Which wets TiB_2 inoculant particles: Al or Al_3Ti ?

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Abstract

TiB_2 particles are proven effective nucleants of commercial purity aluminium, resulting in smaller grains and hence greater desired mechanical properties; however, there is uncertainty as to the mechanism by which it operates. Here we clarify what happens in the initial stages by computing the total Gibbs energy change associated with four possible nucleation mechanisms, each characterised by the termination of the $\text{TiB}_2(0001)$ substrate (Ti or B) and the solid that forms on it (Al or Al_3Ti). The appropriate solid//solid interfacial energies are derived from Density Functional Theory (DFT) calculations, while the bulk energies are derived from thermodynamic data, supplemented with strain energies calculated from DFT. Solid//liquid interfacial energies are estimated using simple models with parameters based on the literature and DFT calculations. The results suggest that the Ti termination of TiB_2 is more stable than the B termination in the melt, and that the direct formation of Al off a Ti-terminated TiB_2 substrate is the most favourable mechanism for the nucleation of Al rather than the previously proposed formation of a Al_3Ti interlayer. On the B termination of TiB_2 , Al formation is more stable for thick solid layers, but this is much more uncertain for thin solid layers where it is possible that Al_3Ti formation is more stable.

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1. Introduction

Aluminium alloys are widely used because they are light, strong, resistant to corrosion, and alumina is abundant in the Earth's crust. The mechanical properties of an aluminium component depend on its microstructure, including
5 the average size and shape of the grains, with smaller equiaxed grains generally leading to greater desirable properties such as improved yield strength and toughness due to the Hall-Petch effect [1, 2], together with reduced defects such as porosity[3] and hot tearing [4]. The addition of grain refiners to molten aluminium alloys is known to encourage significant reduction in grain size, and
10 is common industrial practice. However, the mechanism by these grain refiners nucleate α -Al is still disputed. Therefore, we require a fuller and more detailed understanding of the solidification process, starting with the system under study here: commercial purity (CP) aluminium together with its most commonly used grain refiner, the Al-Ti-B master alloy.

15 In the decades following the 1950s, grain refiner research focussed on observing results and trends, but did not study the mechanics of the process. However, in the 1990s several transmission electron microscope (TEM) experiments [5, 6, 7, 8, 9, 10] suggested that TiB_2 was the heterogeneous nucleant responsible for aluminium nucleation, by showing that thin ordered layers of
20 Al_3Ti -like structure (presumed to be $\text{Al}_3[\text{Ti,Ta}]$), had formed off the (0001) face of a TiB_2 particle in a glass formed from $\text{Al}_{85}\text{Ni}_5\text{Y}_8\text{Co}_2$. It is, however, unclear what the consequence of using this metallic glass rather than molten CP Al is.

Other experiments showed that, in addition to TiB_2 particles, excess solute
25 titanium in the melt was also needed for α -Al nucleation to occur [11]. The role played by this excess Ti is not yet completely understood, but it is thought that in addition to acting as a diffusion restrictor [12], Ti is needed to form Al_3Ti which nucleates off the TiB_2 forming a thin layer; Al then nucleates off the Al_3Ti layer [13]. The confidence in this Al_3Ti nucleation hypothesis is based
30 on Schumacher's TEM experiments [5, 6, 7, 8, 9, 10], backed up by more recent

TEM experiments by Fan [14], and by in situ synchrotron X-ray diffraction experiments [15], where diffraction peaks corresponding to plane separations similar to the those of bulk Al_3Ti were observed at the onset of aluminium solidification.

35 However, none of these experimental results are able to show the precise chemical composition of the nucleating layer. It is possible that what is being observed in these experiments is actually strained $\alpha\text{-Al}$, as suggested by Wang et al. [16], who proposed that the thin layers observed by Schumacher et al. [8] could be strained Al with the same interplanar separation as Al_3Ti . If this is
40 the true mechanism, then the role of the excess Ti could be to ensure that TiB_2 particles become Ti-terminated. Other recent static and molecular dynamics calculations using Density Functional Theory (DFT) [17, 16, 18, 19, 20, 21] show that solid Al adheres well to the Ti-terminated face of TiB_2 , and above the melting point liquid Al shows significant ordering close to this interface,
45 which suggests it is plausible that Al could nucleate without an Al_3Ti layer. None of these computational studies, however, address the role of excess Ti on the heterogeneous nucleation process.

In this paper, we calculate the total Gibbs energies before and after nucleation, of four hypothetical aluminium nucleation mechanisms:

50 where the two species separated by // denote the characteristic interfaces of the system. The planes parallel to the interfaces are $\text{TiB}_2(0001)$, Al (111) and Al_3Ti (112), and the parenthesized element denotes the termination of the $\text{TiB}_2(0001)$ surface. Using DFT and thermodynamic arguments we address the following questions:

55 1. What are the $\text{TiB}_2//\text{Al}$ interfacial energies if we account for the effects of

strain within the interfacial plane, and is the strain energy in the interfacial plane significant?

2. What are the $\text{TiB}_2//\text{Al}_3\text{Ti}$ interfacial energies (also accounting for the effects of interfacial strain) and how do they compare with those of $\text{TiB}_2//\text{Al}$?
3. Based on the evidence provided both here and in the literature, which of the four nucleation mechanisms is the most favourable?

