underline{\Psi}_{-\mathscr{D}_{1,-}\mathscr{D}_{2}} = \underline{\Psi}_{-\mathscr{D}_{,-}\mathscr{D}_{2}} \circ \underline{\Psi}_{-\mathscr{D}_{',-}\mathscr{D}} \circ \underline{\Psi}_{-\mathscr{D}_{1,-}\mathscr{D}'}.$$
(24)

Here, $\underline{\Psi}_{-\mathscr{D},-\mathscr{D}_2}$ and $\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}'}$ are the maps defined in Subsection 4.1 for closures of the same genus.

In the case that $g(\mathcal{D}_2) = g(\mathcal{D}_1) - 1$, we define

$$\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2}=\underline{\Psi}_{-\mathscr{D}_2,-\mathscr{D}_1}^{-1}.$$

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For the general case, we choose a sequence $(\mathcal{D}^1, \bar{\xi}^1), \ldots, (\mathcal{D}^n, \bar{\xi}^n)$ of marked contact closures of (M, Γ, ξ) such that $(\mathcal{D}^1, \bar{\xi}^1) = (\mathcal{D}_1, \bar{\xi}_1), (\mathcal{D}^n, \bar{\xi}^n) = (\mathcal{D}_2, \bar{\xi}_2)$, and

 $|g(\mathcal{D}^{i+1}) - g(\mathcal{D}^i)| \leq 1$

for all $i = 1, \ldots, n - 1$. Then we define

$$\underline{\Psi}_{-\mathscr{D}_1,-\mathscr{D}_2} = \underline{\Psi}_{-\mathscr{D}^{n-1},-\mathscr{D}^n} \circ \cdots \circ \underline{\Psi}_{-\mathscr{D}^1,-\mathscr{D}^2}.$$

We proved in [1] that this map is independent of the choices made in its construction, up to multiplication by a unit in \mathcal{R} .

REMARK 4.9. It is clear from the description of this splicing cobordism that the maps $\Psi_{-\mathcal{D}_1,-\mathcal{D}_2}$ commute with the handle attachment maps $\mathcal{H}_i, 0 \leq i \leq 3$, defined in Subsection 4.2, even when the contact closures \mathcal{D}_1 and \mathcal{D}_2 do not have the same genus. Thus the maps \mathcal{H}_i are indeed well defined, as originally claimed.

Having constructed the maps $\Psi_{-\mathscr{D}_1,-\mathscr{D}_2}$, we can now use the 'existence' part of the relative Giroux correspondence between partial open books and sutured contact manifolds, together with our contact 2-handle attachment maps, to prove Theorem 3.15. Our discussion of this correspondence differs slightly in style but not in substance from the discussions in [11, 20].

DEFINITION 4.10. A partial open book is a quadruple (S, P, h, c), where:

- (1) S is a surface with nonempty boundary,
- (2) P is a subsurface of S,
- (3) $h: P \to S$ is an embedding which restricts to the identity on $\partial P \cap \partial S$,
- (4) $\mathbf{c} = \{c_1, \ldots, c_n\}$ is a set of disjoint, properly embedded arcs in *P* such that $S \setminus \mathbf{c}$ deformation retracts onto $S \setminus P$.

REMARK 4.11. The collection **c** of *basis* arcs for *P* is not typically recorded in the data of a partial open book. Usually, it is just required that *S* be obtained from $\overline{S \setminus P}$ by successive 1-handle attachments. The basis arcs specify a 1-handle decomposition of *P*.

Let H(S) be the product sutured contact handlebody obtained from $(S \times [-1, 1], \partial S \times \{0\}, \xi_S)$ by rounding corners, as defined in Subsection 3.4.

Let γ_i be the curve on $\partial H(S)$ corresponding to

$$(c_i \times \{1\}) \cup (\partial c_i \times [-1, 1]) \cup (h(c_i) \times \{-1\}) \subset \partial(S \times [-1, 1]).$$
(25)



Let $M(S, P, h, \mathbf{c})$ be the sutured contact manifold obtained from H(S) by attaching contact 2-handles along the curves in

$$\boldsymbol{\gamma}(h, \mathbf{c}) := \{\gamma_1, \dots, \gamma_n\}.$$
(26)

DEFINITION 4.12. A *partial open book decomposition* of (M, Γ, ξ) is a partial open book (S, P, h, \mathbf{c}) together with a contactomorphism

$$f: M(S, P, h, \mathbf{c}) \to (M, \Gamma, \xi).$$

The theorem below represents the 'existence' part of the relative Giroux correspondence between partial open books and sutured contact manifolds, proven by Honda *et al.* [20].