2. Modelling the nucleation of aluminium

Heterogeneous nucleation is the initial formation of a new phase out of an original phase, occurring on a substrate. There are a wide range of methods for studying nucleation that are outside the purview of this paper. The interested reader is advised to follow the many good articles cited in this paper, as well as recent books on nucleation, such as that by Greer & Kelton [22]. The total change in Gibbs energy of this process, ΔG_T , is defined for an initial system of N_{melt} mole-atoms of melt (original phase), transforming into N_{solid} mole-atoms of solid (new phase) on a substrate, and $N_{melt'}$ mole-atoms of the remaining unsolidified melt, which might have a slightly different composition to the starting melt. If N_{solid} is small and completely wets, or wets with a very low contact angle, ΔG_T can be approximated by:

$$\Delta G_T = N_{solid}G_{solid} + N_{melt'}G_{melt'} - N_{melt}G_{melt} + \left[\gamma_{solid}^{melt'} + \gamma_{sub}^{solid} - \gamma_{sub}^{melt} \right] A_{sub} \quad (1)$$

where G_a is the bulk Gibbs energy per mole-atoms of species a , γ_b^a is the interfacial energy between species a and b , and A_{sub} is the area of active substrate. For the nucleation reaction considered in this study, the nucleating solid refers to either Al or Al_3Ti , the melt refers to liquid Al with some small amount of dissolved Ti, before (*melt*) and after (*melt'*) the formation of the solid, and the substrate refers to the surfaces $\text{TiB}_2(\text{Ti})$ or $\text{TiB}_2(\text{B})$. In this study we are primarily interested in the *difference in* ΔG_T between Al_3Ti and Al wetting, given

a particular TiB_2 substrate, and to see how these differences vary according to N_{solid} , X_{Ti} (or μ_{Ti}), and T (temperature).

The bulk Gibbs energies will be computed here using formulae from the literature [23, 24, 25, 26, 27], augmented with DFT to include strain effects. The three interfacial energies are determined as follows: γ_{sub}^{solid} is obtained from DFT calculations reported here; $\gamma_{solid}^{melt'}$ is estimated by interpolating between literature values for similar interfaces where the melt is pure liquid Al and Al-Ti liquid with $X_{Ti} = 0.0169$ at.%; γ_{sub}^{melt} is estimated through a simple model which involves the surface energies γ_{sub}^{vac} and γ_{melt}^{vac} , calculated using DFT and interpolated literature values respectively. We note that the values of N and A are interrelated and depend on assumptions made about the size and shape of the substrate, and of the solid that forms on the substrate.

Note that a central approximation of this paper is the use of static DFT energies – i.e. at 0K, and with no atomic vibrations. Nevertheless it is possible, with our calculated and literature values, to form an approximate expression for ΔG_T , especially since our main goal is a *comparison* between different mechanisms.

3. Bulk Gibbs Energies

The Gibbs energies of the bulk phases – the G 's in Eq. 1 – are calculated using the temperature dependent Gibbs energy expressions of the pure elements from the SGTE databases [23], which are empirical equations fitted to the numerous heating and cooling experiments in the literature. To calculate the Gibbs energy of the multi-component phases, the melt (liquid Al with dissolved Ti) and bulk Al_3Ti , the methods and parameters described in Kattner et al. [27] were used. We augment the solid Al and Al_3Ti Gibbs energies with the DFT 0K strain energies from the next section.

Furthermore, the bulk Gibbs energy of the melt is used to obtain the relationship between Ti concentration X_{Ti} and the chemical potential μ_{Ti} using $\mu_{Ti}^{melt} = \frac{\partial G^{melt}}{\partial N_{Ti}}$. This enables us to express the interfacial energies as a func-

tion of X_{Ti} , thereby making all the variables of Eq. 1 functions of the same Ti concentration variable. The chemical potential is a non-linear function of concentration, but locally the activity, $a_{Ti} = \exp\left(\frac{\mu_{Ti} - \mu_{Ti}^{bulk}}{RT}\right)$, is approximately linear in X_{Ti} : $a_{Ti} = \gamma_{Ti}X_{Ti}$, where γ_{Ti} (not to be confused with interfacial energy) is the activity coefficient, a dimensionless factor that is a function of X_{Ti} and temperature. The activity γ_{Ti} is calculated to be about $2.5 \times 10^{-5} - 3.0 \times 10^{-5}$ around the melting point of Al, at typical melt Ti concentrations of 0.001 to 0.01 at.%, which is broadly in line with that shown by Kostov et al. [28, 29].

4. Interfacial energies

4.1. DFT method

To calculate γ_{sub}^{solid} , γ_{sub}^{vac} (a term in our γ_{sub}^{melt} model), and the strain energies that make part of G_{solid} , DFT simulations were performed using the ABINIT code [30, 31, 32], which implements a planewave basis set. A planewave energy cutoff of 30 Ha was used with a PAW [33, 34, 35] auxiliary energy cutoff of 60 Ha. The PBE GGA functional [36] was used for the exchange and correlation energy. Monkhorst-Pack grids [37] of $6 \times 6 \times 6$ k points for bulk materials, and $6 \times 6 \times 1$ k points for slabs were employed. Band occupations were calculated using the cold smearing function of Marzari [38]. SCF calculations were converged to within 10^{-9} Ha, while atomic and geometric relaxations were carried out using the BFGS method [39] to within a tolerance of 5×10^{-5} Ha/Bohr per atom for the bulk and surface energy calculations, and 5×10^{-4} Ha/Bohr per atom for the larger, interface calculations. These parameters were chosen after performing extensive convergence tests, to ensure measurable quantities are converged to experimental accuracy: 0.01 J/m² for the TiB₂ surface energies, 0.05 J/m² for the Al surface energy and TiB₂//Al interfacial energies, 0.2 J/m² for the Al₃Ti surface energy, and 0.1 J/m² for the TiB₂//Al₃Ti and interfacial energies; 0.01 Å for lattice constants.