THEOREM 4.13. Every sutured contact manifold admits a partial open book decomposition.

DEFINITION 4.14. We define $N(M, \Gamma, \xi)$ to be the minimum of

$$\{g(H(S)) = \max\{2, g(S) + |\partial S|\}\}$$

over all partial open book decompositions (S, P, h, \mathbf{c}, f) of (M, Γ, ξ) . This is the constant in Theorem 3.15.

Proof of Theorem 3.15. Let $(\mathcal{D}, \overline{\xi})$ and $(\mathcal{D}', \overline{\xi}')$ be marked contact closures of (M, Γ, ξ) with genus at least $N(M, \Gamma, \xi)$. It suffices to show that

$$\underline{\Psi}_{-\mathscr{D},-\mathscr{D}'}(\psi(\mathscr{D},\bar{\xi})) \doteq \psi(\mathscr{D}',\bar{\xi}').$$
(27)

Suppose (S, P, h, \mathbf{c}, f) is a partial open book for (M, Γ, ξ) with $g(H(S)) = N(M, \Gamma, \xi)$. Let $(\mathcal{D}_f, \overline{\xi})$ and $(\mathcal{D}'_f, \overline{\xi}')$ be the induced marked contact closures of $M(S, P, h, \mathbf{c})$. Let $(\mathcal{D}_S, \overline{\xi}_S)$ and $(\mathcal{D}'_S, \overline{\xi}'_S)$ be marked contact closures of H(S) with

$$g(\mathscr{D}_S) = g(\mathscr{D}) = g(\mathscr{D}_f)$$
 and $g(\mathscr{D}'_S) = g(\mathscr{D}') = g(\mathscr{D}'_f).$ (28)

Since $M(S, P, h, \mathbf{c})$ is obtained from H(S) by attaching contact 2-handles, there is a morphism

$$\mathscr{H} : \underline{\mathbf{SHM}}(-H(S)) \to \underline{\mathbf{SHM}}(-M(S, P, h, \mathbf{c}))$$

obtained by composing the corresponding 2-handle morphisms defined in Subsubsection 4.2.3. Let

$$\begin{aligned} \mathscr{H}_{-\mathscr{D}_{S},-\mathscr{D}_{f}} &: \underline{SHM}(-\mathscr{D}_{S}) \to \underline{SHM}(-\mathscr{D}_{f}) \\ \mathscr{H}_{-\mathscr{D}_{S}',-\mathscr{D}_{f}'} &: \underline{SHM}(-\mathscr{D}_{S}') \to \underline{SHM}(-\mathscr{D}_{f}') \end{aligned}$$

be the induced (equivalence classes of) maps. Then the diagram

commutes, up to multiplication by a unit in \mathcal{R} . Furthermore, the genus equalities in (28), combined with Proposition 4.5, imply that

$$\begin{aligned} \mathscr{H}_{-\mathscr{D}_{S},-\mathscr{D}_{f}}(\psi(\mathscr{D}_{S},\bar{\xi}_{S})) &\doteq \psi(\mathscr{D}_{f},\bar{\xi}) \\ \mathscr{H}_{-\mathscr{D}_{S},-\mathscr{D}_{f}'}(\psi(\mathscr{D}_{S}',\bar{\xi}_{S}')) &\doteq \psi(\mathscr{D}_{f}',\bar{\xi}'). \end{aligned}$$

We know that

$$\underline{\Psi}_{-\mathscr{D}_{S},-\mathscr{D}'_{S}}(\psi(\mathscr{D}_{S},\bar{\xi}_{S})) \doteq \psi(\mathscr{D}'_{S},\bar{\xi}'_{S})$$

since these two contact classes generate

$$\underline{SHM}(-\mathscr{D}_S) \cong \underline{SHM}(-\mathscr{D}'_S) \cong \mathcal{R},$$

by Proposition 3.29. The commutativity of the leftmost square in the diagram above then implies that

$$\underline{\Psi}_{-\mathscr{D}_f,-\mathscr{D}'_f}(\psi(\mathscr{D}_f,\bar{\xi})) \doteq \psi(\mathscr{D}'_f,\bar{\xi}').$$

But this fact, combined with the commutativity of the rightmost square and the obvious equalities

implies (27).

In particular, Theorem 3.15 implies that the elements $\psi^g(M, \Gamma, \xi)$ are equal for all $g \ge N(M, \Gamma, \xi)$. As in Definition 3.16, we denote this common element by

$$\psi(M, \Gamma, \xi) \in \underline{\mathbf{SHM}}(-M, -\Gamma).$$

The following are then immediate corollaries of Propositions 4.2–4.7. We refer to those propositions for the notation.

COROLLARY 4.15. For i = 0, ..., 3, the morphism

$$\mathscr{H}_i : \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M_i, -\Gamma_i)$$

sends $\psi(M, \Gamma, \xi)$ to $\psi(M_i, \Gamma_i, \xi_i)$.

COROLLARY 4.16. The morphism $F_K : \underline{SHM}(-M, -\Gamma) \to \underline{SHM}(-M', -\Gamma')$

sends $\psi(M, \Gamma, \xi)$ to $\psi(M', \Gamma', \xi')$.

COROLLARY 4.17. The morphism

$$F_p: \underline{\mathbf{SHM}}(-Y(p)) \to HM_{\bullet}(-Y) \otimes_{\mathbb{Z}} \mathcal{R}$$

sends $\psi(Y(p))$ to $\psi(\xi) \otimes \mathbf{1}$.

The following corollary provides the inspiration for our construction in [2] of a contact invariant in sutured instanton homology.

COROLLARY 4.18. Suppose (S, P, h, \mathbf{c}, f) is a partial open book decomposition of (M, Γ, ξ) . Let

$$\mathscr{H} : \underline{\mathbf{SHM}}(-H(S)) \to \underline{\mathbf{SHM}}(-M(S, P, h, \mathbf{c}))$$

be the composition of contact 2-handle morphisms associated to c. Then

$$\psi(M, \Gamma, \xi) = \underline{\mathbf{SHM}}(f)(\mathscr{H}(1)) \in \underline{\mathbf{SHM}}(-M, -\Gamma),$$

where 1 is the generator of $\underline{SHM}(-H(S)) \cong \mathcal{R}$.

Suppose (M, Γ) is a *sutured submanifold* of (M', Γ') , as defined in [19]. Let ξ be a contact structure on $M' \setminus \operatorname{int}(M)$ with convex boundary and dividing set Γ on ∂M and Γ' on $\partial M'$. The sutured contact manifold $(M' \setminus \operatorname{int}(M), \Gamma \cup \Gamma', \xi')$ can be obtained from a vertically invariant contact structure on $\partial M \times I$ by attaching contact handles. Given a contact handle decomposition H of this sort, we define

$$\Phi_{\xi,H} : \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M', -\Gamma')$$

to be the corresponding composition of contact handle attachment maps, as in the introduction. Note that if ξ_M is a contact structure on M which agrees with ξ near ∂M , then

 $\Phi_{\xi,H}(\psi(M,\,\Gamma,\,\xi_M))=\psi(M',\,\Gamma',\,\xi_M\cup\xi)$

by Corollary 4.15.

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COROLLARY 4.19. If (M, Γ, ξ) embeds into (M', Γ', ξ') as a sutured contact submanifold and $\psi(M, \Gamma, \xi) = 0$, then $\psi(M', \Gamma', \xi') = 0$.

We can use Corollary 4.19 to prove the following slightly weaker version of Theorem 3.22 without relying on the fact that the monopole Floer invariant vanishes for overtwisted contact structures on closed 3-manifolds (Theorem 2.20).

LEMMA 4.20. If (M, Γ, ξ) is overtwisted, then $\psi(M, \Gamma, \xi) = 0$.

Proof. By Corollary 4.19, it is enough to show that a standard neighborhood (M, Γ, ξ) of an overtwisted disk has vanishing invariant. In [20], Honda *et al.* describe a partial open book for (S, P, h, \mathbf{c}) for (M, Γ, ξ) in which S is an annulus, **c** consists of a single boundary parallel arc c, and h(c) is another boundary parallel arc such that $c \cup h(c)$ is homotopic to a core curve α of the annulus S. As usual, we let γ be the curve on $\partial H(S)$ corresponding to

$$(c \times \{1\}) \cup (\partial c \times [-1, 1]) \cup (h(c) \times \{-1\}) \subset S \times [-1, 1].$$

Then $M(S, P, h, \mathbf{c})$ is obtained from H(S) by attaching a contact 2-handle along γ . Let

$$\mathscr{H} : \underline{\mathbf{SHM}}(-H(S)) \to \underline{\mathbf{SHM}}(-M(S, P, h, \mathbf{c}))$$

be the corresponding map. By Corollary 4.18, it suffices to show that $\mathcal{H} \equiv 0$. In fact, we will show that **SHM** $(-M(S, P, h, \mathbf{c})) = 0$.