4.2. Strain effects

140 The solid forming on the substrate ($\text{TiB}_2(\text{Ti})$ or $\text{TiB}_2(\text{B})$) is assumed to be coherent and dislocation free, based on TEM images [8]. The solid is assumed to stretch to accommodate the strain, since the TiB_2 substrate is a very large particle (on the atomic scale) of a stiff ceramic [40]; the solid is a thin layer of a less stiff material [41, 42]. Although dislocations will form as the solid becomes
145 thicker, we are interested only in the region close to the interface i.e. the case when the strained phases are in equilibrium with the liquid and the substrate. Thus while we shall continue to refer to the solid as either Al or Al_3Ti , we shall really mean strained Al or strained Al_3Ti , which ensures that γ_{sub}^{solid} is correctly defined as being independent of the amount of solid. It is shown in section 5
150 that strain significantly alters the predicted interfacial energy.

4.3. Ti Chemical Potential

In order to calculate the surface and interfacial energies of TiB_2 by DFT, we require knowledge of the Ti chemical potential, μ_{Ti} , as there is an exchange of Ti between the melt and the nucleated solid, and possibly the substrate.
155 This chemical potential is sensitive to the Ti concentration in the melt (X_{Ti}). At thermodynamic equilibrium μ_{Ti} should be constant over the entire system; however, as solid forms our system will not be at equilibrium and μ_{Ti} will vary with position. As the Ti reservoir is the Ti in the melt, whose composition remains practically constant, we will take μ_{Ti} to be that for the melt. In the
160 systems we are studying, there are limitations that restrict the range of μ_{Ti} (and X_{Ti}), which are inferred from the stability of TiB_2 particles, which do not dissolve in the melt, and the absence of pure Ti or B [43]. Combining the μ_{Ti} and μ_{B} ranges with simple thermodynamic expressions of the formation of TiB_2 , leads to the expression, $\Delta G_F^{TiB_2} < \Delta\mu_{\text{Ti}} < 0$, where $\Delta\mu_{\text{Ti}} = \mu_{\text{Ti}} - \mu_{\text{Ti}}^{bulkTi}$, and
165 $\Delta G_F^{TiB_2}$ is the Gibbs energy of formation of TiB_2 (a detailed derivation was done by Han [43]).

4.4. Bulk calculations

A unit cell of each material in its most stable bulk phase at 0K was simulated: fcc for Al; face-centered tetragonal DO₂₂ for Al₃Ti [44]; hexagonal for TiB₂; hcp for Ti; and a 12-atom rhombohedral cell (α -phase) for B ¹. The strained bulk states were simulated using 6-layer unit cells of Al(111) and Al₃Ti(112), which were allowed to fully relax in the z-direction, but held fixed in the x - y plane to match the 'a' lattice parameter of TiB₂ (3.031 Å), thus matching the strained bulk state of Al and Al₃Ti present in the surface and interfacial slabs presented in section 4.5.

Table 1 shows the lattice constants obtained from the relaxed bulk simulations, which are later used to define certain cell dimensions in the surface and interface simulations. In addition, the table below shows the calculated energies of bulk formation for TiB₂ and Al₃Ti (those for Al, Ti and B are zero by definition), and the strained forms of Al and Al₃Ti.

The lattice constants agree closely with experiment, with all errors being less than 0.05 Å, and many being less than 0.01 Å. The formation energies of relaxed TiB₂ and Al₃Ti are also close to the experimental values. Table 1 shows that strained Al and Al₃Ti have significantly higher energies than their relaxed counterparts, and that the strain induced on the solid to match the TiB₂ substrate is greater for Al₃Ti than for Al: their bulk strain energies are: $\Delta G_{strain}^{Al} = +2.2$ kJ/mol-atoms and $\Delta G_{strain}^{Al_3Ti} = +16$ kJ/mol-atoms. This significant difference in strain energy is likely caused by Al₃Ti having a tetragonal structure rather than a regular fcc one like Al, which has two important consequences: firstly, the first Al₃Ti (112) plane, unlike Al (111), does not exactly align with the perfect hexagonal structure of TiB₂(0001); secondly, whilst the Al (111) planes are

¹ α -B is not quite the B ground state, but it is used because it is much simpler than the real ground state, the β -phase (~ 105 atoms per unit cell) whilst the difference in energy per atom between α -B and β -B is very small. Recent DFT calculations [45] found the difference in energy per atom between α -B and β -B to be only 0.29 kJ/mol, which would make less than 0.01 J/m² difference to the final interfacial energies.

Phase	Lattice constant (Å)		Formation energy (kJ/mol)	
	calculated	experimental	calculated relaxed/strained	experimental relaxed
Al	a = 4.051	a = 4.0496 [46]	0/+2.2	-
Ti	a = 2.933 c = 4.657	a = 2.9506 [46] c = 4.6835	0	-
B	a = 5.049	a = 5.064 [47]	0	-
Al ₃ Ti	a = 3.853 c = 8.632	a = 3.8537 [48] c = 8.5839	-155/-90	-150 [44]
TiB ₂	a = 3.0314 c = 3.2228	a = 3.0236 [40] c = 3.2204	-310	-322 [49]

Table 1: The lattice constants and formation energies obtained from bulk calculations at 0 K and prior experiments.

vertically aligned, repeating every three planes, the Al₃Ti (112) planes lean at about 5 degrees from the vertical. Subsequently, fixing the Al₃Ti (112) planes to conform to TiB₂(0001) results in compression of some of the atoms in the plane and extra induced strain to straighten the slab.