To see this, let $\mathscr{D} = (Y, R, r, m, \eta)$ be any marked closure of H(S). Let γ' be a parallel copy of γ in the interior of Y and let Y' be the result of 0-surgery on $m(\gamma')$ with respect to the framing induced by $\partial H(S)$. By the construction of the contact 2-handle map in the previous section, we know that there is an embedding

$$m': M(S, P, h, \mathbf{c}) \to Y'$$

such that $\mathscr{D}' = (Y', R, r, m', \eta')$ is a marked closure of $M(S, P, h, \mathbf{c})$. Note that γ is isotopic to the curve $\alpha' \subset \partial H(S)$ corresponding to $\alpha \times \{1\} \subset S \times [-1, 1]$, by an isotopy which sends the $\partial H(S)$ -framing on γ to that of α' , as depicted in Figure 22. The image $m(\alpha')$ is isotopic to $r(a \times \{t\})$ for some embedded curve $a \subset R$ and any $t \in [0, 1]$, by an isotopy which sends the $\partial H(S)$ -framing on $m(\alpha')$ to the $r(R \times \{t\})$ -framing on $r(a \times \{t\})$. We can therefore view Y' as obtained from Y by 0-surgery on $r(a \times \{t\})$. Since $r(a \times \{t\})$ compresses $r(R \times \{t\})$, the surface $r(-R \times \{0\}) \subset -Y'$ is homologous to a surface of genus g(R) - 1. By the adjunction inequality in monopole Floer homology [27], this implies that $\widetilde{HM}_{\bullet}(-Y', \mathfrak{s}; \Gamma_n) = 0$ whenever

$$|\langle c_1(\mathfrak{s}), [r(-R \times \{0\})] \rangle| = 2g(R) - 2.$$



Figure 22. A partial open book for a standard neighborhood of an overtwisted disk. The shaded regions represent *P* and h(P). The two rightmost diagrams show the curves γ and α' in $\partial H(S)$, drawn as $(c \times \{1\}) \cup (\partial c \times [-1, 1]) \cup (h(c) \times \{-1\})$ and $\alpha \times \{1\}$ in $S \times [-1, 1]$.

In particular, <u>SHM</u>($-\mathscr{D}'$) = 0, which implies that <u>SHM</u>($-M(S, P, h, \mathbf{c})$) = 0.

REMARK 4.21. With a bit of work, one should similarly be able to use Corollary 4.19 to prove that if (M, Γ, ξ) has positive Giroux torsion, then $\psi(M, \Gamma, \xi) = 0$ in analogy with [14].

REMARK 4.22. In [19], Honda *et al.* define a map similar to $\Phi_{\xi,H}$ which depends only on ξ . We expect that our map $\Phi_{\xi,H}$ is likewise independent of H, as in Conjecture 1.7.

5. The bypass exact triangle

In this section, we work over the Novikov field $\mathcal{R}/2\mathcal{R} := \mathcal{R} \otimes_{\mathbb{Z}} \mathbb{Z}/2\mathbb{Z}$ in order to use the surgery exact triangle in monopole Floer homology (see Remark 2.19). The results of the previous sections, including the construction and invariance of $\psi(M, \Gamma, \xi)$ and the definition of the contact handle attachment maps, hold over $\mathcal{R}/2\mathcal{R}$ without modification.

Suppose (M, Γ) is a sutured manifold and $\alpha \subset \partial M$ is an arc which intersects Γ in three points, including both endpoints of α . A *bypass move* along α replaces Γ with a new set of sutures Γ' which differ from Γ in a neighborhood of α , as shown in Figure 23.

If Γ is the dividing set of a contact structure ξ on M, then a bypass move is achieved by attaching an actual *bypass* along α , as defined by Honda in [18]. In [40], Özbağcı observed that attaching a bypass along α is equivalent to first attaching a contact 1-handle along disks in ∂M centered at the endpoints of α and then attaching a contact 2-handle along the union β of α with an arc on the boundary of this 1-handle, as shown in Figure 24. There is a canonical isotopy



Figure 23. A bypass move along the arc α .



Figure 24. Performing a bypass move by attaching a contact 1-handle at the endpoints of α and a contact 2-handle along β .

class of diffeomorphisms between the resulting manifold and M which restrict to the identity outside a neighborhood of these handles. A bypass move along α thus gives rise to a morphism

$$\mathscr{H}_{\alpha}: \underline{\mathbf{SHM}}(-M, -\Gamma) \to \underline{\mathbf{SHM}}(-M, -\Gamma')$$

which is the composition of the corresponding contact 1- and 2-handle maps with the map induced by this isotopy class of diffeomorphisms. Corollary 4.15 implies the following.