It is important to note that by using 0K strain energies we have neglected differences in the strain that might arise due to thermal expansion and compositional disorder [27], instead assuming the ideal lattice occupancies in the DFT cells. The 0K strain energies will be used with the temperature-dependent relaxed bulk energies for Al and Al₃Ti derived in section 3. This should not significantly affect the main results, since the experimentally determined lattice expansion coefficients for Al and TiB₂ [50, 40] and the theoretically determined values for Al₃Ti [51] show that going from 0K to the melting temperature of Al would result in fairly small reductions in lattice mismatch for both Al (111) (~ +5.5% to +4.2%) and Al₃Ti (112) (~ +11.2% to +10.7% and +4.7% to +4.6%). Furthermore, the Al mismatch, already lower than the Al₃Ti mismatch at 0K, is reduced by a greater amount at the Al melting point, hence the main result of this paper, that TiB₂(Ti)//Al is the favoured nucleation mechanism, would

likely be reinforced if thermal expansion was taken into account.

210 4.5. Surface and interfacial energy calculations

The following single material surface slabs were simulated: Al(111), strained Al(111), Al₃Ti(112), strained Al₃Ti(112), TiB₂(Ti), and TiB₂(B). The supercells for TiB₂(Ti) and TiB₂(B) were seven layer slabs, containing 10 and 11 atoms respectively (the same as simulated by Han [43]), while the Al and Al₃Ti
215 supercells were six layer slabs, containing 6 and 24 atoms respectively (the Al₃Ti supercells contain 4 atoms per layer, as each layer must have 1 Ti atom for every 3 Al atoms). The strained Al and Al₃Ti supercells differ from their relaxed counterparts by having the cell parameters in the plane of the interfaces fixed to match those of the TiB₂ slabs.

220 Four interfacial supercells were simulated, each a slab containing seven layers of TiB₂ adhered to six layers of strained solid, Al (111) or Al₃Ti (112). Hence a 16 atom TiB₂(Ti)//Al, a 17 atom TiB₂(B)//Al, a 64 atom TiB₂(Ti)//Al, and a 68 atom TiB₂(B)//Al₃Ti supercell were simulated.

The vacuum added to each surface and interface supercell was least 13 Å
225 thick, sufficient to prevent interaction between periodic images. The number of layers of each material was tested for convergence to ensure a good representation of the bulk material, while still remaining small enough for a full accuracy run: seven layers of TiB₂, six layers of Al, six layers of Al₃Ti, and six Al layers' worth of vacuum were found to converge γ to 0.05 J/m² for TiB₂//Al and 0.2
230 J/m² for TiB₂//Al₃Ti (these are conservative estimates), while the difference in γ between systems, which is more important, converged even more tightly.

The surface and interfacial energies are calculated by the common method of subtracting away appropriate amounts of bulk energy, dividing by the area, and then, for interface systems, subtracting any excess surface energy[52] . For
235 example, the interfacial energy calculated from the TiB₂(Ti)//Al slab is:

$$\gamma_{TiB_2(Ti)}^{Al} = \frac{1}{A} (E^{slab} - \{3\mu_{TiB_2}^{bulk} + \mu_{Ti}^{slab} + 6\mu_{Al}^{bulk}\}) - \{\gamma_{TiB_2(Ti)}^{vac} + \gamma_{Al}^{vac}\}2)$$

The μ_{Ti} term is needed because the TiB₂(Ti) substrate in the supercell does not

Solid surface	Relaxed σ (Jm ⁻²)		Strained σ (Jm ⁻²)
	This work	Previous work	This work
Al (111)	0.82	0.939[53]	0.96
Al ₃ Ti (112)	0.97	0.92[54]	1.08

Table 2: Relaxed and strained surface energies of the solid, Al and Al₃Ti, calculated from our slab simulations, compared with other simulation results.

contain a whole number of TiB₂ units (this is discussed in Han’s TiB₂ surface study [43]). Thus γ for all systems involving a TiB₂ substrate are functions of μ_{Ti} , and are thus expressed as a range, going from minimum μ_{Ti} to maximum μ_{Ti} .

4.6. Surface and interfacial energy results

The surface energies of TiB₂, $\gamma_{TiB_2(Ti)}^{vac}$ and $\gamma_{TiB_2(B)}^{vac}$, were calculated to be 5.47 – 2.23 J/m² and 2.99 – 6.23 J/m² respectively, which is in very close agreement with Han’s results [43]. The surface energies of relaxed and strained Al and Al₃Ti are shown in table 2.

It is interesting to note that, although the surface energy of strained Al is less than that of strained Al₃Ti, (strained to achieve coherency with a TiB₂ substrate that is), compared to its relaxed counterpart, the strain seems to have a greater comparative effect on Al than on Al₃Ti, which is the reverse trend to what was seen for the bulk energy discussed in the previous section.

Our calculated interfacial energies are shown in table 3, and plotted in figure 1 (the plot treats the strained bulk as the reference system). Note that the negative values of interfacial energies shown in these tables and graphs are actually unphysical, but we have kept them to help the reader fully see and compare each plot.

Our values for TiB₂(Ti)//Al and TiB₂(B)//Al are in close agreement with those from previous simulations [17], while there are no published interface calculations for the Al₃Ti systems that we are aware of. As explained in section 2, the use of the strained bulk energies to calculate the interfacial energy makes

System	γ (J/m ²)		
	Previous work	This work (inc. xy strain)	This work (exc. xy strain)
TiB ₂ (Ti)//Al	3.25 – -0.08[17]	3.04 – -0.20	2.62 – -0.62
TiB ₂ (B)//Al	1.12 – 4.45 [17]	0.99 – 4.23	0.57 – 3.82
TiB ₂ (Ti)//Al ₃ Ti	-	3.61 – 0.37	2.93 – -0.31
TiB ₂ (B)//Al ₃ Ti	-	0.46 – 3.71	-0.21 – 3.03

Table 3: Calculated ranges of values for the interfacial energies - the first number in the range is for $\mu_{Ti} = -0.12$ Ha/atom. (-310 kJ/mol-a.); the second number is for $\mu_{Ti} = 0$ Ha/atom (0 kJ/mol-a.).

Figure 1: Interfacial energy versus Ti chemical potential for the four interfacial systems. The energies of formation of Al₃Ti, both relaxed and strained, are shown by the vertical dotted lines.

Figure 2: Interfacial energies of $\text{TiB}_2//\text{Al}$ for the present results – both with and without x - y strain – and Han’s results [17], which include x - y strain.

260 a significant difference to the results, which figure 2 demonstrates. The small
 265 difference between our strain-included γ and those of Han may be at least partly
 explained by Han’s use of ultrasoft pseudopotentials, in contrast to our use of
 PAW.

The results from figure 1 suggest three main findings concerning γ_{sub}^{solid} :

- 265 1. Both solid Al and Al_3Ti form a more stable interface with $\text{TiB}_2(\text{Ti})$ than
 $\text{TiB}_2(\text{B})$ at higher Ti chemical potentials; at lower Ti chemical potentials,
 $\text{TiB}_2(\text{B})$ forms the more stable interface.
2. The $\text{TiB}_2(\text{Ti})$ substrate forms more stable interfaces with Al than with
 Al_3Ti ; conversely, $\text{TiB}_2(\text{B})$ forms more stable interfaces with Al_3Ti than
 270 Al.
3. We see that for higher Ti concentrations ($\Delta\mu_{\text{Ti}} \gtrsim -184$ kJ/mol, which

around the melting point equates to $X_{Ti} \gtrsim 0.0003\text{at.}\%$) the most stable interface is $\text{TiB}_2(\text{Ti})//\text{Al}$; for lower Ti concentrations ($\Delta\mu_{Ti} \lesssim -184 \text{ kJ/mol}$ or $X_{Ti} \lesssim 0.0003\text{at.}\%$) the most stable is $\text{TiB}_2(\text{B})//\text{Al}_3\text{Ti}$. However, bulk Al_3Ti is not stable in this range, but only stable when $\Delta\mu_{Ti} > -90 \text{ kJ/mol}$.

It therefore seems that based on the GS substrate//solid interfacial energies alone, $\text{TiB}_2(\text{Ti})//\text{Al}$ is the most favorable system.

4.7. Solid-liquid interfacial energies

We now consider the solid-liquid interfacial energies γ_{sub}^{melt} and γ_{solid}^{melt} . The γ_{solid}^{melt} values, γ_{Al}^{melt} and $\gamma_{Al_3Ti}^{melt}$, are estimated as follows: γ_{Al}^{melt} at 660K was taken as a linear interpolation between literature values of $\gamma_{Al}^{Al(l)}$ (0.131 J/m² – the average of 0.121 J/m² [55] and 0.141 J/m² [56]) and $\gamma_{Al}^{melt(X_{Ti}=0.0169\%)}$ (rounded up to 0.171 J/m² [57]). The effect of strain – we are actually dealing with $\gamma_{Al-strained}^{melt}$ – was estimated by calculating the difference that straining Al makes to the $\text{Al}(111)//\text{vacuum}$ surface energy, $\{\sigma_{Al-strained}^{vac} - \sigma_{Al-relaxed}^{vac}\}$, and was found to be 0.258 J/m² (see table 2). This results in an estimate for γ_{Al}^{melt} of 0.389 J/m². For $\gamma_{Al_3Ti}^{melt}$, a similar method was used, except that the two values to interpolate between were themselves estimated, due to a lack of literature values, using $\gamma_{Al_3Ti}^{Al(l)} \approx \gamma_{Al}^{Al(l)} + \left(\gamma_{TiB_2(Ti)}^{Al_3Ti} - \gamma_{TiB_2(Ti)}^{Al}\right)$ and $\gamma_{Al_3Ti}^{melt(X_{Ti}=0.0169\%)} \approx \gamma_{Al}^{melt(X_{Ti}=0.0169\%)} + \left(\gamma_{TiB_2(Ti)}^{Al_3Ti} - \gamma_{TiB_2(Ti)}^{Al}\right)$.

Modelling γ_{sub}^{melt} . To estimate the interfacial energy between the melt and the substrate we have built a simple model. We start by expressing γ_{sub}^{melt} as follows:

$$\gamma_{sub}^{melt} = \gamma_{sub}^{vac} + \gamma_{melt}^{vac} + \Delta\gamma_{sub}^{melt} \quad (3)$$

where $\Delta\gamma_{sub}^{melt}$ is the difference in total interfacial and surface energies caused by the immersion of the substrate into the melt. For γ_{sub}^{vac} we use the 0K interfacial energies obtained from the DFT surface energy calculations (see table 2). For γ_{melt}^{vac} we start with $\gamma_{Al(liq)}^{vac}$ as 1 J/m² [58, 59, 60] and use the same linear interpolation as for γ_{solid}^{melt} above, and then add the 0K difference between the

strained and relaxed solid Al surface energies, which is 0.14 J/m² (see table 2).