PROPOSITION 5.1. Suppose (M, Γ', ξ') is obtained from (M, Γ, ξ) by attaching a bypass along α and pulling back the resulting contact structure to M by the canonical isotopy class of diffeomorphisms. Then the induced map \mathscr{H}_{α} sends $\psi(M, \Gamma, \xi)$ to $\psi(M, \Gamma', \xi')$.

Figure 25 shows a sequence of bypass moves, performed in some fixed neighborhood in ∂M , resulting in a 3-periodic sequence of sutures on M. Such a sequence of bypass moves is what Honda calls a *bypass triangle*. Work in progress of Honda shows that a bypass triangle gives rise to a *bypass exact triangle* in sutured (Heegaard) Floer homology. The main result of this section is the analogous result in the monopole Floer setting, per the theorem below.


Figure 25. The bypass triangle. Each picture shows the attaching arc used to achieve the next set of sutures in the triangle.

THEOREM 5.2. Suppose $\Gamma_1, \Gamma_2, \Gamma_3 \subset \partial M$ is the 3-periodic sequence of sutures resulting from successive bypass moves along arcs $\alpha_1, \alpha_2, \alpha_3$ as in Figure 25. Then the maps $\mathscr{H}_{\alpha_1}, \mathscr{H}_{\alpha_2}, \mathscr{H}_{\alpha_3}$ fit into an exact triangle



Proof. We will prove Theorem 5.2 by realizing the bypass exact triangle as the usual surgery exact triangle in monopole Floer homology.

Note that by enlarging our local picture slightly, we can think of the arcs α_1 , α_2 , α_3 as being arranged as in Figure 26 with respect to Γ_1 . We may therefore view

 (M, Γ_2) and (M, Γ_3) and (M, Γ_1)

as being obtained from (M, Γ_1) by attaching bypasses along the arcs

$$\alpha_1$$
 and α_1, α_2 and $\alpha_1, \alpha_2, \alpha_3$,

respectively. As described above, attaching a bypass along α_i amounts to attaching a contact 1-handle H_i along disks centered at the endpoints of α_i and then attaching a contact 2-handle along a curve β_i which extends α_i over the handle.



Figure 26. Another view of the arcs of attachment for the bypasses in the triangle. The suture drawn here is Γ_1 .



Figure 27. A view of (Z_1, γ_1) , obtained by attaching the contact 1-handles H_1, H_2 , H_3 to (M, Γ_1) . Middle, the attaching curves $\beta_1, \beta_2, \beta_3$ for the contact 2-handles. Right, the curves *a* and *b*.

Let (Z_1, γ_1) be the sutured manifold obtained by attaching all three H_1, H_2, H_3 to (M, Γ_1) , as in Figure 27. We will view $\beta_1, \beta_2, \beta_3$ as curves in ∂Z_1 , as shown in the figure. For i = 1, 2, 3, let (Z_{i+1}, γ_{i+1}) be the result of attaching a contact 2-handle to (Z_i, γ_i) along β_i . We thus have the following canonical (up to isotopy) identifications:

$$(Z_1, \gamma_1) \cong (M, \Gamma_1) \cup H_1 \cup H_2 \cup H_3$$

$$(Z_2, \gamma_2) \cong (M, \Gamma_2) \cup H_2 \cup H_3$$

$$(Z_3, \gamma_3) \cong (M, \Gamma_3) \cup H_3$$

$$(Z_4, \gamma_4) \cong (M, \Gamma_1).$$

Recall that contact 1-handle attachment has little effect on the level of closures. Specifically, if $\mathcal{D} = (Y, R, r, m, \eta)$ is a marked closure of sutured manifold after the 1-handle attachment, then there is a marked closure of the sutured manifold before the 1-handle attachment of the form $\mathscr{D}' = (Y, R, r, m', \eta)$. The corresponding 1-handle attachment morphism is induced by the identity map from $\underline{SHM}(-\mathscr{D}')$ to $\underline{SHM}(-\mathscr{D})$. We thus have canonical isomorphisms

SHM
$$(-Z_i, -\gamma_i) \cong \underline{SHM}(-M, -\Gamma_i),$$

for i = 1, 2, 3, 4, where the subscript of Γ_i is taken mod 3. In particular, <u>SHM</u> $(-Z_4, -\gamma_4)$ is canonically identified with <u>SHM</u> $(-Z_1, -\gamma_1)$. Therefore, to prove Theorem 5.2, it suffices to prove that there is an exact triangle



where \mathscr{H}_{β_i} is the morphism associated to contact 2-handle attachment along β_i .