300 The energy changes caused by $\Delta\gamma_{sub}^{melt}$ are based only on the amount of ordering of the liquid at the substrate, based on the results of DFT MD simulations by Wang [16] and Zhang [18, 21]. An ordering function is used, $a(z)$, to quantify the state of the liquid at a distance z from the substrate (0 is perfect disorder, i.e. liquid; 1 is perfect order, i.e. solid), and is approximated by an exponential
305 function, $a(z) = \exp(-kz)$ where k is a disordering parameter. Based on Wang's [16] diagrams of the nuclei's final positions and the density profile away from the interface, k was set to $0.25 \times 10^{-10} \text{ m}^{-1}$ and $1 \times 10^{-10} \text{ m}^{-1}$ for TiB₂(B) and TiB₂(Ti). The interfacial free energy is then computed using the procedure detailed in the supplementary material, and is a function of $a(z)$, and thus
310 ultimately a function of k . Our final expression for γ_{sub}^{melt} is:

$$\gamma_{sub}^{melt} = \gamma_{sub}^{vac} + \gamma_{melt}^{vac} - b\rho_{liq} \left(\frac{8}{3} \frac{\rho_{liq}}{\Delta\rho} + \frac{1}{4} \right) k^{-1} \quad (4)$$

where b is the temperature dependent Gibbs energy of fusion of the Al liquid, ρ_{liq} is the density of Al liquid, and $\Delta\rho = \rho_{solid} - \rho_{liq}$ with ρ_{solid} being the density of the solid. While very simple, this model contains two important elements: firstly, the interfacial energy varies with respect to X_{Ti} , because γ_{sub}^{vac} and γ_{melt}^{vac}
315 vary with X_{Ti} ; secondly, it contains an element, $\Delta\gamma_{sub}^{melt}$, that lowers γ_{sub}^{melt} in proportion to the amount of ordering seen at the substrate i.e. more ordering, means a lower γ_{sub}^{melt} . Figure 3 shows the interfacial energy derived from the model using the values of k given above.

The plots for γ_{sub}^{melt} are quite similar to those of γ_{sub}^{solid} (and γ_{sub}^{vac}), but shifted
320 about 3.5 – 4 J/m² (1 J/m²) higher. The crossover point occurs at about $\mu_{Ti} = -200 \text{ kJ/mol}$, which around the melting point of Al corresponds to $X_{Ti} = 1 \times 10^{-7}$ to 1×10^{-6} . In a typical industrial melt X_{Ti} is about 1×10^{-5} to 1×10^{-4} , hence TiB₂(Ti) is predicted to be the more stable substrate prior to nucleation, and hence, the two nucleation mechanisms starting with TiB₂(Ti)//melt appear
325 to be the most likely nucleation mechanisms. However, the possibility that TiB₂(B) substrates might still be present is discussed in the analysis section.

Figure 3: The interfacial energy between TiB_2 substrates and the melt, $\gamma_{\text{sub}}^{\text{melt}}$, plotted against $\mu_{\text{Ti}} - \mu_{\text{Ti}}^{\text{bulk}}$, according to our model .

4.8. Finite temperature corrections to interfacial energy

One major limitation of the γ_{sub}^{solid} and γ_{sub}^{melt} figures is that they were calculated using GS DFT simulations, and so do not include finite temperature effects. Further DFT perturbation calculations (DFPT), implementing the harmonic approximation, can be used to estimate the finite temperature effects. However, at the temperatures considered here (close to the melting point), the harmonic approximation breaks down and further anharmonic effects need to be considered, which would be very computationally demanding and beyond the scope of this paper. However, some preliminary DFPT calculations using an LDA exchange correlation functional and norm-conserving pseudopotentials were carried out to see qualitatively how the finite temperature corrections affect the initial substrate//melt system and the ΔG_T for the nucleation of Al. These preliminary results suggest that the final conclusion, which predicts the TiB₂(Ti)//Al nucleation mechanism as the most favoured, would not be affected by the finite temperature corrections. Please see the supplementary material for more details. For this study, the GS results shown in sections 4 and 4.7 are used for the ΔG_T analysis in section 5.

5. ΔG_T Analysis

The interfacial energies from section 4 and the bulk energies from section 3 are now inserted into Eq. 1 to calculate the total Gibbs energy of solid formation, and analyse it as a function of solid thickness n , Ti concentration X_{Ti} , and temperature T . It must be emphasised that this analysis does not say anything about the critical point of nucleation, that is, the most stable number of layers of solid. According to Eq. 1, above the melting point and even slightly below it, one layer of solid should be the most stable arrangement, because the first layer reduces the overall Gibbs energy by reducing the total interfacial energy, while the formation of further layers of solid would only increase the total Gibbs energy, because the formation of strained solid, Al or Al₃Ti, is positive (see table 1). Yet Eq. 1 is derived from macroscopic equilibrium thermodynamics,

and it is unclear how closely very thin layers of solid obey these rules. Hence, the analysis will consider separately a thin layer system (1 atomic layer) and a thick layer system (6 atomic layers), in order to more clearly identify where any uncertainty in the conclusions lies.

360 We make assumptions about the size, shape, and number density of TiB_2 substrates, based on estimates by Greer [61]: the average diameter of the substrate = $3\mu\text{m}$, the particle density = 1×10^{14} particles/ m^2 , and the fraction of active particles = 0.001. This gives a total active substrate area = $4.93 \times 10^{-7}\text{m}^2/\text{mol-atoms of melt}$. The value of these constants does significantly influence the absolute values of G_T and ΔG_T , but they have a negligible
365 effect on the difference in ΔG_T between the 4 systems. Throughout, unless specified otherwise, X_{Ti} is taken to be fixed at a typical value of 5×10^{-5} mole fraction (0.01wt%) used in industry, and the temperature is taken to be 950K, which is approximately when wetting on the substrate is first observed [15].

370 5.1. G_T and ΔG_T vs n layers

Figure 4 shows the absolute values of G_T plotted against the number of layers n . We see that under typical melt conditions, $\text{TiB}_2(\text{Ti})//\text{melt}$ is the most stable starting system before nucleation, and $\text{TiB}_2(\text{Ti})//\text{Al}//\text{melt}$ is the most stable after nucleation. Hence this plot supports $\text{TiB}_2(\text{Ti})//\text{melt} \rightarrow$
375 $\text{TiB}_2(\text{Ti})//\text{Al}//\text{melt}$ as the most likely nucleation mechanism. Interestingly, if the starting system is $\text{TiB}_2(\text{B})//\text{melt}$, it is much less clear whether $\text{TiB}_2(\text{B})//\text{Al}//\text{melt}$ or $\text{TiB}_2(\text{B})//\text{Al}_3\text{Ti}//\text{melt}$ would be the most stable system after nucleation. The evidence above suggests that thin layers of solid Al_3Ti might be more stable than thin layers of solid Al, on a $\text{TiB}_2(\text{B})$ substrate.

380 Figure 5 shows the difference in values of ΔG_T , the Gibbs energy change due to nucleation, plotted as functions of n , the number of layers of solid. It shows the most likely solid, Al or Al_3Ti , *given a particular starting substrate* - a negative value indicates that solid Al formation is more stable, whereas a positive value indicates that solid Al_3Ti formation is more stable. There
385 is a clear trend that as n increases, formation of Al becomes more and more

Figure 4: The total Gibbs energy, G_T , of the initial and final systems. The absolute value of G_T is arbitrary: here the value for the initial $\text{TiB}_2(\text{Ti})//\text{melt}$ system is chosen as zero. *Note:* the $\text{TiB}_2(\text{Ti})//\text{Al}_3\text{Ti}//\text{melt}$ and $\text{TiB}_2(\text{B})//\text{Al}_3\text{Ti}//\text{melt}$ lines are very similar and are overlapping on this plot.

Figure 5: The difference in ΔG_T between formation of n layers of Al and Al_3Ti , for both substrates, at two different temperatures. The vertical line in both graphs represents the minimum number of layers of solid beyond which subsequent layers are bulk-like, according to our DFT calculations.

favourable over Al_3Ti .

5.2. ΔG_T vs X_{Ti} and T

Figure 6 shows the effects of varying X_{Ti} and T , for thin and thick layers of solid. As expected from the Al-Ti phase diagram, an increase in X_{Ti} increases the stability of Al_3Ti relative to Al. In the range of X_{Ti} shown here, which is typical of an industrial aluminium melt, and for much higher X_{Ti} , the Al-favouring trends shown in figure 5 do not change – that is, for 6 atomic layers on $\text{TiB}_2(\text{B})$, and any amount of solid thickness on $\text{TiB}_2(\text{Ti})$, it remains that Al is much more stable than Al_3Ti . However, for thin layers of solid forming on $\text{TiB}_2(\text{B})$, Al_3Ti appears to be more stable, although there is significant un-

Figure 6: The difference in ΔG_T for the formation of 1 and 6 layers of Al and Al_3Ti on both substrates, plotted against X_{Ti} , at two different temperatures.

certainty in which solid is more stable. It is quite possible that the cross-over point – below which thin layers of Al_3Ti would cease to be more stable than thin layers of Al – might lie within an industrially relevant composition. Direct evidence for the $\text{TiB}_2(\text{B})//\text{Al}_3\text{Ti}$ mechanism was not seen in Wang’s DFT MD simulation, but it is possible that a longer simulation with more Ti atoms in the liquid at the $\text{TiB}_2(\text{B})$ surface might show at least one Al_3Ti layer form spontaneously at the surface. The effect of decreasing temperature decreases slightly the likelihood of Al forming: this effect becomes more noticeable for thicker amounts of solid.

Figure 7: Plot of the difference in ΔG_T between sub//Al and sub//Al₃Ti mechanisms against $\gamma_{Al}^{melt} - \gamma_{Al_3Ti}^{melt}$. The left half of the graph represents cases where (strained) Al has a lower interfacial energy with the melt than does Al₃Ti; vice versa for the right half of the graph.

5.3. ΔG_T sensitivity to γ^{melt} values

This and the next subsection look at how sensitive the ΔG_T results are to the γ^{melt} values, which were calculated relatively roughly compared to the G and γ_{sub}^{solid} values. Figure 7 shows the effects of varying the estimates for γ_{solid}^{melt} , specifically the difference $\gamma_{Al}^{melt} - \gamma_{Al_3Ti}^{melt}$. The plot shows that for both thick and thin layers of solid on a TiB₂(Ti) substrate, quite large variations in $\gamma_{Al}^{melt} - \gamma_{Al_3Ti}^{melt}$ from the value we used (-0.208 J/m², shown by the crosses) would not alter the original conclusion that thick layers of Al are more stable than Al₃Ti on both TiB₂ substrates. However, for thin layers on a TiB₂(B) substrate, the more stable solid is reasonably sensitive to variations in $\gamma_{Al}^{melt} - \gamma_{Al_3Ti}^{melt}$ – a shift to -0.35 J/m² would make Al more stable than Al₃Ti.