Recall that on the level of closures, contact 2-handle attachment corresponds to surgery. Specifically, if $\mathcal{D}_i = (Y_i, R, r_i, m_i, \eta)$ is a marked closure of (Z_i, γ_i) , then there is a marked closure of (Z_{i+1}, γ_{i+1}) of the form $\mathcal{D}_{i+1} = (Y_{i+1}, R, r_{i+1}, m_{i+1}, \eta)$, where Y_{i+1} is the result of 0-surgery on $m_i(\beta_i)$ with respect to the (∂Z_i) framing, where β'_i is a pushoff of β_i into the interior of Z_i . The morphism \mathscr{H}_{β_i} is induced by the 2-handle cobordism map

$$F_i := HM_{\bullet}(-W_i | -R; \Gamma_{-\nu}) : \underline{SHM}(-\mathcal{D}_i) \to \underline{SHM}(-\mathcal{D}_{i+1})$$

corresponding to this surgery. So, to prove the exact triangle above, and, therefore, Theorem 5.2, it suffices to find a closure \mathcal{D}_1 of (Z_1, γ_1) such that the surgeries relating the $-Y_i$ are exactly those that one encounters in the usual surgery exact triangle in monopole Floer homology. More precisely, it suffices to arrange that:

- F_1 is the map associated to 0-surgery on some $K \subset -Y_1$,
- F_2 is the map associated to (-1)-surgery on a meridian $\mu_1 \subset -Y_2$ of K,
- F_3 is the map associated to (-1)-surgery on a meridian $\mu_2 \subset -Y_3$ of μ_1 .

Let $\mathscr{D} = (Y, R, r, m, \eta)$ be a marked closure of (Z_1, γ_1) . Let *a* and *b* be embedded curves in the positive and negative regions of ∂Z_1 as shown in Figure 27. Since neither curve intersects γ_1 , we can assume that *a* and *b* are contained in $r(R \times \{-1\})$ and $r(R \times \{+1\})$, respectively. Let Y_1 be the manifold



Figure 28. Top left, the curves $\beta'_1, \beta'_2, \beta'_3, a', b'$ in a neighborhood of $\partial Z_1 \subset Y$. Red indicates curves that have been surgered along. Top middle, sliding $\beta'_2 \subset Y_2$ over b' to produce β''_2 . Top right, showing that β''_2 bounds a meridional disk of β'_1 disjoint from the other surgery curves. Bottom left, $\beta'_3 \subset Y_3$. Bottom middle, sliding β'_3 over a' and β'_1 to produce β''_3 . Bottom right, showing that β''_3 bounds a meridional disk of β''_2 disjoint from the other surgery curves.

obtained from Y by performing (+1)-surgeries on pushoffs a' and b' of a and b into the interior of $r(R \times [-1, 1])$, with respect to their ∂Z_1 -framings. Then $\mathscr{D}_1 = (Y_1, R, r_1, m_1, \eta)$ is a marked closure of (Z_1, γ_1) , where m_1 is the embedding induced by m and r_1 is the canonical (up to isotopy) embedding induced by r. For ease of notation, we will think of the m_i as being inclusions, and simply write x for $m_i(x)$ for points $x \in Z_i$. In particular, W_i is the 2-handle cobordism corresponding to 0-surgery on $\beta'_i \subset Y_i$.

Recall that Y_2 is the result of 0-surgery on $\beta'_1 \subset Y_1$. Let β''_2 be the curve in Y_2 obtained by handlesliding β'_2 across the surgered curve b', as shown in the top middle of Figure 28. Note that the 0-framing on β'_2 corresponds to the (+1)-framing on β''_2 under this isotopy. We may therefore think of Y_3 as the result of (+1)-surgery on β''_2 and W_2 as the corresponding 2-handle cobordism. We

claim that β_2'' is a meridian of the surgered curve β_1' . This is apparent once we handleslide the surgered curve b' over the surgered curve β_1' , as shown in the top right of Figure 28.

Let β''_3 be the curve in Y_3 obtained by handlesliding β'_3 over the surgered curve a' and then over the surgered curve β'_1 , as shown in the bottom middle of Figure 28. The 0-framing on β'_3 corresponds to the (+1)-framing on β''_3 under this isotopy, so we may therefore think of $Y_4 \cong Y_1$ as the result of (+1)-surgery on β''_3 and W_3 as the corresponding 2-handle cobordism. We claim that β''_3 is a meridian of the surgered curve β''_2 . This is apparent once we handleslide the surgered curve a' over the surgered curve β''_2 , as shown in the bottom right of Figure 28, noting that we are free to isotope β''_2 through the 1-handle H_2 . It follows from these considerations that the maps F_1 , F_2 , F_3 are of the form described above for $K = \beta'_1$, $\mu_1 = \beta''_2$, $\mu_2 = \beta''_3$. This completes the proof of Theorem 5.2.