Figure 8 looks at the effect of varying the solid//liquid interfacial energy of our starting system, γ_{sub}^{melt} , specifically $\gamma_{TiB_2(Ti)}^{melt} - \gamma_{TiB_2(B)}^{melt}$. Previous graphs have plotted the ΔG_T difference between Al and Al_3Ti mechanisms, *given a particular substrate* - that is the more useful comparison if we assume that in our
420 real system all or almost all of the substrates have the same termination. However, we may wish to consider the possibility that both substrates are available in the melt. In this case, we would want to know, *given a particular nucleating solid*, what is the more favourable substrate, and this is what figure 8 shows. The plot suggests that the precise value of $\gamma_{TiB_2(Ti)}^{melt} - \gamma_{TiB_2(B)}^{melt}$ is important in
425 determining the favoured substrate. It is very likely, given our values for $\gamma_{TiB_2}^{Al(s)}$ and $\gamma_{TiB_2}^{vac}$, that $\gamma_{TiB_2(Ti)}^{melt} - \gamma_{TiB_2(B)}^{melt}$ is also negative in typical industrial X_{Ti} and T . Our default results confirm that Al nucleation clearly favours $TiB_2(Ti)$ as a substrate, and Al_3Ti nucleation favours $TiB_2(B)$. These results are fairly stable with respect to errors in our $\gamma_{TiB_2(Ti)}^{melt} - \gamma_{TiB_2(B)}^{melt}$ estimation. However,
430 γ_{sub}^{melt} was estimated using the ordering of liquid Al atoms only, and not Al atoms with some dissolved Ti. Understanding how the presence of Ti atoms affects this ordering is an interesting topic of ongoing research [21].

6. Conclusions

Four potential mechanisms for the nucleation of aluminium were investi-
435 gated and compared. Four interfaces were simulated using DFT, each involving a substrate, $TiB_2(Ti)$ or $TiB_2(B)$, and a nucleated solid, Al or Al_3Ti . Each interfacial energy was calculated as a function of the Ti chemical potential, itself a function of Ti concentration (X_{Ti}) and temperature (T) in the melt. The interfacial energy was then combined with Gibbs energy data from the literature
440 to assess the nucleating potential of each mechanism. The following conclusions are made:

1. Regarding the stability of the interfaces at 0K: the $TiB_2(Ti)//Al$ interface is more stable than $TiB_2(Ti)//Al_3Ti$ for all values of X_{Ti} ; the $TiB_2(B)//Al_3Ti$ interface is more stable than $TiB_2(B)//Al$ for all values

Figure 8: The difference in ΔG_T between formation of a solid on $\text{TiB}_2(\text{Ti})$ and $\text{TiB}_2(\text{B})$, plotted against the difference in the starting solid-liquid interfacial energy $\gamma_{\text{TiB}_2(\text{Ti})}^{\text{melt}} - \gamma_{\text{TiB}_2(\text{B})}^{\text{melt}}$. The left half of the graph represents cases where $\text{TiB}_2(\text{Ti})$ has the lower interfacial energy with the melt; the right half likewise for $\text{TiB}_2(\text{B})$. This difference in ΔG_T is plotted for each solid separately, at $T=950\text{K}$, for three different X_{Ti} .

445 of X_{Ti} ; the most stable interface at 0K is $TiB_2(Ti)//Al$ for $X_{Ti} \gtrsim 0.0003$ at.%, and $TiB_2(B)//Al_3Ti$ for $X_{Ti} \lesssim 0.0003$ at.%. Strain plays a significant role in the value of the interfacial energy, adding about 0.5 J/m^2 to $TiB_2//Al$ interfacial energies.

2. The results here suggest that any possible Al_3Ti layers that do form, on
450 either substrate, are likely to be very thin, and probably significantly thinner than any Al layers that might form.
3. $TiB_2(Ti)$ is more stable in the melt than $TiB_2(B)$ prior to nucleation. In this case, formation of Al is more stable than Al_3Ti formation, for thin and thick solid layers. However, if $TiB_2(B)$ is present in the melt prior to
455 nucleation, then only for thick solid layers is formation of Al is more stable over Al_3Ti , whilst for thin solid layers, it is unclear whether formation of Al or Al_3Ti is more stable, but our results slightly favour Al_3Ti .

The results and analysis as they stand point towards a mechanism wherein either something similar to pure Al, rather than Al_3Ti , nucleates off a $TiB_2(Ti)$
460 substrate, or else a mixture of Al and Al_3Ti , perhaps an intermediate Al-Ti structure, nucleates off a $TiB_2(B)$ substrate. Given the non-uniform and locally varying nature of real-life interfaces, it is a possibility that any combination of these mechanisms are active at once throughout the melt. One thing all the suggested mechanisms have in common, however, is Ti contact with both B and
465 Al, whether in the last Ti layer of TiB_2 , or in the first layer of Al_3Ti .

To get closer to a firm conclusion several extensions to this work could be made. Firstly, the liquid-solid interfacial energies, which were modelled quite simply in this study, need to be calculated accurately as a function of X_{Ti} and T . Secondly, all interfacial energies, which were fully or partially calculated at
470 0 K in this study, should be calculated at finite temperature. Finally, while the classical model has been useful to observe general trends between the four systems, in response to several parameters, ultimately large scale long running DFT MD calculations of TiB_2 substrates in the presence of liquid melt need to be run.

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