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Appendix A. Some facts about contact manifolds with boundary

In this appendix, we provide proofs of some of the results from Subsection 2.4. We repeat the statements of each result here for convenience.

PROPOSITION 2.28. If \mathfrak{F}_0 and \mathfrak{F}_1 are two characteristic foliations of ∂M divided by the same multicurve Γ , then there is a canonical bijection $f_{01} : \pi_0(\text{Cont}(M, \mathfrak{F}_0)) \to \pi_0(\text{Cont}(M, \mathfrak{F}_1)).$

Proof. Suppose ξ_0 is a contact structure on M with characteristic foliation $(\partial M)_{\xi_0} = \mathfrak{F}_0$. We claim that there exists a contact structure ξ_{01} on $\partial M \times [0, 1]$ such that:

- (1) the restriction $\xi_{01}|_{\partial M \times \{0\}} = \xi_0|_{\partial M}$,
- (2) the characteristic foliation $(\partial M \times \{1\})_{\xi_{01}} = \mathfrak{F}_1$,
- (3) each $\partial M \times \{t\}$ is convex and $\Gamma \times \{t\}$ divides $(\partial M \times \{t\})_{\xi_{01}}$,
- (4) ∂_t is a contact vector field near the boundary.

This is a relatively easy application of Theorem 2.25.

REMARK A.1. For any contact structure ξ_1 defined near ∂M with $(\partial M)_{\xi_1} = \mathfrak{F}_1$, we can arrange that ξ_{01} restricts to ξ_1 on $\partial M \times \{1\}$.

REMARK A.2. If \mathfrak{F}_0 agrees with \mathfrak{F}_1 on some open subset $A \subset \partial M$, then we can take ∂_t to be a contact vector field on $A \times [0, 1]$.

To define f_{01} , we first choose a vertically invariant collar neighborhood $\partial M \times (-\infty, 0]$ of $\partial M = \partial M \times \{0\}$ such that Γ is the dividing set associated to ∂_t . Let (M', ξ') be the contact manifold formed by gluing $(\partial M \times [0, 1], \xi_{01})$ to (M, ξ_0) along $\partial M \times \{0\}$ according to the identity map and the obvious collars. Let

$$\varphi: M' \to M$$

be the smooth map which is the identity outside of $\partial M \times (-\infty, 1]$ and sends (x, t) to (x, t - 1) for $(x, t) \in \partial M \times (-\infty, 1]$. We define $f_{01}(\xi_0)$ to be the contact structure $\xi_1 = \varphi_*(\xi')$. Note that $(\partial M)_{\xi_1} = \mathfrak{F}_1$, as desired.

REMARK A.3. We say that two contact structures ξ_0 and ξ_1 on *M* are *related by flexibility* if ξ_1 is obtained from ξ_0 in this way.

REMARK A.4. Note that $\xi_1 = \xi_0$ outside of $\partial M \times [-1, 0]$. If $\mathfrak{F}_0 = \mathfrak{F}_1$ on some open subset $A \subset \partial M$, then we can arrange, per Remark A.2, that $\xi_1 = \xi_0$ outside of $(\partial M \setminus A) \times [-1, 0]$.

Giroux's Uniqueness lemma (Lemma 2.26) implies that the contact structure ξ_{01} is unique, up to isotopy stationary on the boundary of $\partial M \times [0, 1]$. If follows that $f_{01}(\xi_0)$ is independent of ξ_{01} , up to isotopy stationary on ∂M . The fact that the space of vertically invariant collars as above is connected (in fact, contractible) implies that $f_{01}(\xi_0)$ is independent of the chosen collar. Finally, it is clear that if ξ_0 and ξ'_0 are isotopic, then so are $f_{01}(\xi_0)$ and $f_{01}(\xi'_0)$. Thus, f_{01} is well defined as a map from $\pi_0(\text{Cont}(M, \mathfrak{F}_0))$ to $\pi_0(\text{Cont}(M, \mathfrak{F}_1))$. It is clear that $f_{00} = \text{id}$. The transitivity $f_{02} = f_{12} \circ f_{01}$ is an easy application of Lemma 2.26. Note that these two relations imply that f_{01} is a bijection with inverse f_{10} .

LEMMA 2.29. Suppose *S* is a surface with boundary, and let Γ be a nonempty collection of oriented, disjoint, properly embedded curves and arcs on *S* such that $S \setminus \Gamma = S_+ \sqcup S_-$ with

$$\partial \overline{S}_+ = -\partial \overline{S}_- = \Gamma.$$

Then there exists a [-1, 1]-invariant contact structure on $S \times [-1, 1]$ for which each $S \times \{t\}$ is convex with collared Legendrian boundary $\partial S \times [0, 1] \times \{t\}$ and dividing set $\Gamma \times \{t\}$.



Proof. Let $(S' = S \cup -S, \Gamma' = \Gamma \cup -\Gamma)$ be the double of (S, Γ) . Then $S' \setminus \Gamma'$ is a disjoint union $S'_{+} \sqcup S'_{-}$ with

$$\partial \overline{S'}_{+} = -\partial \overline{S'}_{-} = \Gamma',$$

and it is not hard to construct a [-1, 1]-invariant contact structure ξ' on $S' \times [-1, 1]$ for which each $S' \times \{t\}$ is convex with dividing set $\Gamma' \times \{t\}$. Note that $\partial S \subset S'$ is *nonisolating*, meaning that each component of $S' \setminus \partial S$ intersects Γ' nontrivially. It follows that there is a singular foliation \mathfrak{F} of S' which is divided by Γ' and contains ∂S as a union of leaves (see [18]). In fact, we can assume that \mathfrak{F} restricts to a [0, 1]-invariant foliation on $\partial S \times [0, 1] \subset S \subset S'$. By Proposition 2.28, there exists a contact structure ξ' on $\partial S' \times [-1, 1]$ such that the characteristic foliation of ξ' on $S' \times \{1\}$ is equal to \mathfrak{F} . Changing notation, let us now denote by $(S' \times [-1, 1], \xi')$ a vertically invariant neighborhood of $S' \times \{1\}$. Then the restriction of ξ' to $S \times [-1, 1]$ is the desired contact structure.

LEMMA 2.31. Suppose ξ and ξ' are contact structures on $S \times [-1, 1]$ as in Lemma 2.29. Then, up to flexibility, ξ and ξ' are isotopic.

Proof. Let \mathfrak{F} and \mathfrak{F}' be the characteristic foliations on *S* induced by ξ and ξ' , and let *C* and *C'* be the collars of ∂S associated to ξ and ξ' . There exists an isotopy $\varphi_r : (S, \Gamma) \to (S, \Gamma), r \in [0, 1]$, such that $\varphi_0 = \text{id}$ and φ_1 sends the restriction of \mathfrak{F}' on *C'* to the restriction of \mathfrak{F} on *C*. Let $\mathfrak{F}'' = (\varphi_1)^{-1}(\mathfrak{F})$. Let ξ'' be the contact structure, obtained from ξ' by flexibility, whose characteristic foliation on $S \times \{\pm 1\}$ agrees with \mathfrak{F}'' . Note that we can apply Proposition 2.28 here, even though *S* has boundary, because \mathfrak{F}'' agrees with \mathfrak{F}' on *C'*. In fact, we may assume that ξ'' agrees with ξ' on *C'* × [-1, 1], as in Remark A.4. To prove the lemma, it suffices to show that ξ'' is isotopic to ξ . We do this in three steps.

The isotopy φ_r extends to an isotopy $\varphi_r \times \text{id}$ of $S \times [-1, 1]$. Let $\xi''' = (\varphi_1 \times \text{id})_*(\xi'')$. Then the characteristic foliation of ξ''' on $S \times [-1, 1]$ agrees with that of ξ . Moreover, ξ''' is [-1, 1]-invariant on $C \times [-1, 1]$. Thus, ξ''' is isotopic to a contact structure ξ'''' which agrees with ξ on $C \times [-1, 1]$ by a [-1, 1]-invariant isotopy which preserves the characteristic foliation on each $S \times \{t\}$. This is essentially Giroux's Reconstruction lemma [16]. Since each $S \times \{t\}$ is convex with dividing set $\Gamma \times \{t\}$ for both ξ'''' and ξ and the characteristic foliations of these two contact structures agree on $S \times \{\pm 1\}$, Lemma 2.26 asserts that ξ'''' and ξ are isotopic by an isotopy which is stationary on $S \times \{\pm 1\}$. In fact, we can take this isotopy to be stationary on $C \times [-1, 1]$ since ξ'''' and ξ agree there.

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